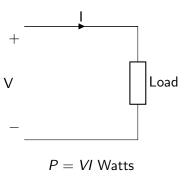
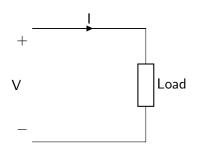
## Power in DC Circuits



### Power in AC Circuits

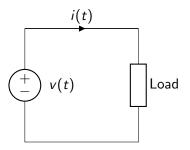


To find power,

- RMS values of V and I alone are not sufficient.
- ▶ The phase angle difference between them is also needed.

### Power in AC Circuits

Let us consider the following circuit.



if  $v = V_m \sin(\omega t)$ , the steady state current in R-L load is

$$i = I_m \sin(\omega t - \phi)$$

where 
$$I_m = \frac{V_m}{\sqrt{R^2 + (\omega L)^2}}$$
 and  $\phi = \tan^{-1} \frac{\omega L}{R}$ .

Let  $v(t) = \sqrt{2}V\sin(\omega t + \theta_V)$  and  $i(t) = \sqrt{2}I\sin(\omega t + \theta_I)$  be the voltage across and current through a load.

The **instantaneous power** delivered to the load is 
$$p(t) = v(t)i(t)$$

The **instantaneous power** delivered to the load is 
$$ho(t) = v(t)i(t)$$

 $p(t) = V_m \sin(\omega t + \theta_V) I_m \sin(\omega t + \theta_I)$ 

 $p(t) = \frac{V_m I_m}{2} (\cos(\theta_V - \theta_I) - \cos(2\omega t + \theta_V + \theta_I))$ 

 $p(t) = \frac{V_m I_m}{2} \cos(\theta_V - \theta_I) - \frac{V_m I_m}{2} \cos(2\omega t + \theta_V + \theta_I)$ 

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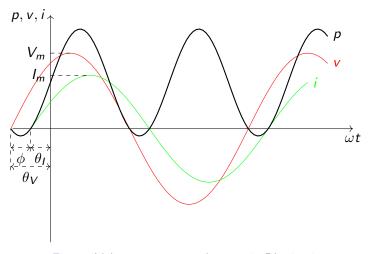


Figure: Voltage, current and power in RL circuit

Let  $\theta_V - \theta_I$  be  $\phi$ .

$$p(t) = VI \cos \phi - VI \cos(2\omega t + \theta_V + \theta_I)$$

$$p(t) = VI \cos \phi - VI \cos(2\omega t + \theta_V - \theta_I + 2\theta_I)$$

$$p(t) = VI \cos \phi - VI \cos(2\omega t + 2\theta_I - \phi)$$

$$p(t) = \underbrace{VI \cos \phi (1 - \cos(2\omega t + 2\theta_I))}_{\rho_I} - \underbrace{VI \sin \phi \sin(2\omega t + 2\theta_I)}_{\rho_{II}}$$

 $p_I$  has an average value of  $VI \cos \phi$  which is called the average power.

 $p_{II}$  does not have an average. But it's maximum value is  $VI \sin \phi$  which is called reactive power.

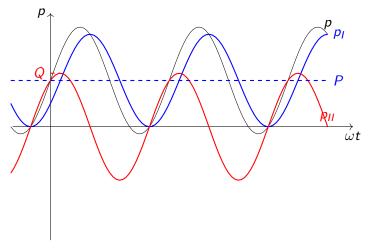


Figure: Power in RL circuit

# Average Power / Real Power

The average power P is

$$P = \frac{V_m I_m}{2} \cos(\theta_V - \theta_I) = VI \cos(\phi)$$

where  $\phi = \theta_V - \theta_I$ . Its unit is watts (W).

1. Resistor: V and I are in phase.

$$P = VI \cos(0^\circ) = VI$$

2. Ideal Inductor : V leads I by  $90^{\circ}$ .

$$P = VI\cos(90^\circ) = 0$$

3. Ideal Capacitor : I leads V by  $90^{\circ}$ .

$$P = VI \cos(90^\circ) = 0$$

### Reactive Power

This does not do any useful work. But it keeps oscillating between source and load with zero average.

The maximum value is

$$Q = VI \sin \phi$$

Its unit is VAr.

1. Resistor: V and I are in phase.

$$Q = VI \sin(0^\circ) = 0$$

2. Ideal Inductor : V leads I by  $90^{\circ}$ .

$$Q = VI \sin(90^\circ) = VI$$

3. Ideal Capacitor : I leads V by  $90^{\circ}$ .

$$Q = VI \sin(90^\circ) = VI$$

# Apparent Power and Power Factor

If the voltage and the current were dc quantities, the power delivered to a load would be

$$|S| = VI$$

As dc values and RMS are equal,

$$|S| = V_{RMS}I_{RMS}$$

where |S| is called as the **apparent power**. Its unit is **volt-ampere (VA)**.

The ratio of real power (P) to apparent power is called as the **power factor (pf)**.

$$pf = \frac{VI\cos\phi}{VI} = \cos\phi$$

Since  $\cos \phi$  can never be greater than unity,  $P \leq |S|$ .

1. Resistor:

$$\phi=0^\circ$$
  $ext{pf}=\cos(0^\circ)=1$ 

2. Ideal Inductor:

$$\phi=90^{\circ}$$
  $ext{pf}=\cos(90^{\circ})=0$ 

3. Ideal Capacitor:

$$\phi = -90^{\circ}$$
  $\mathrm{pf} = \cos(-90^{\circ}) = 0$ 

- ▶ RL Circuit: Let  $\phi = 60^{\circ}$ . pf = cos( $60^{\circ}$ ) = 0.5.
- ▶ RC Circuit: Let  $\phi = -60^{\circ}$ . pf =  $\cos(-60^{\circ}) = 0.5$

In order to differentiate these two cases, power factor in a RL circuit is mentioned **lagging** pf and in a RC circuit as **leading** pf.

## Complex Power

Let us define voltage phasor and current phasor.

$$V = V \angle \theta_V, \quad I = I \angle \theta_I$$

The complex power S is

$$S = VI^*$$

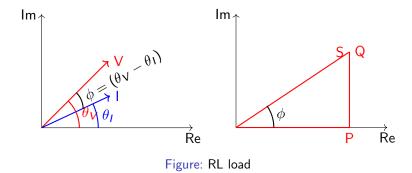
$$S = V \angle \theta_V I \angle - \theta_I$$

$$= VI \angle (\theta_V - \theta_I)$$

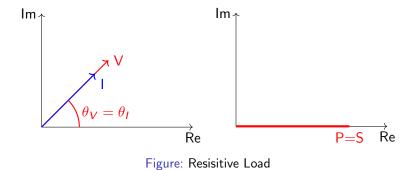
$$S = VI \cos \phi + \gamma VI \sin \phi$$

The real part of S is called the average power (P). The imaginary part of S is called the reactive power (Q).

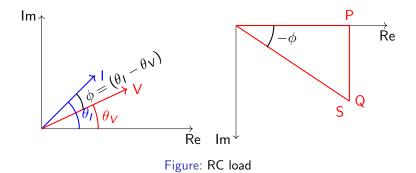
$$S = P + \jmath Q$$



If V leads I ( $\phi > 0$ ), power factor is lagging.

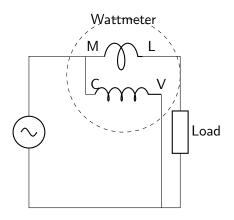


If V and I are in phase ( $\phi = 0$ ), power factor is unity.

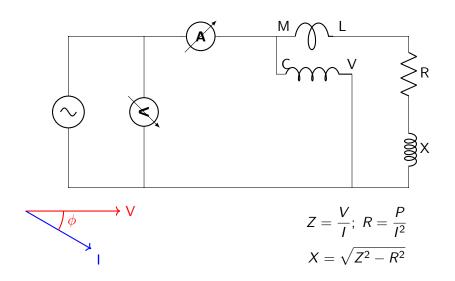


If I leads V ( $\phi < 0$ ), power factor is leading.

# Power Measurement - Single Phase



## Measurement of R and X



### Power in Three Phase

Let  $v_a$ ,  $v_b$  and  $v_c$  be the instantaneous voltages of a balanced three phase source.

$$\begin{aligned} v_a &= \sqrt{2}V\sin(\omega t + \theta_V) \\ v_b &= \sqrt{2}V\sin(\omega t + \theta_V - 120^\circ) \\ v_c &= \sqrt{2}V\sin(\omega t + \theta_V - 240^\circ) \end{aligned}$$

When it supplies a balanced load,

$$i_a = \sqrt{2}I\sin(\omega t + \theta_I)$$

$$i_b = \sqrt{2}I\sin(\omega t + \theta_I - 120^\circ)$$

$$i_c = \sqrt{2}I\sin(\omega t + \theta_I - 240^\circ)$$

The instantaneous power is

$$p = v_{a}i_{a} + v_{b}i_{b} + v_{c}i_{c}$$

$$p = \sqrt{2}V_{p}\sin(\omega t + \theta_{V}) \times \sqrt{2}I_{p}\sin(\omega t + \theta_{I})$$

$$\sqrt{2}V_{p}\sin(\omega t + \theta_{V} - 120^{\circ}) \times \sqrt{2}I_{p}\sin(\omega t + \theta_{I} - 120^{\circ})$$

$$\sqrt{2}V_{p}\sin(\omega t + \theta_{V} - 240^{\circ}) \times \sqrt{2}I_{p}\sin(\omega t + \theta_{I} - 240^{\circ})$$

$$p = V_{p}I_{p}\cos(\theta_{V} - \theta_{I}) + V_{p}I_{p}\cos(2\omega t + \theta_{V} + \theta_{I})$$

$$V_{p}I_{p}\cos(\theta_{V} - \theta_{I}) + V_{p}I_{p}\cos(2\omega t + \theta_{V} + \theta_{I} - 120^{\circ})$$

$$V_{p}I_{p}\cos(\theta_{V} - \theta_{I}) + V_{p}I_{p}\cos(2\omega t + \theta_{V} + \theta_{I} - 240^{\circ})$$

$$p = 3V_{p}I_{p}\cos\phi$$

where  $\phi = \theta_V - \theta_I$ .

The instantaneous power in a 3 phase balanced system is constant.

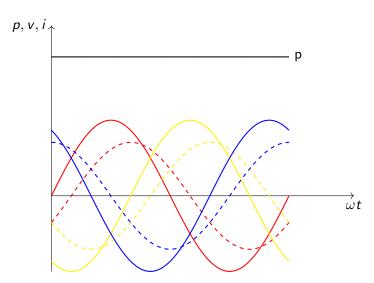


Figure: Voltage, current and power in a R-L load

The average/real power in a 3-phase system is

$$P = 3V_p I_p \cos \phi$$
 Watts

In a Y connected load,  $V_L = \sqrt{3}V_p$  and  $I_L = I_p$ ,

$$P = \sqrt{3}V_L I_L \cos \phi$$

In a  $\Delta$  connected load,  $V_L=V_p$  and  $I_L=\sqrt{3}I_p$ ,

$$P = \sqrt{3}V_I I_I \cos \phi$$

Therefore, the three phase real power is

$$P = 3V_p I_p \cos \phi = \sqrt{3}V_I I_I \cos \phi$$

Since the instantaneous power in a 3-phase balanced system is constant, it does not mean that there is no reactive power. Still the instantaneous power of individual phases is pulsating.

The 3-phase reactive power is

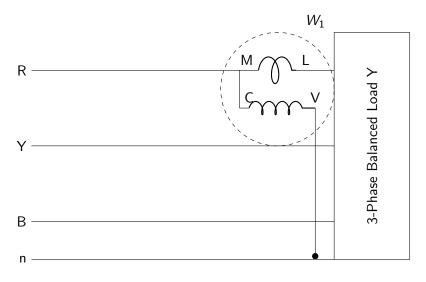
$$Q = 3V_p I_P \sin \phi = \sqrt{3}V_I I_I \sin \phi$$
 VAr

The apparent power is

$$|S| = \sqrt{P^2 + Q^2} = 3V_p I_p = \sqrt{3}V_L I_L$$
 VA

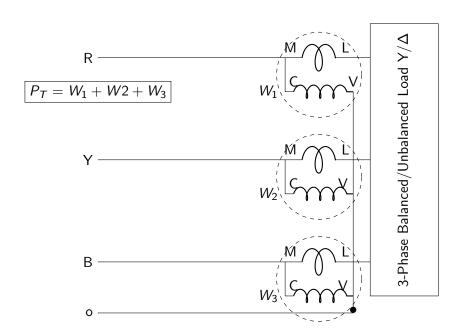
## 3-Phase Power Measurement

If the load is balanced,

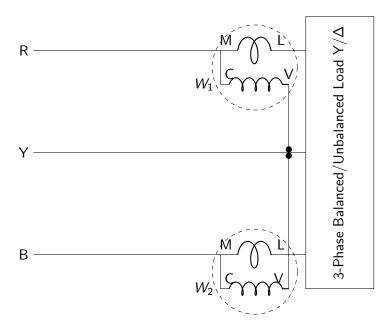


The total 3-phase power is  $P = 3 \times W_1$ 

If the load is unbalanced,



## Two Wattmeter Method



The total average power absorbed the load is

$$P_T = W_1 + W_2$$

#### Proof:

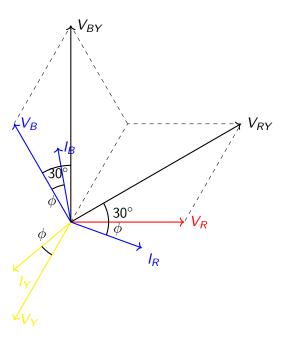
Consider a balanced Y connected RL load.

$$V_p = V \angle 0^\circ$$
;  $I_L = I_p = I \angle - \phi$ ;  $V_L = \sqrt{3}V \angle 30^\circ$ 

Therefore

$$W_1 = V_{RY}I_R\cos(\angle V_{RY} - \angle I_R)$$

$$W_2 = V_{BY}I_B\cos(\angle V_{BY} - \angle I_B)$$



Since  $V_{RY} = V_{RY} = V_I$ ,

So, the total average power is

$$W_1 = V_I I_I \cos(30^\circ + \phi)$$

 $W_2 = V_1 I_1 \cos(30^{\circ} - \phi)$ 

 $W_1 + W_2 = V_L I_L \cos(30^\circ + \phi) + V_L I_L \cos(30^\circ - \phi)$  $W_1 + W_2 = \sqrt{3} V_1 I_1 \cos \phi$ 

 $P = W_1 + W_2$ 

Let us find  $W_2 - W_1$ .

$$W_2 - W_1 = V_L I_L \cos(30^\circ - \phi) - V_L I_L \cos(30^\circ + \phi)$$

$$W_2 - W_1 = V_L I_L \sin \phi$$

The total reactive power is

$$Q=\sqrt{3}(W_2-W_1)$$

The power factor angle can be found as follows:

$$\phi = tan^{-1} \left( \frac{\sqrt{3}(W_2 - W_1)}{W_1 + W_2} \right)$$

- 1. If  $W_1 = W_2$ , the load is resistive.
- 2. If  $W_2 > W_1$ , the load is inductive.
- 3. If  $W_2 < W_1$ , the load is capacitive.