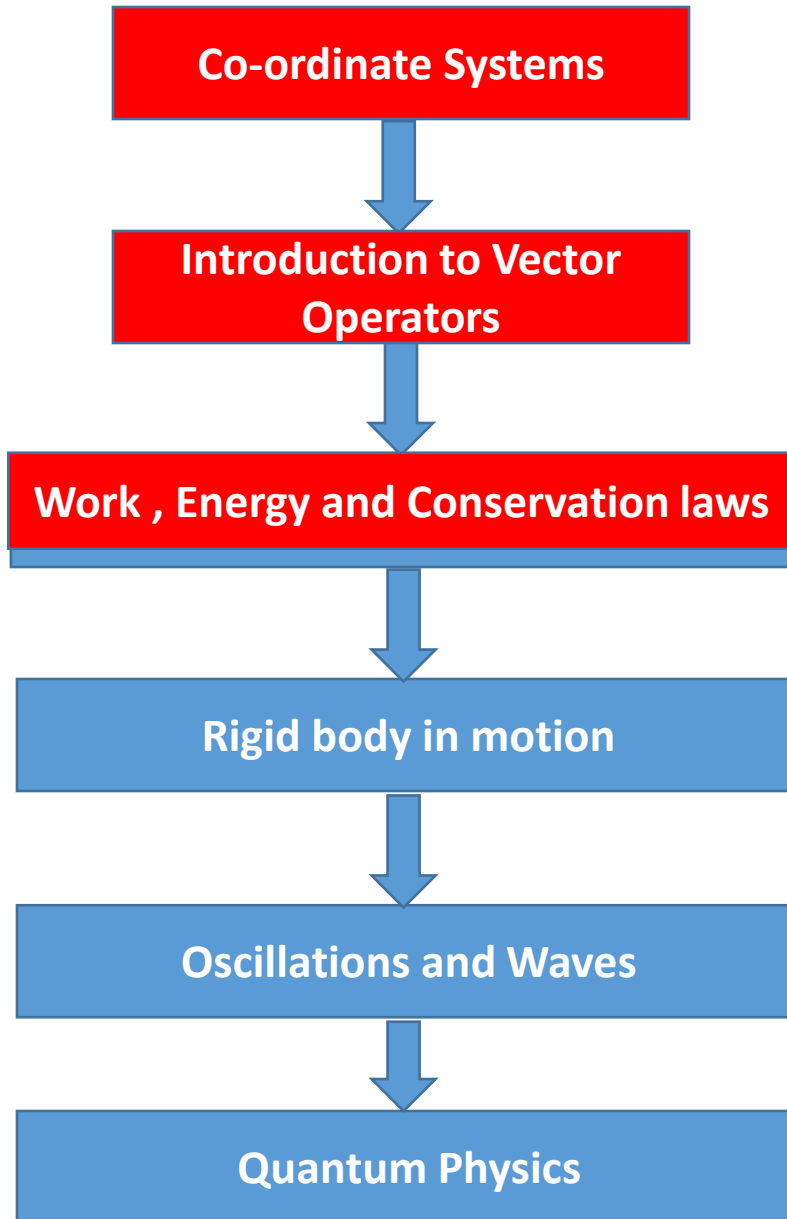


# Highlights of the course

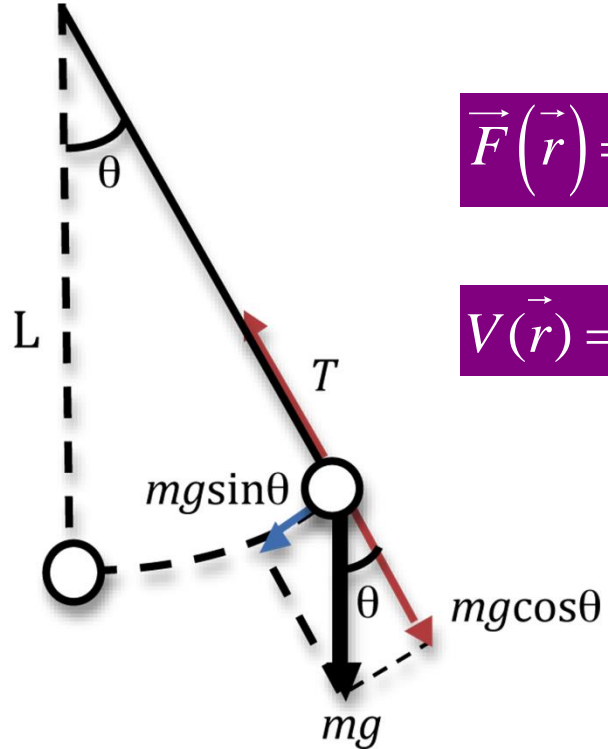


# Chapter-3: Work , Energy and Conservation laws



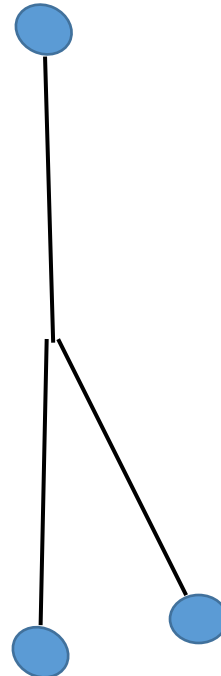
# Concept of equilibrium

## Simple Pendulum

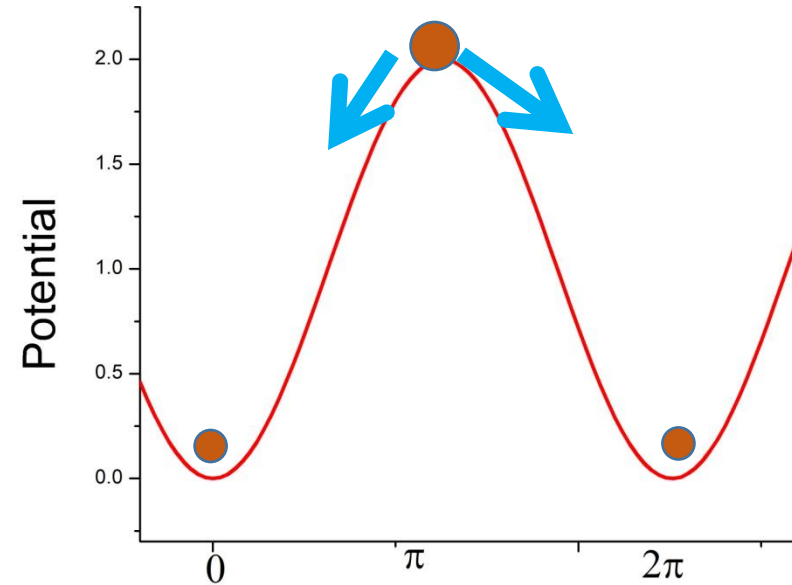


$$\vec{F}(\vec{r}) = -mg \sin \theta \hat{e}_\theta$$

$$V(\vec{r}) = mgl(1 - \cos \theta)$$



## Unstable equilibrium



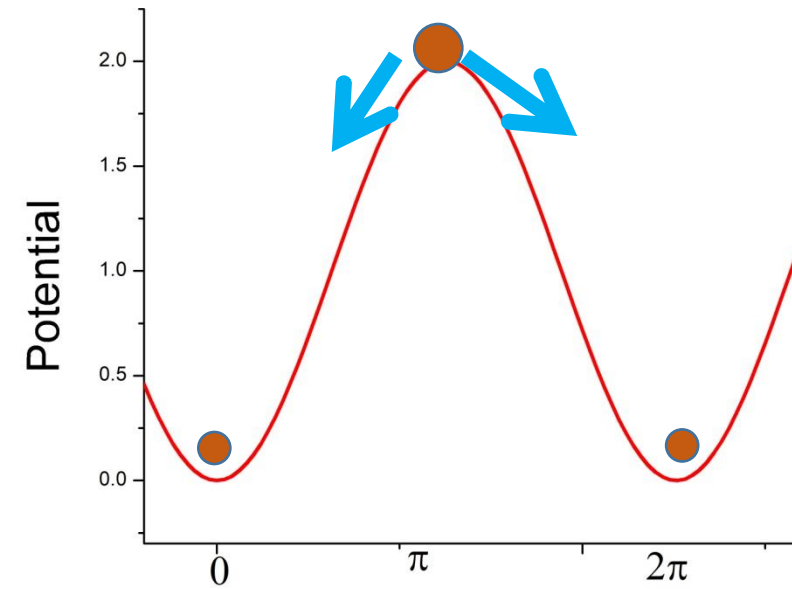
$$\theta = \pi$$

$$\theta = 0$$

$$V(\vec{r}) = mgl(1 - \cos \theta)$$

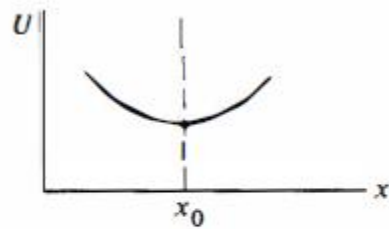
$$\frac{dV(\vec{r})}{d\theta} = mgl \sin \theta$$

$$\frac{d^2V(\vec{r})}{d\theta^2} = mgl \cos \theta$$



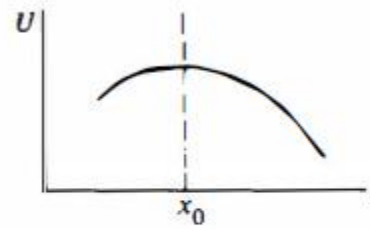
$$\frac{d^2V(\vec{r})}{d\theta^2} = mgl(\theta = 0)$$

$$\frac{d^2V(\vec{r})}{d\theta^2} = -mgl(\theta = \pi)$$



$$\frac{d^2U}{dx^2} > 0$$

stable



$$\frac{d^2U}{dx^2} < 0$$

unstable

# Plot $\dot{\theta}$ v/s $\theta$ ?

$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl(1 - \cos \theta)$$
$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl(1 - (1 - \frac{\theta^2}{2!} + \dots))$$

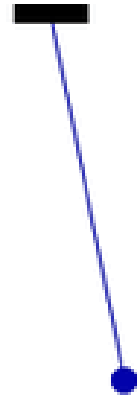
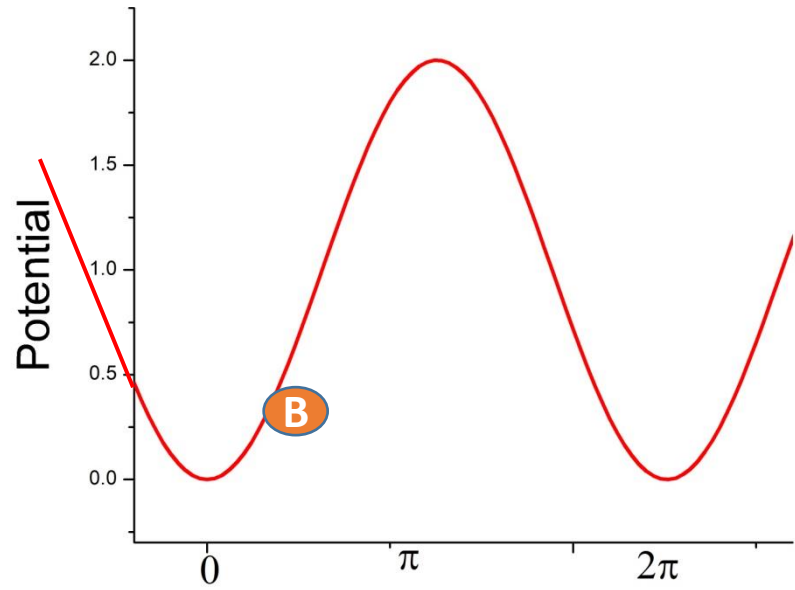


$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl \frac{\theta^2}{2!}$$
$$\frac{\dot{\theta}^2}{2E / ml^2} + \frac{\theta^2}{2E / mgl} = 1$$

Equation of ellipse

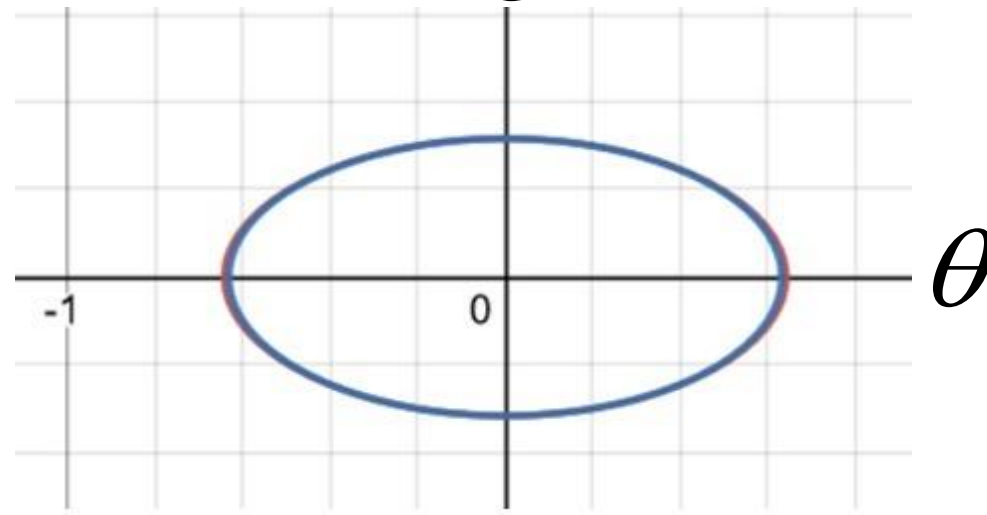
For small values of  $\theta$  the equation is of ellipse. But as  $\theta$  becomes larger it deviates from an ellipse

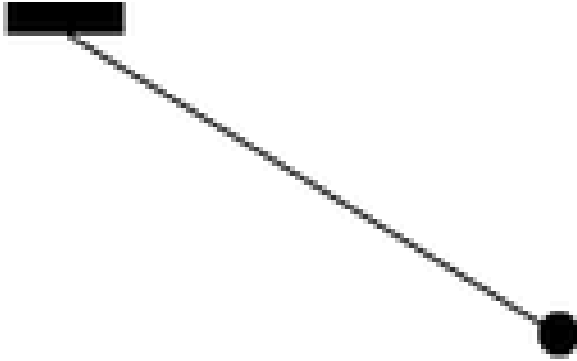
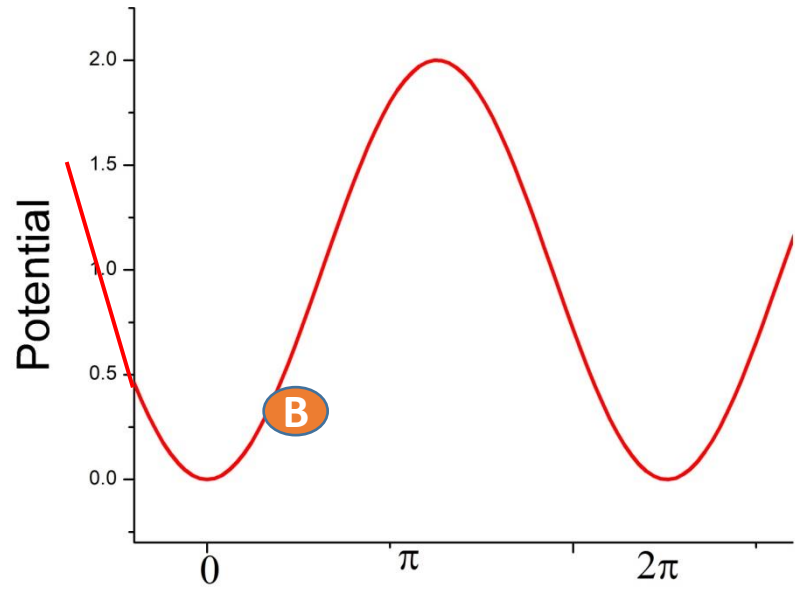
$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl \frac{\theta^2}{2!} - mgl \frac{\theta^4}{4!} + \dots$$
$$\frac{\dot{\theta}^2}{2E / ml^2} + \frac{\theta^2}{2E / mgl} - \frac{\theta^4}{24E / mgl} + \dots = 1$$



$$\frac{\dot{\theta}^2}{2E/ml^2} + \frac{\theta^2}{2E/mgl} = 1$$

**Small Oscillations**

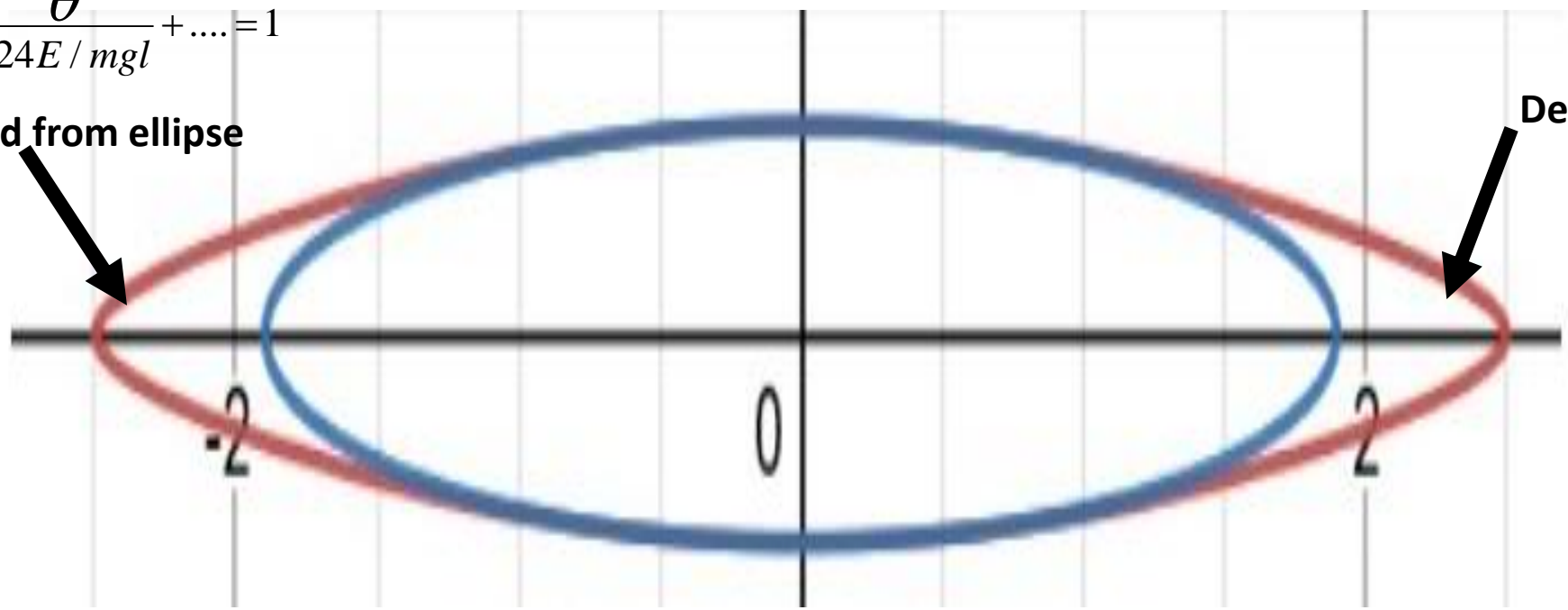




**larger Oscillations**

$$\frac{\dot{\theta}^2}{2E/ml^2} + \frac{\theta^2}{2E/mgl} - \frac{\theta^4}{24E/mgl} + \dots = 1$$

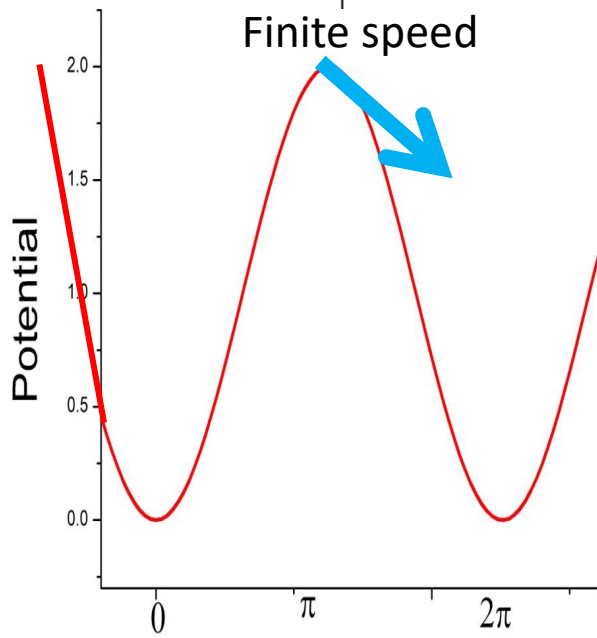
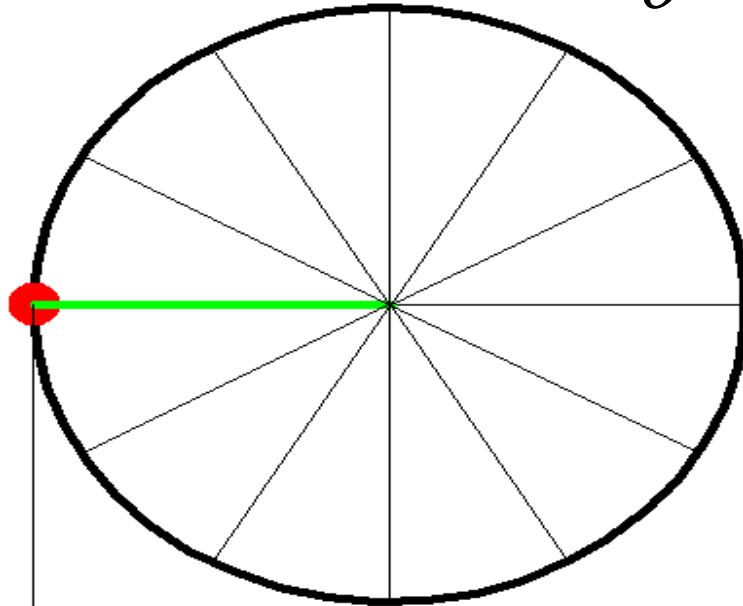
**Deviated from ellipse**



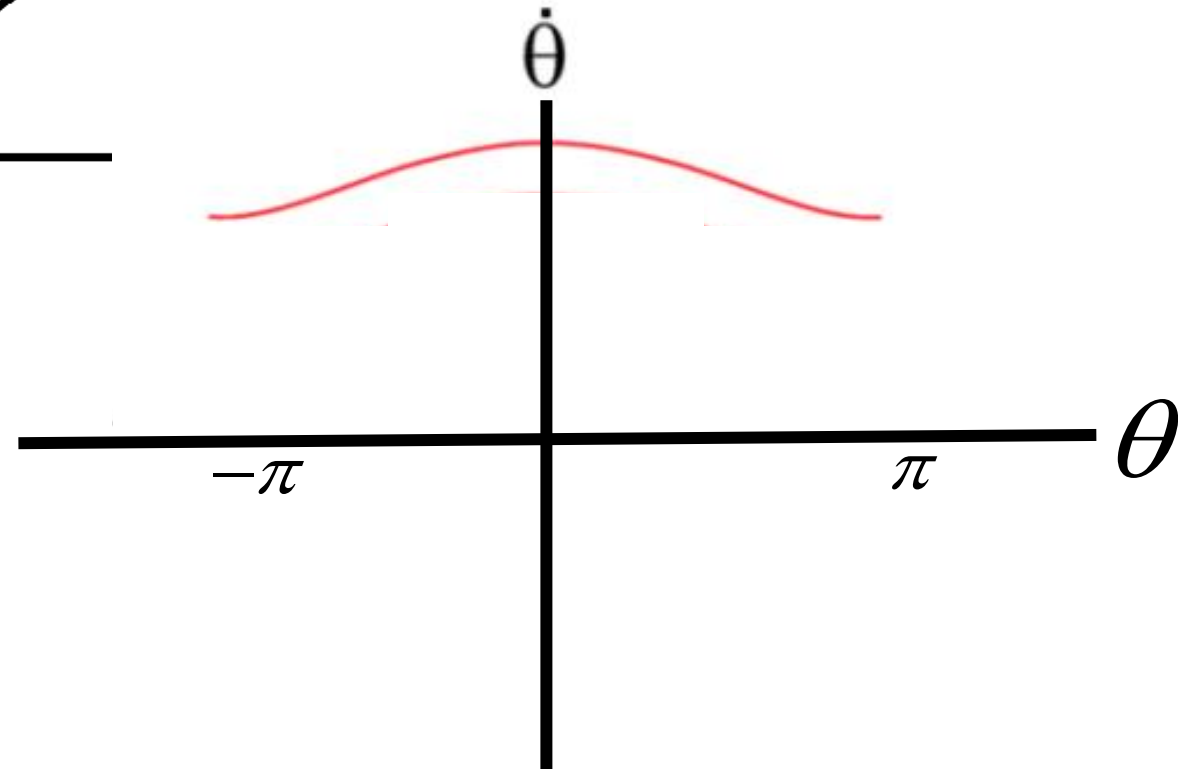
**Deviated from ellipse**

# Circular motion

Finite speed ( $\dot{\theta}$ )



B

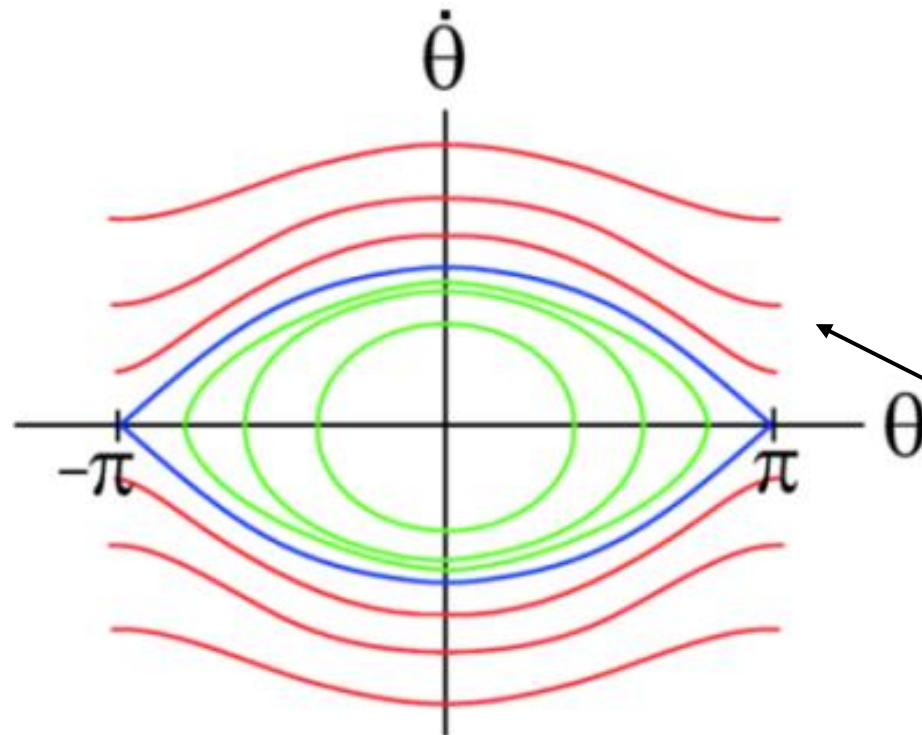




# Plot $\dot{\theta}$ v/s $\theta$

$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl \frac{\theta^2}{2!}$$
$$\frac{\dot{\theta}^2}{2E/ml^2} + \frac{\theta^2}{2E/mgl} = 1$$

$$E = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl \frac{\theta^2}{2!} - mgl \frac{\theta^4}{4!} + \dots$$
$$\frac{\dot{\theta}^2}{2E/ml^2} + \frac{\theta^2}{2E/mgl} - \frac{\theta^4}{24E/mgl} + \dots = 1$$

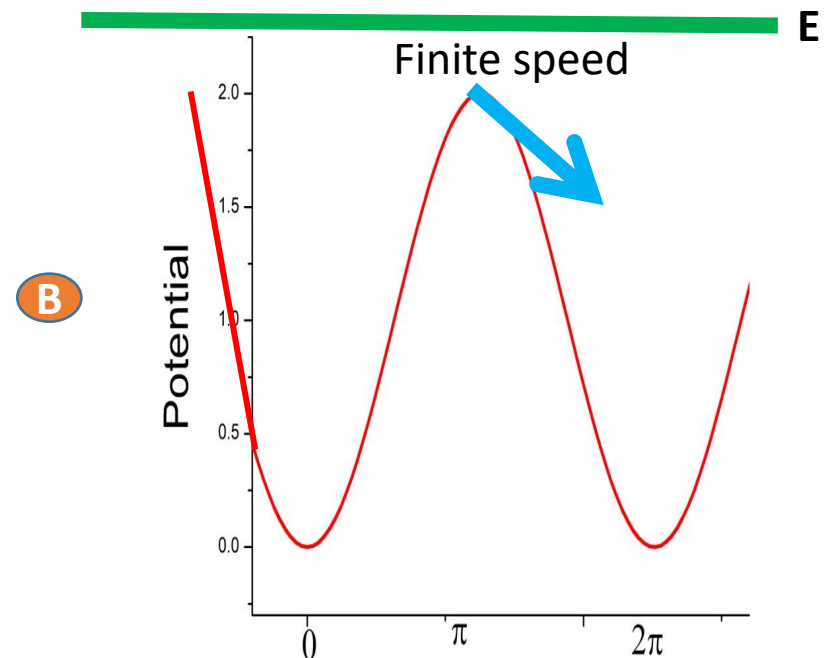
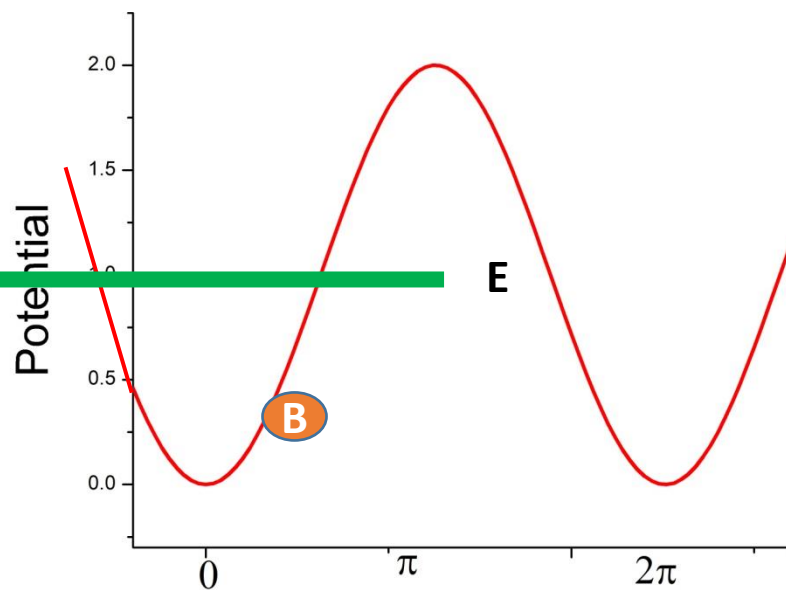
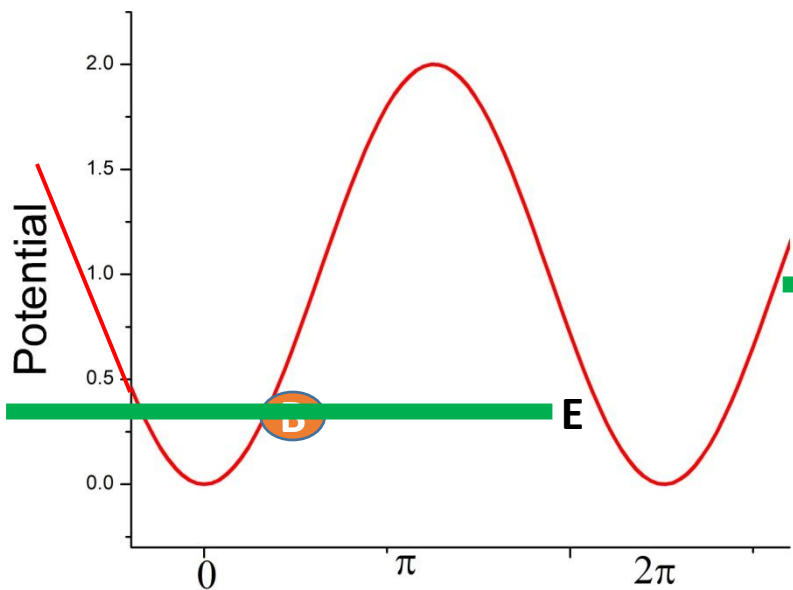


For larger E , motion  
Of the pendulum  
Becomes  
Circular motion

# Simple Pendulum

Bounded motion

Unbounded motion



Small Oscillations

larger Oscillations

Circular motion

# Concept of equilibrium

## Duffing Oscillator (Georg Duffing, German engineer)

$$V(x) = \frac{1}{2}\beta x^2 + \frac{1}{4}\alpha x^4, \quad \beta < 0$$

---

### Plot $V(x)$ v/s $x$

---

#### How to Plot the graph?

1. Find Maxima and Minima
2. Find the zero crossing points
3. Imagine the function for smaller and larger values of  $x$

# 1. Maxima and Minima

## Condition for maxima and minima of a function

A function  $V(x)$  is maximum when  $\frac{dV(x)}{dx} = 0$  and  $\frac{d^2V(x)}{dx^2} < 0$

A function  $V(x)$  is minimum when  $\frac{dV(x)}{dx} = 0$  and  $\frac{d^2V(x)}{dx^2} > 0$


# 1. Maxima and Minima


$$V(x) = \frac{1}{2}\beta x^2 + \frac{1}{4}\alpha x^4$$

**To find maxima and minima:**

$$\frac{dV(x)}{dx} = 0$$

$$\beta x + \alpha x^3 = 0$$


$$x(\beta + \alpha x^2) = 0$$


$$x = 0 \text{ and } x = \pm \sqrt{\frac{-\beta}{\alpha}}$$

# 1. Maxima and Minima

$$\frac{d^2V(x)}{dx^2} = \beta + 3\alpha x^2$$

When  $x=0$ ,  $\frac{d^2V(x)}{dx^2} = \beta < 0 \Rightarrow$  Maxima


$$\text{When } x = \pm \sqrt{\frac{-\beta}{\alpha}}, \frac{d^2V(x)}{dx^2} = -2\beta > 0$$

(since  $\beta < 0$ )  $\Rightarrow$  Minima

## 2. Zero crossing points

$$V(x) = 0$$

$$\frac{1}{2}\beta x^2 + \frac{1}{4}\alpha x^4 = 0$$


$$x = \pm \sqrt{\frac{-2\beta}{\alpha}} \text{ and } x=0$$

# Plot for small and large values of x

1. Maxima at  $x = 0$

Minima at

$$-\sqrt{\frac{-\beta}{\alpha}}$$

and

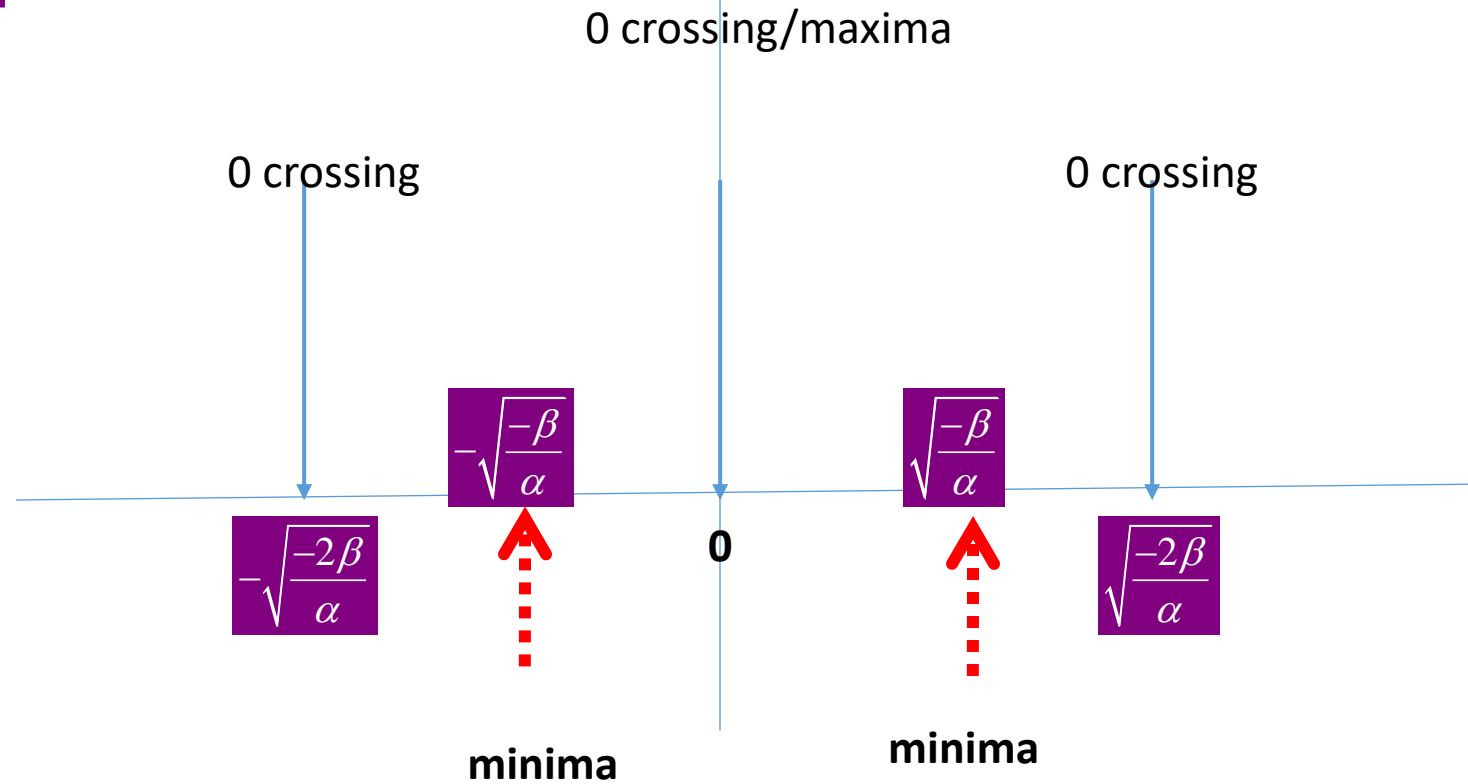
$$\sqrt{\frac{-\beta}{\alpha}}$$

$$V(x) = \frac{1}{2}\beta x^2 + \frac{1}{4}\alpha x^4$$

2. Zero crossing at 3 points,  $x = 0,$

$$-\sqrt{\frac{-2\beta}{\alpha}}$$

$$\sqrt{\frac{-2\beta}{\alpha}}$$



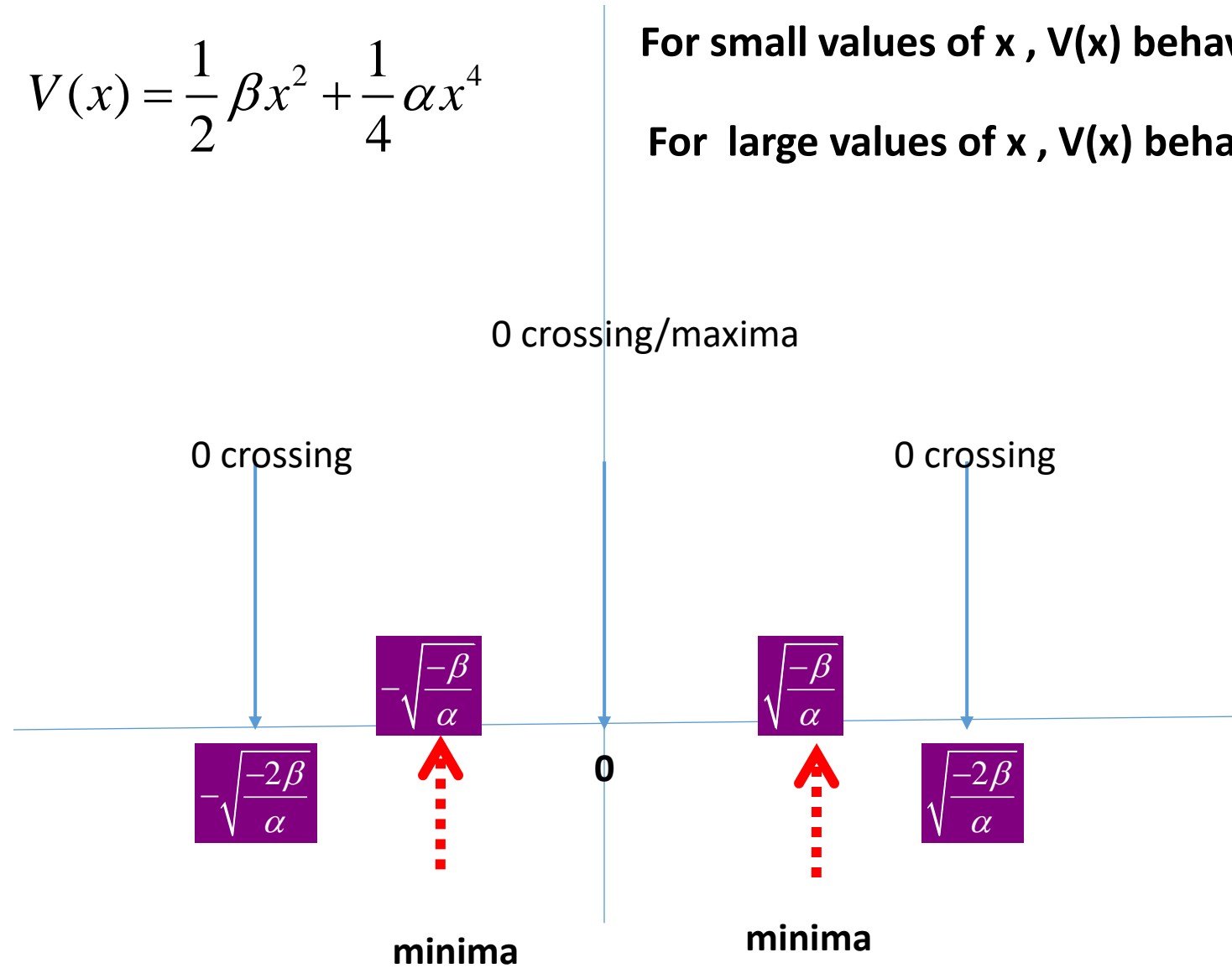


# Plot for small and large values of x

$$V(x) = \frac{1}{2} \beta x^2 + \frac{1}{4} \alpha x^4$$

For small values of x , V(x) behaves as x<sup>2</sup>

For large values of x , V(x) behaves as x<sup>4</sup>



# Concept of equilibrium

## Duffing Oscillator

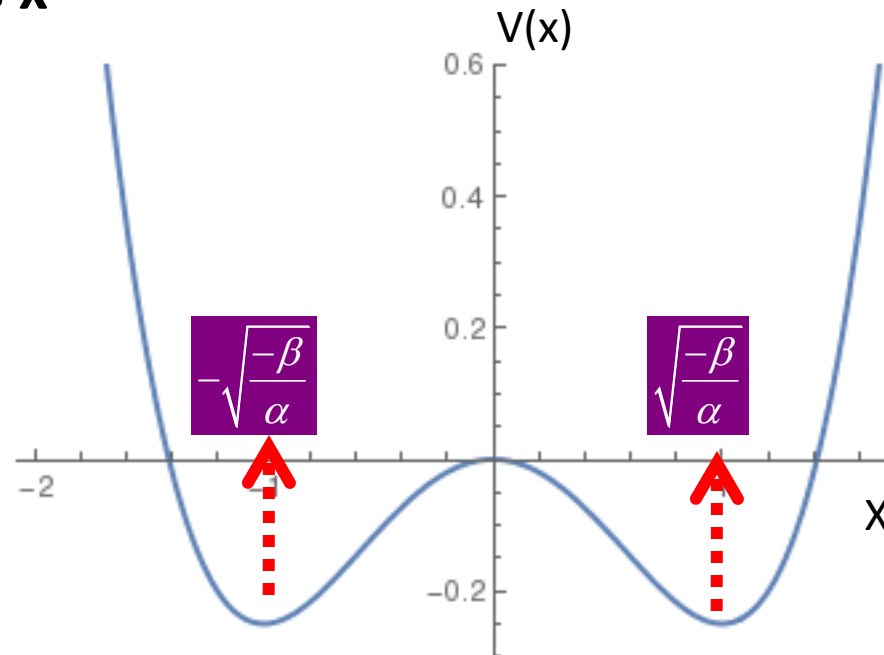
$$V(x) = \frac{1}{2} \beta x^2 + \frac{1}{4} \alpha x^4, \quad \beta < 0$$

Plot  $V(x)$  v/s  $x$

1. Maxima at  $x = 0$

Minima at  $-\sqrt{\frac{-\beta}{\alpha}}$

and  $\sqrt{\frac{-\beta}{\alpha}}$



To Plot the graph

1. Find Maxima and Minima

2. Find the zero crossing points

3. Imagine the function For smaller and larger

Values of  $x$

2. Zero crossing at 3 points,  $x = 0,$

$$-\sqrt{\frac{-2\beta}{\alpha}}$$

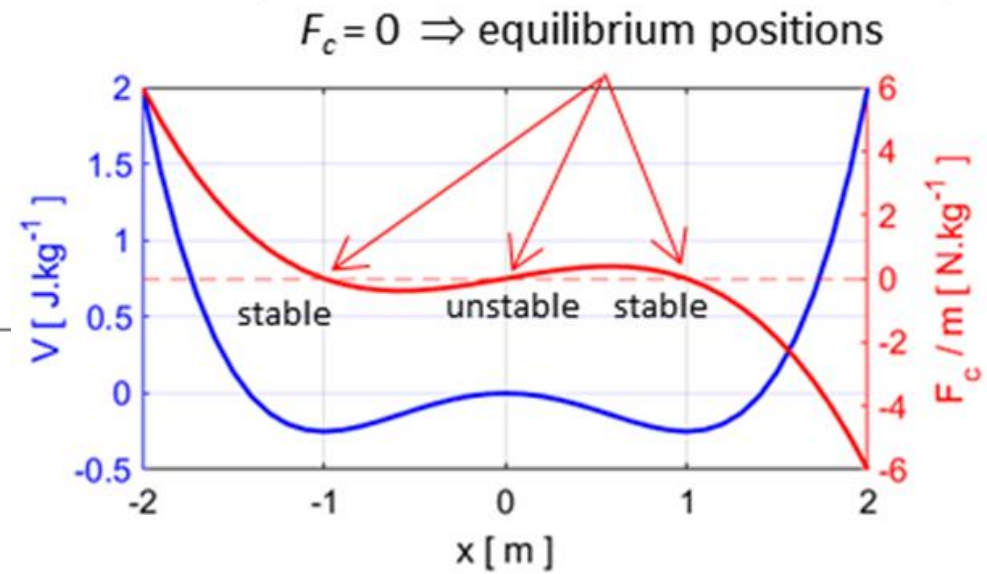
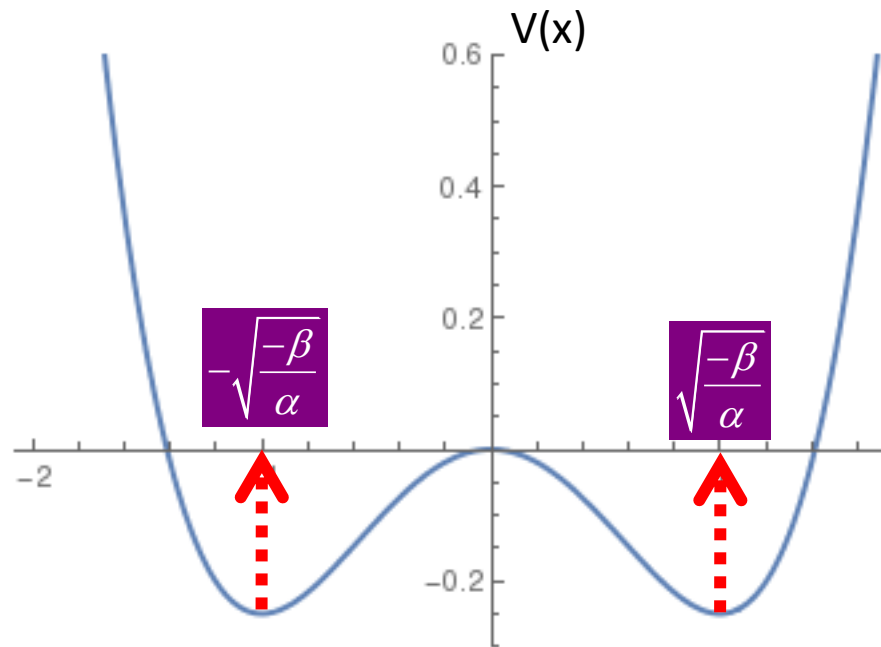
$$\sqrt{\frac{-2\beta}{\alpha}}$$

# Concept of equilibrium

## Duffing Oscillator

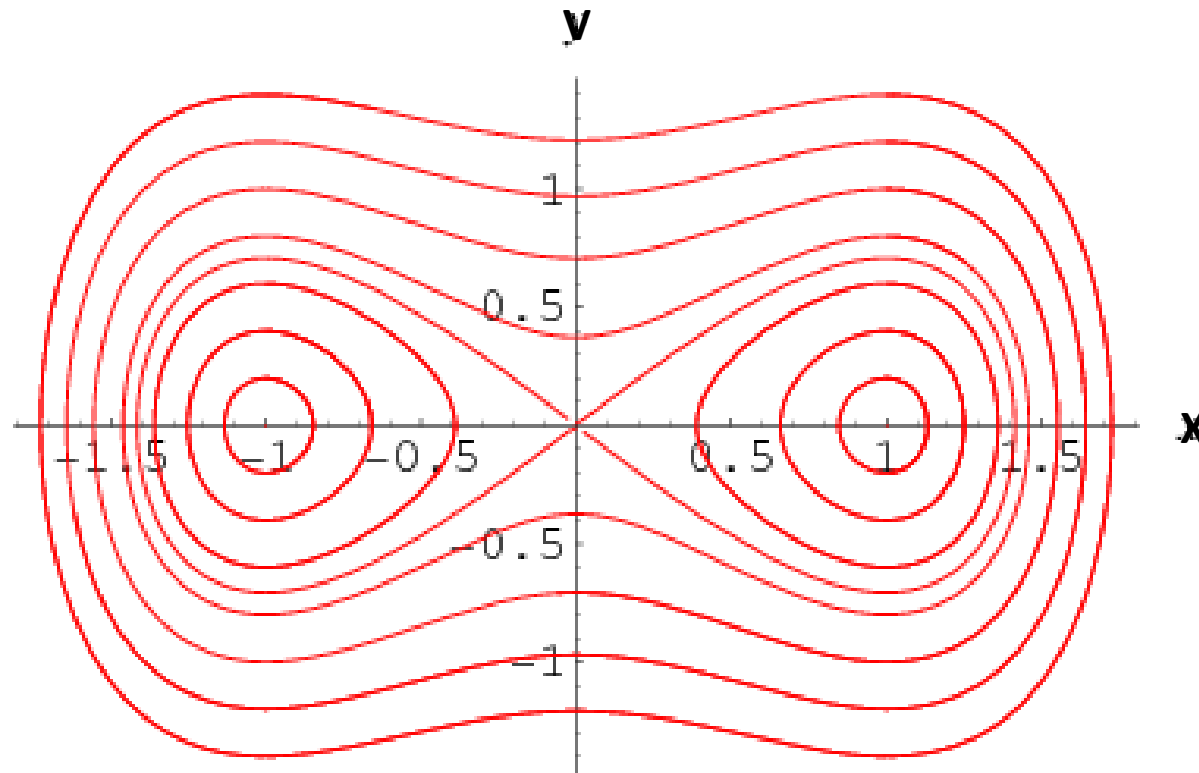
$$V(x) = \frac{1}{2}\beta x^2 + \frac{1}{4}\alpha x^4, \quad \beta < 0$$

$$\text{Component of Force } F(x) = -\frac{dV(x)}{dx} = -\beta x - \alpha x^3$$

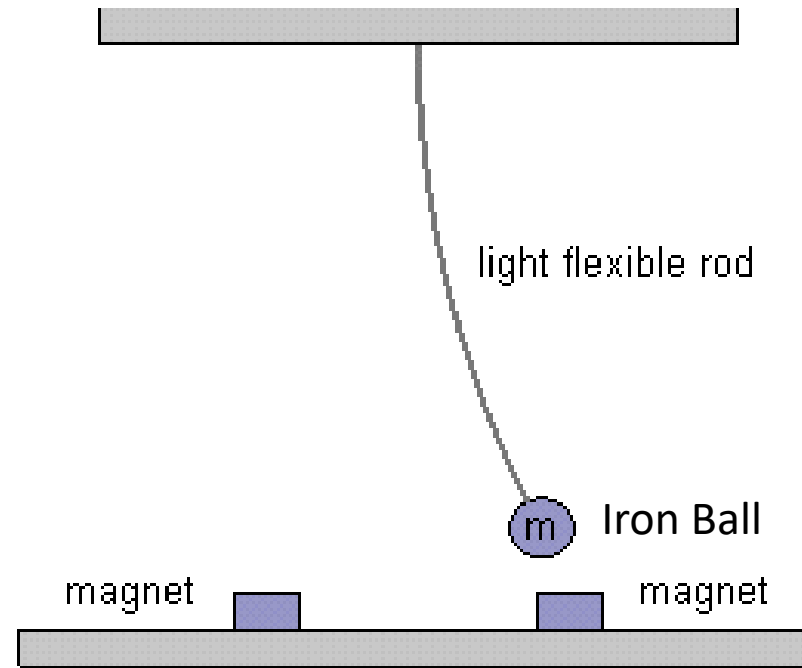
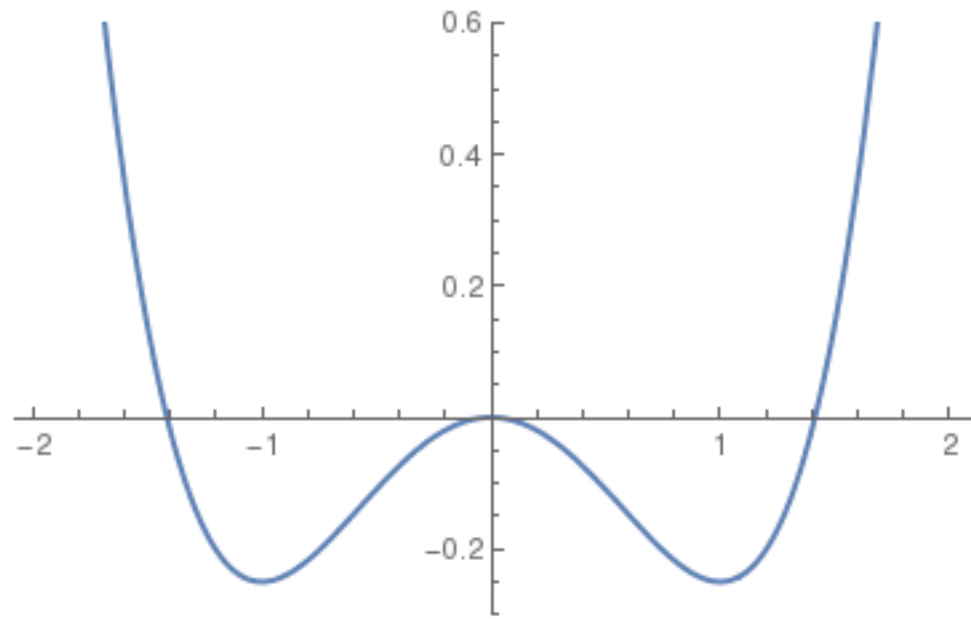


# Velocity Vs. Position plot

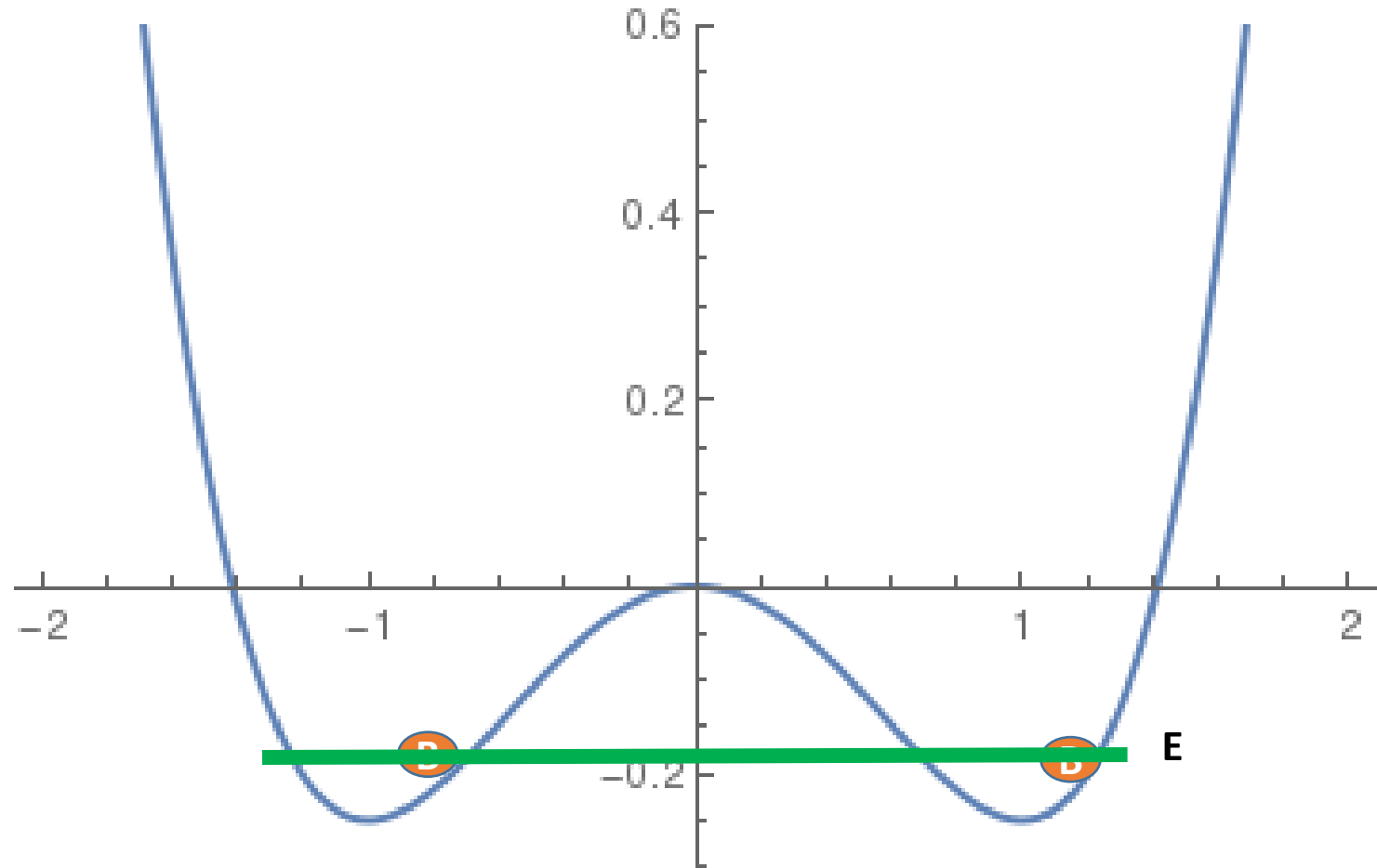
$$E = \frac{1}{2} \beta x^2 + \frac{1}{4} \alpha x^4 + \frac{1}{2} m v^2$$

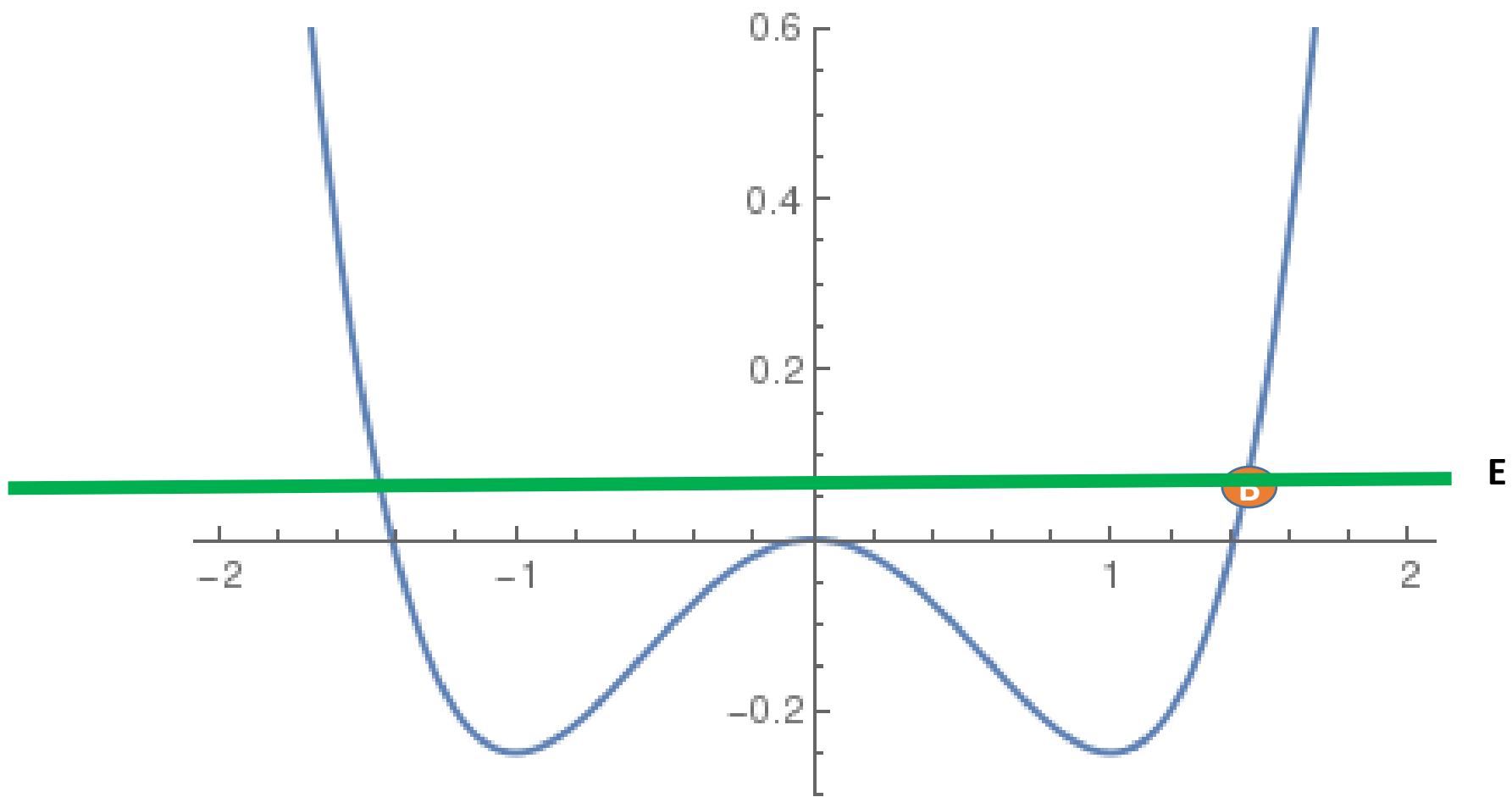


# Physical Example of double well



# Duffing Oscillator (Georg Duffing, German engineer)





# Velocity Vs. Position plot (Summary)

