

Introduction to Deep Learning

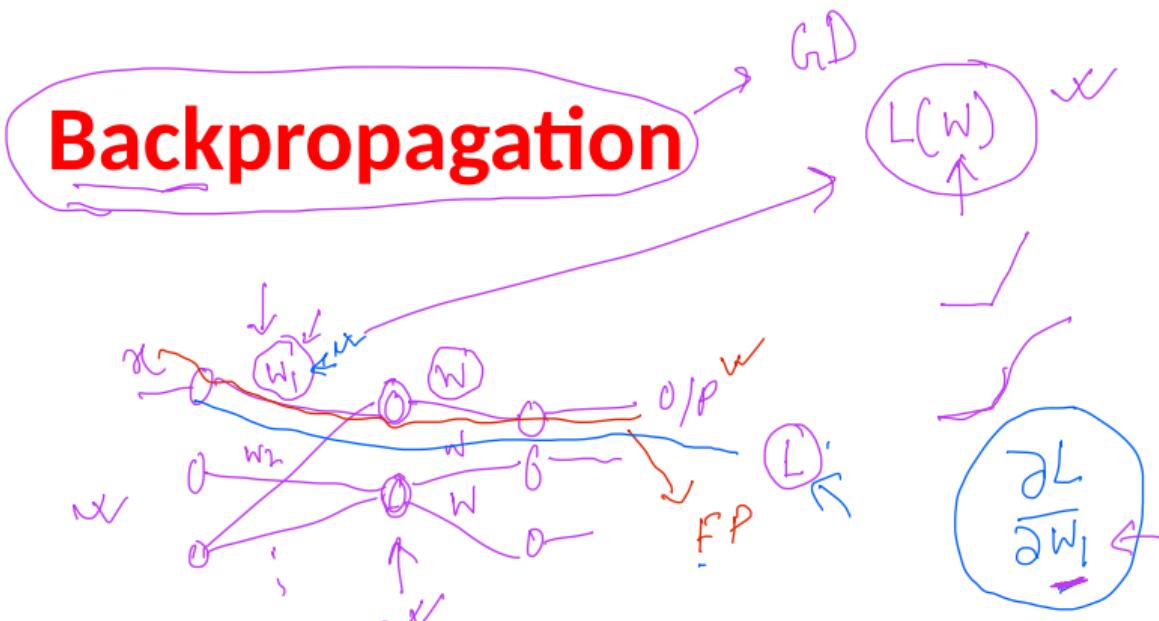


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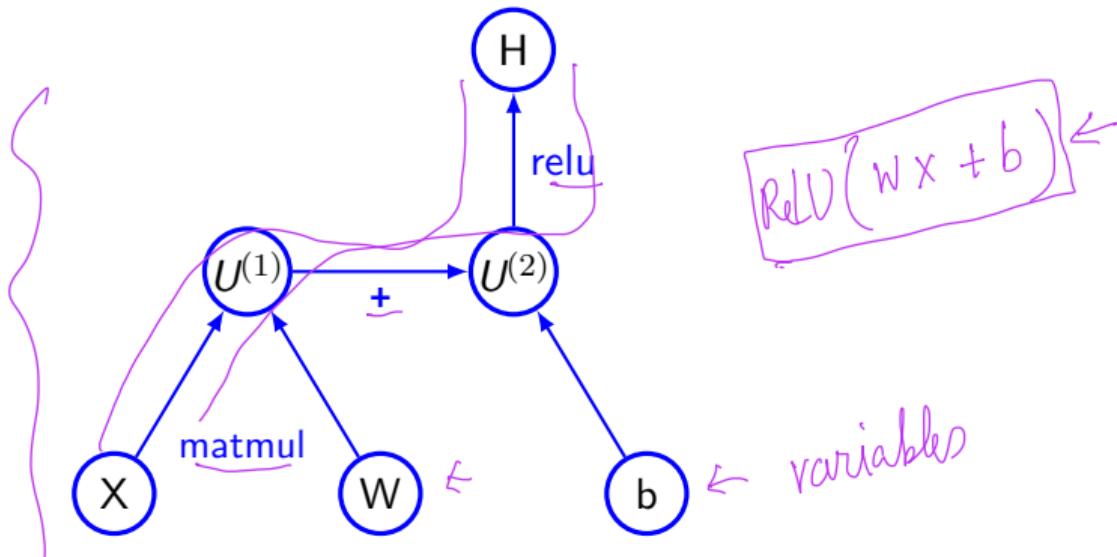
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Back propagation

- In a feedforward network, an input x is read and produces an output \hat{y}
 - This is forward propagation |
- During training forward propagation continues until it produces cost $J(\theta)$
- Back-propagation algorithm allows the information to flow backward in the network to compute the gradient
- Computation of analytical expression for gradient is easy
- We need to find out gradient of the cost function with respect to the parameters ie. $\nabla_{\theta} J(\theta)$

Computational graph

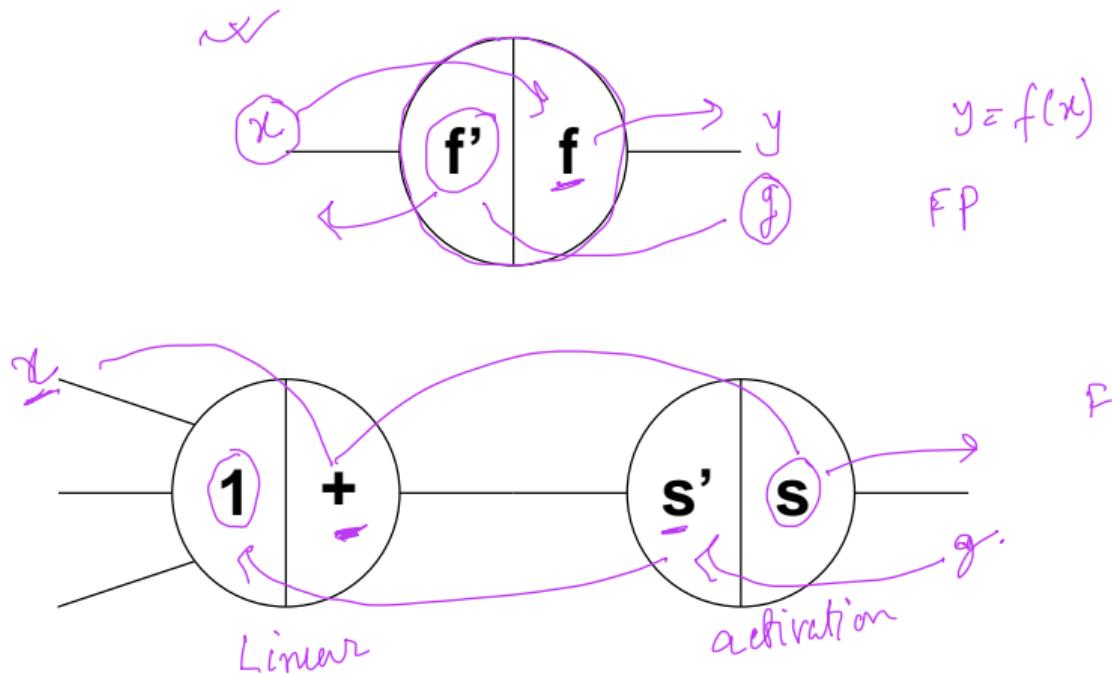


Chain rule of calculus

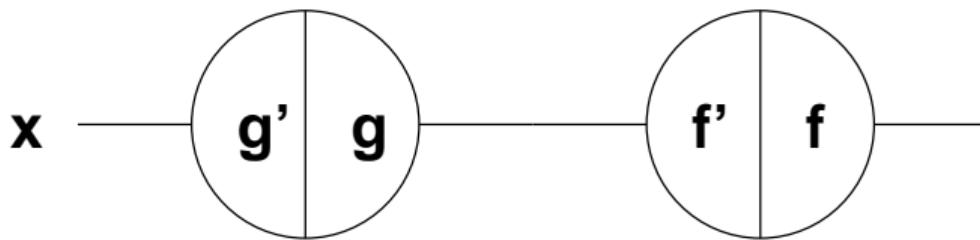
- Back-propagation algorithm heavily depends on it
- Let x be a real number and $y = g(x)$ and $z = f(g(x)) = f(y)$ $\approx x, y, z$
- Chain rule says $\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$, $w \leftarrow v$
- This can be generalized: Let $x \in \mathbb{R}^m$, $y \in \mathbb{R}^n$, $g: \mathbb{R}^m \rightarrow \mathbb{R}^n$ and $f: \mathbb{R}^n \rightarrow \mathbb{R}$ and $y = g(x)$ and $z = f(y)$ then $\frac{\partial z}{\partial x_i} = \sum_j \frac{\partial z}{\partial y_j} \frac{\partial y_j}{\partial x_i}$
- In vector notation it will be where $\frac{\partial y}{\partial x}$ is the $n \times m$ Jacobian matrix of g

$$\nabla_x z = \left(\frac{\partial y}{\partial x} \right)^T \nabla_y z$$

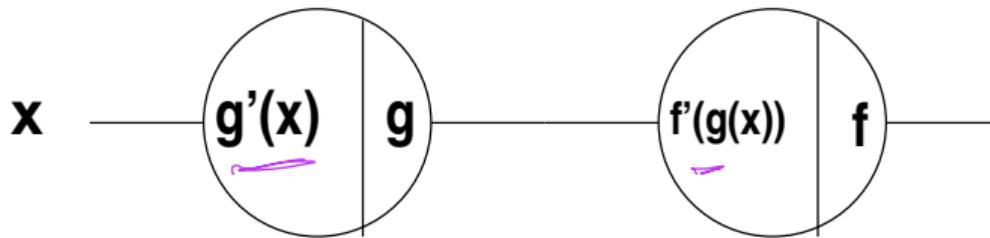
Back propagation



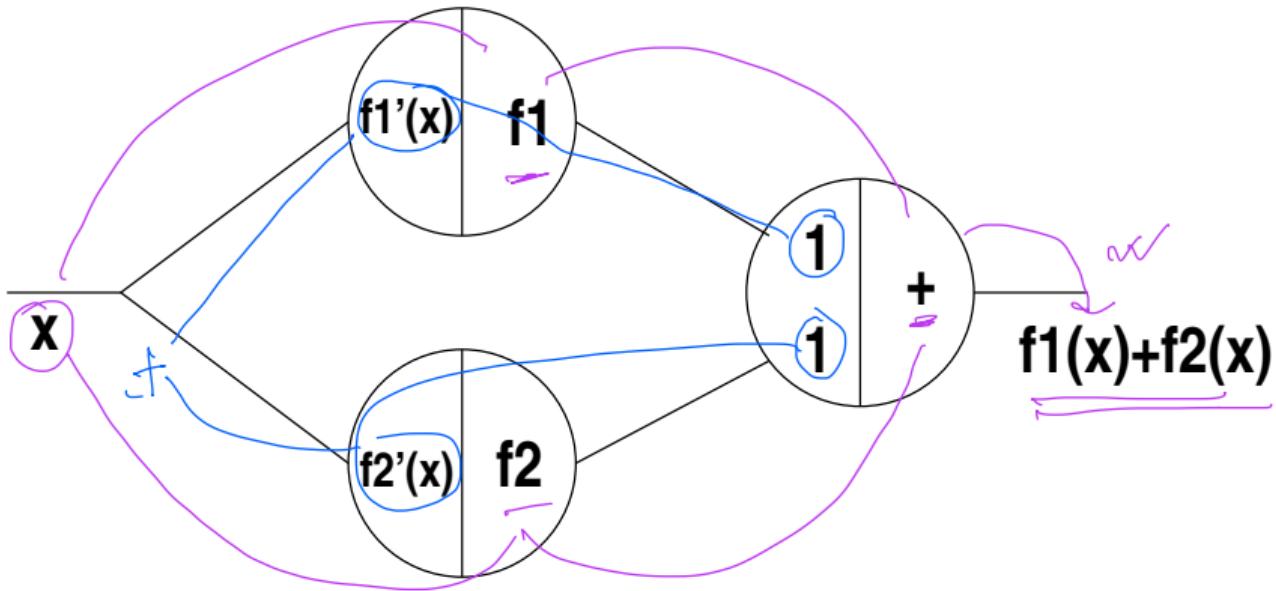
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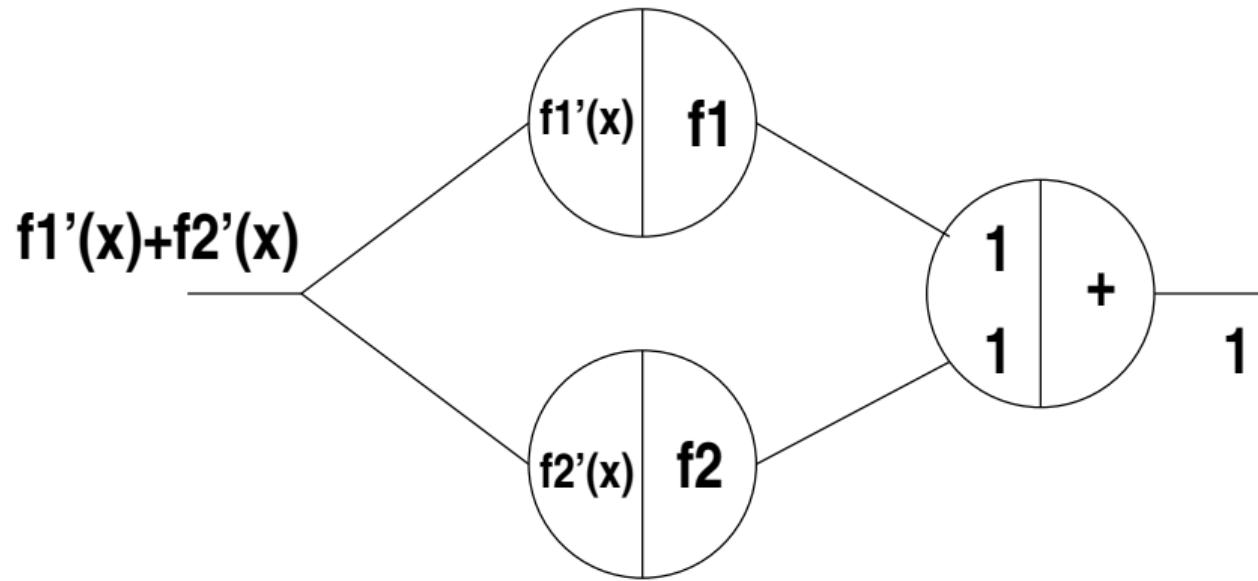
Back propagation



Back propagation



Back propagation



Backpropagation

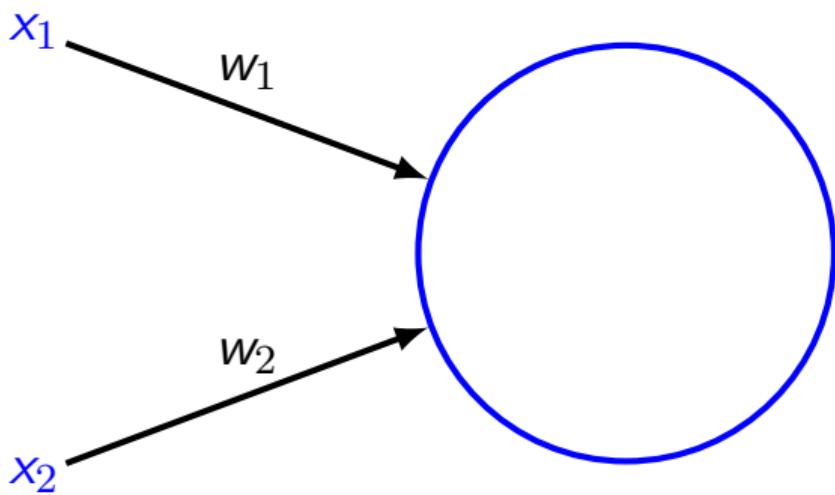
x_1

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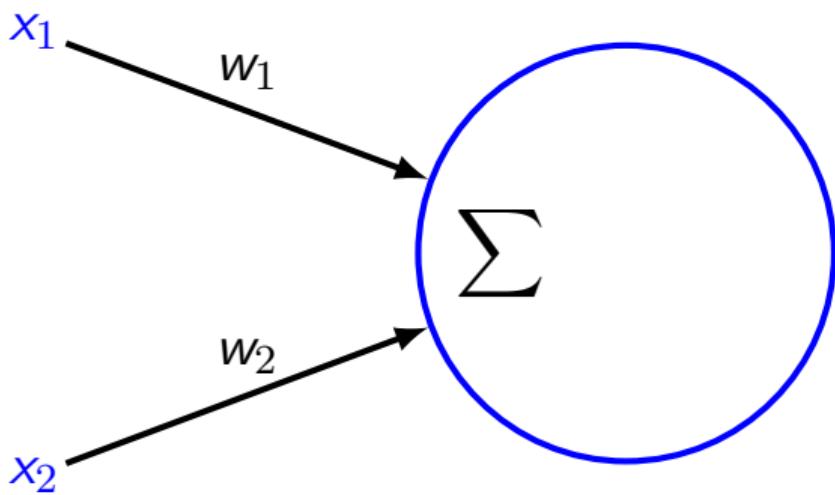
x_2

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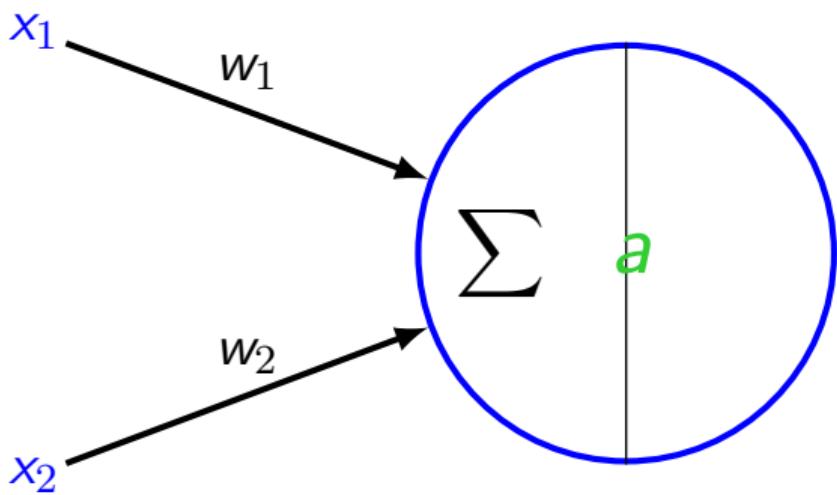
Backpropagation



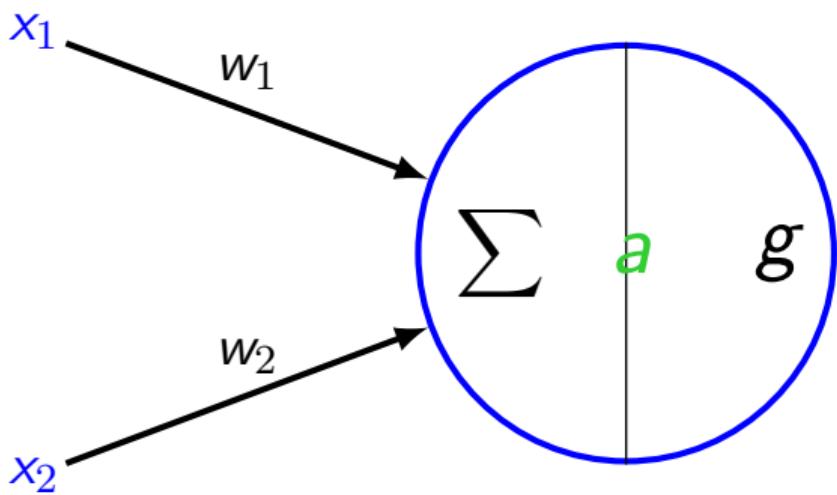
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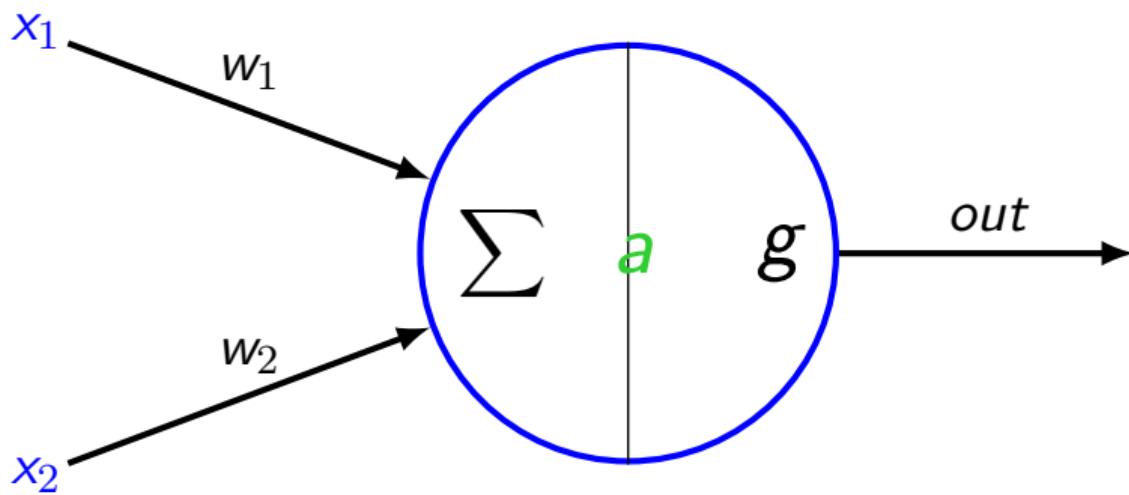
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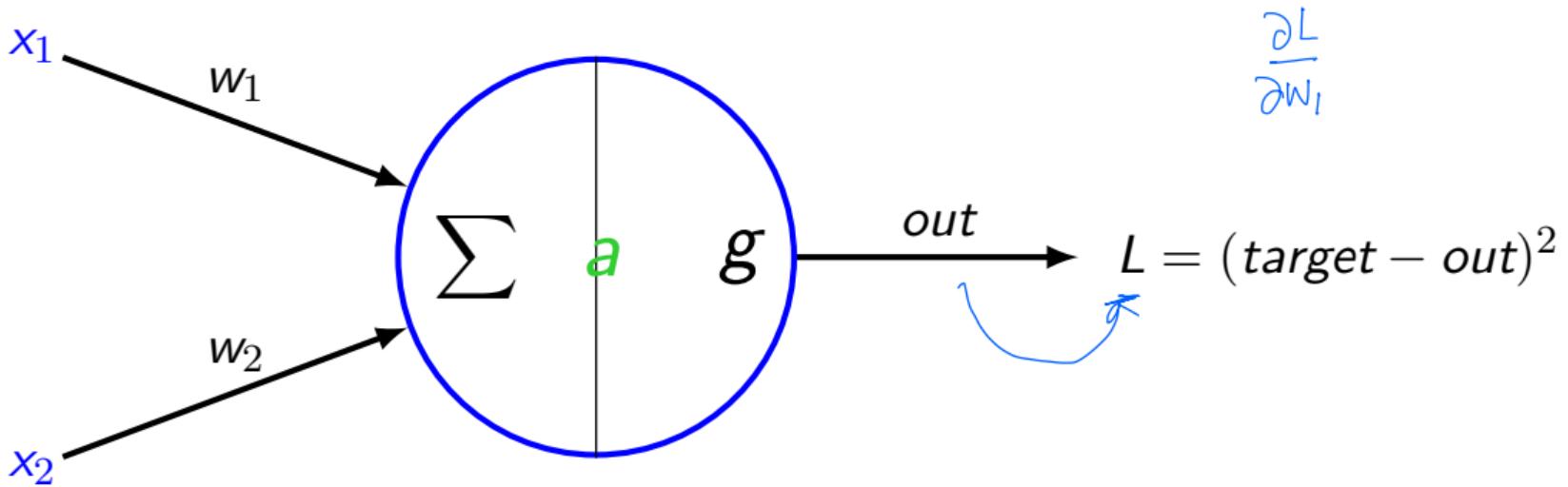
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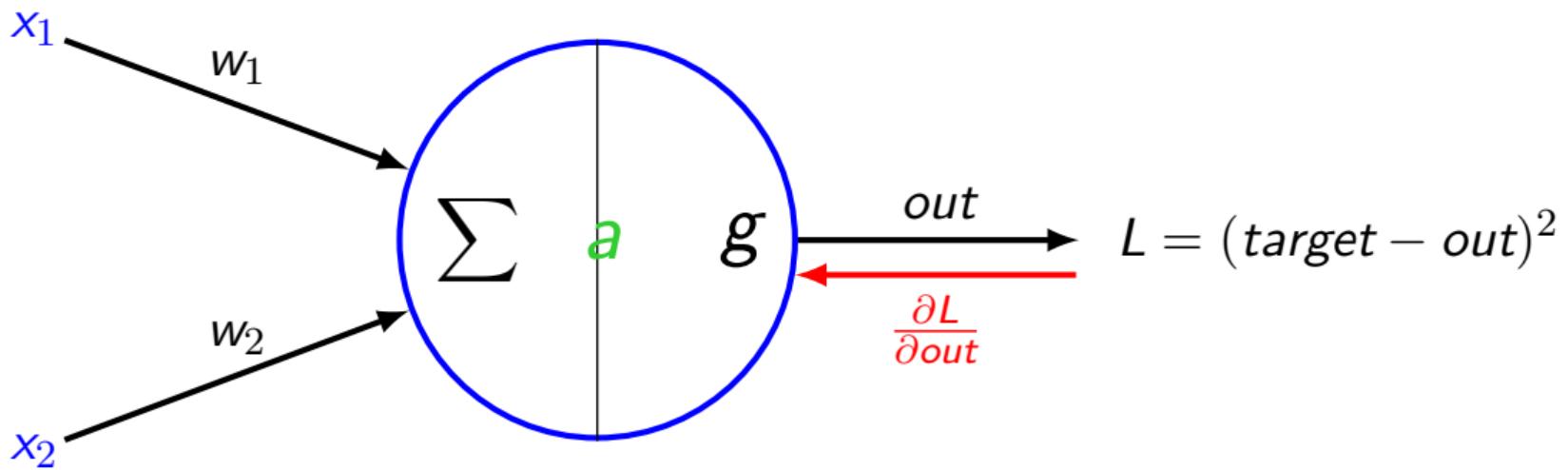
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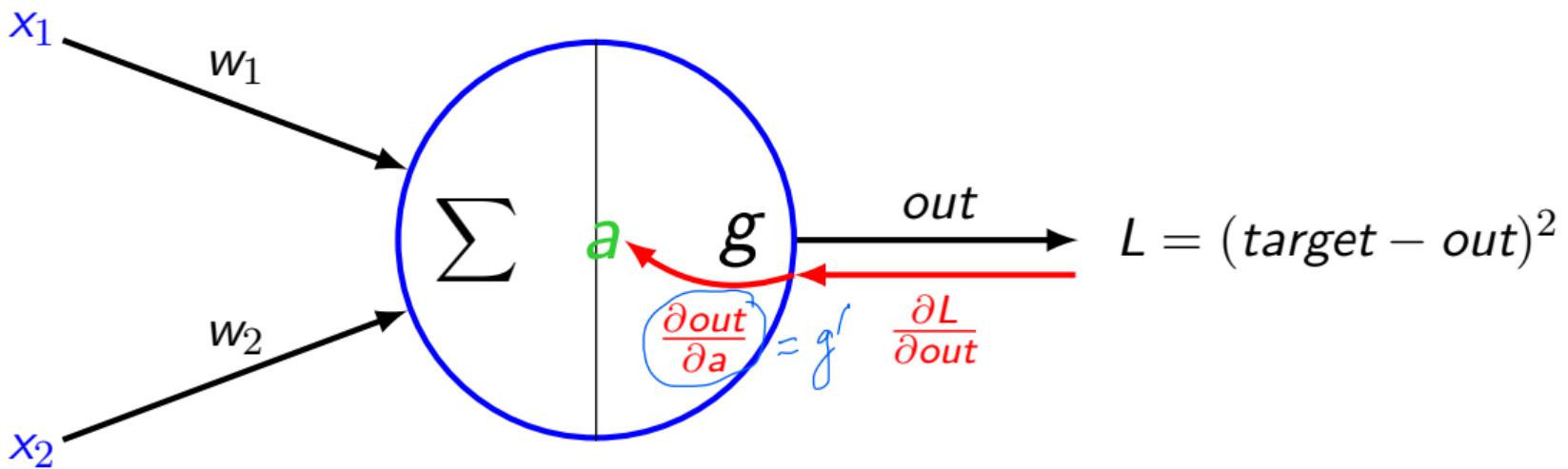
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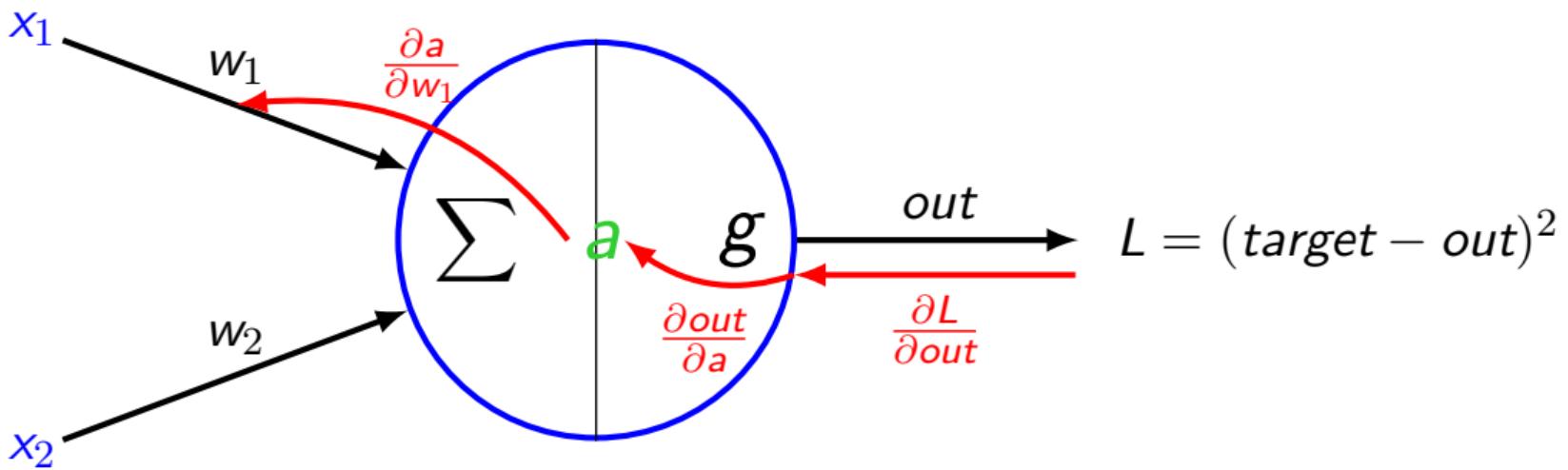
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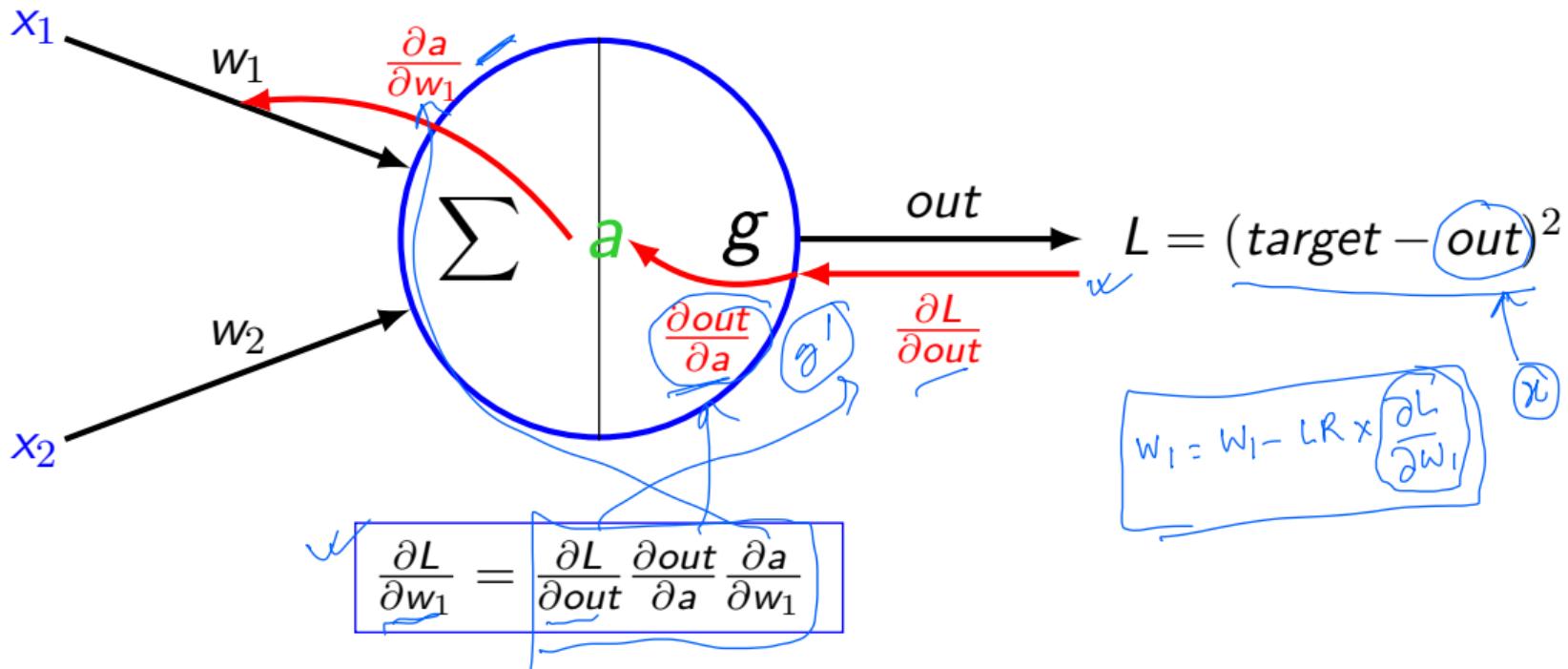
Backpropagation



Backpropagation

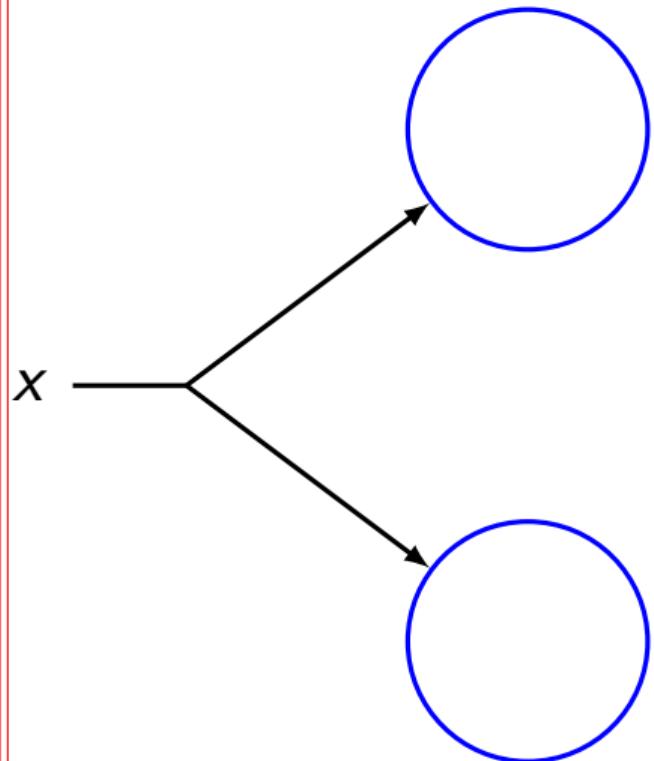


Backpropagation

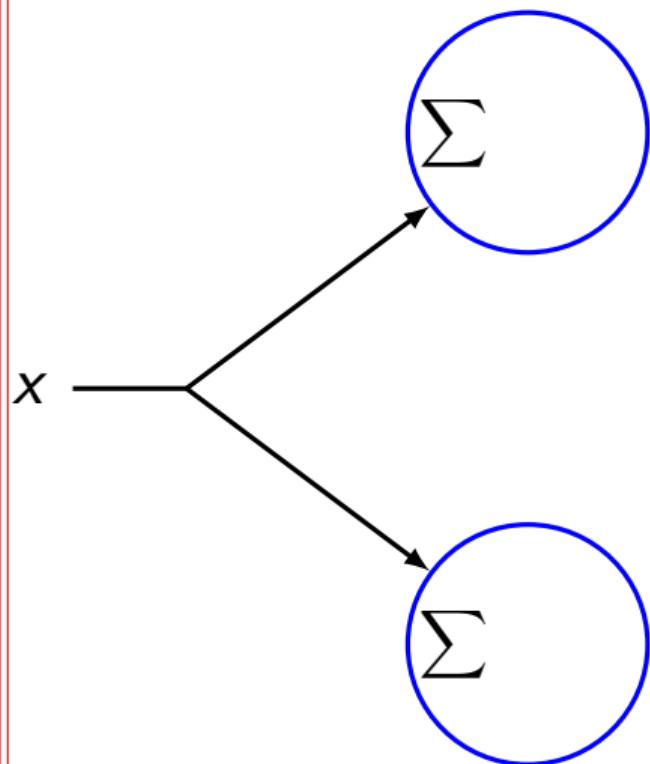


Backpropagation

Backpropagation



Backpropagation



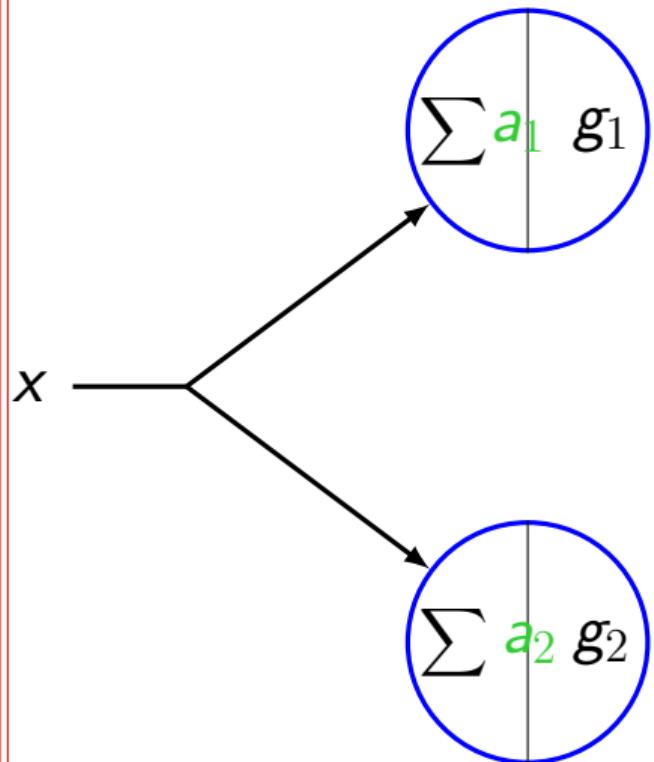
Backpropagation

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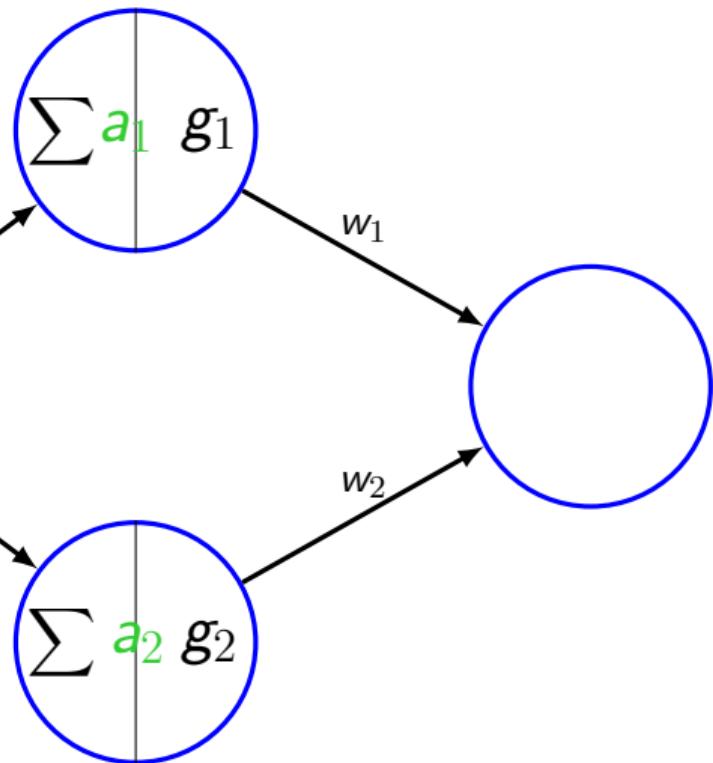


Backpropagation



Backpropagation

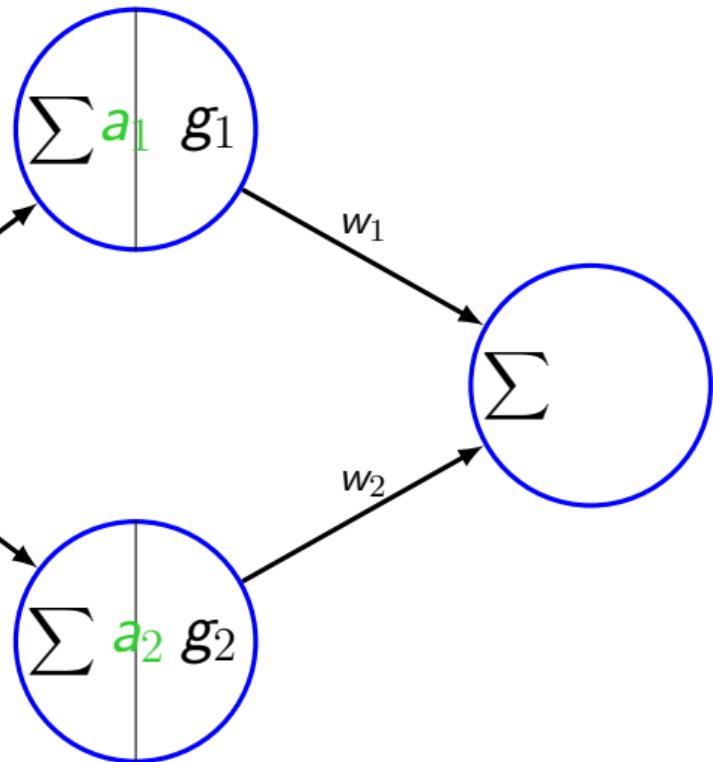
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Backpropagation

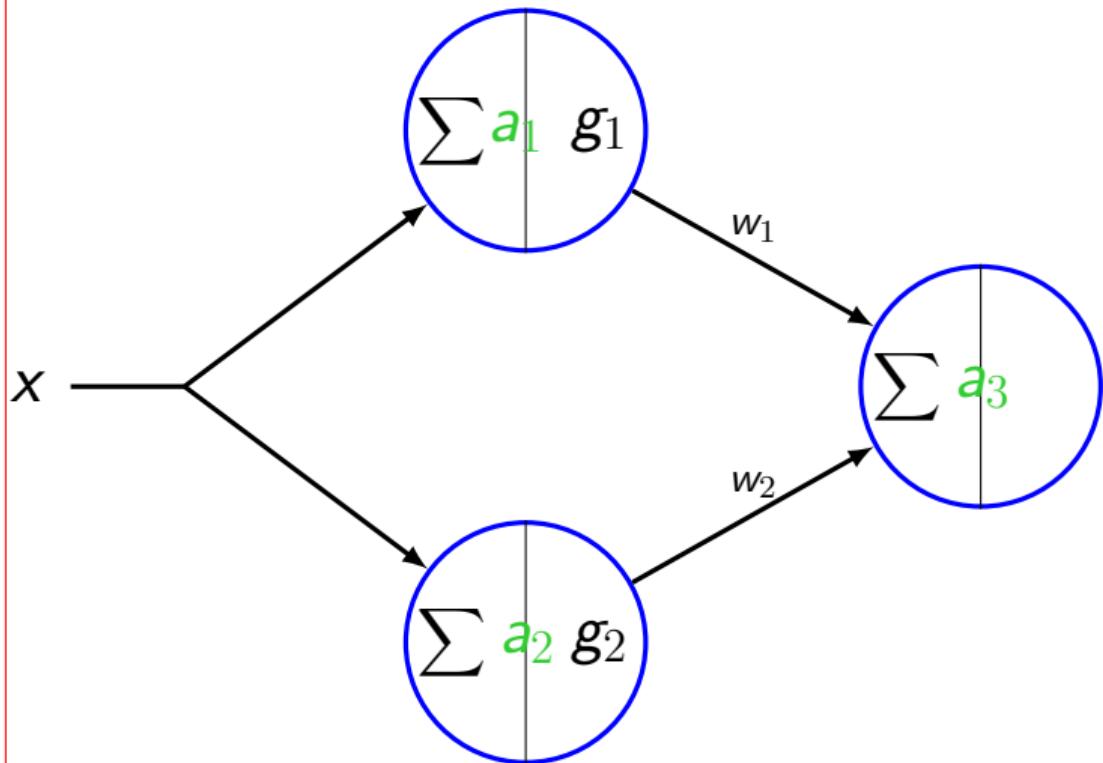
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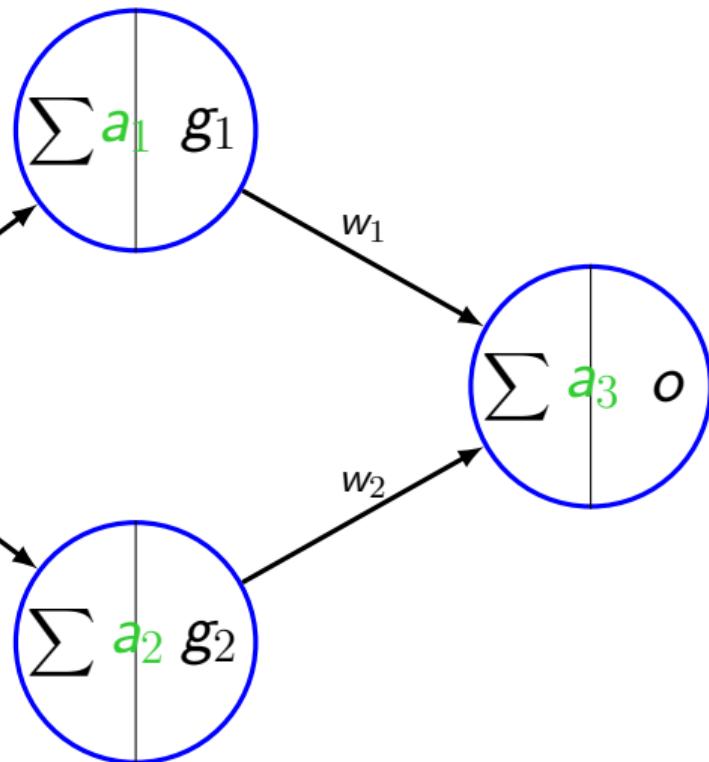
Backpropagation

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Backpropagation

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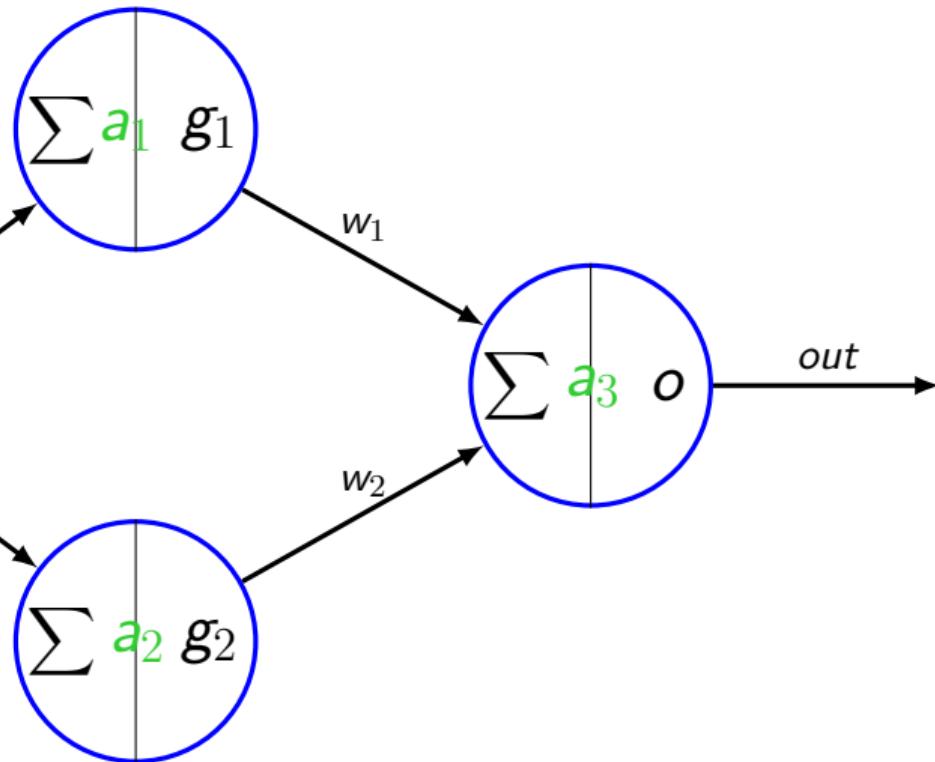


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Backpropagation

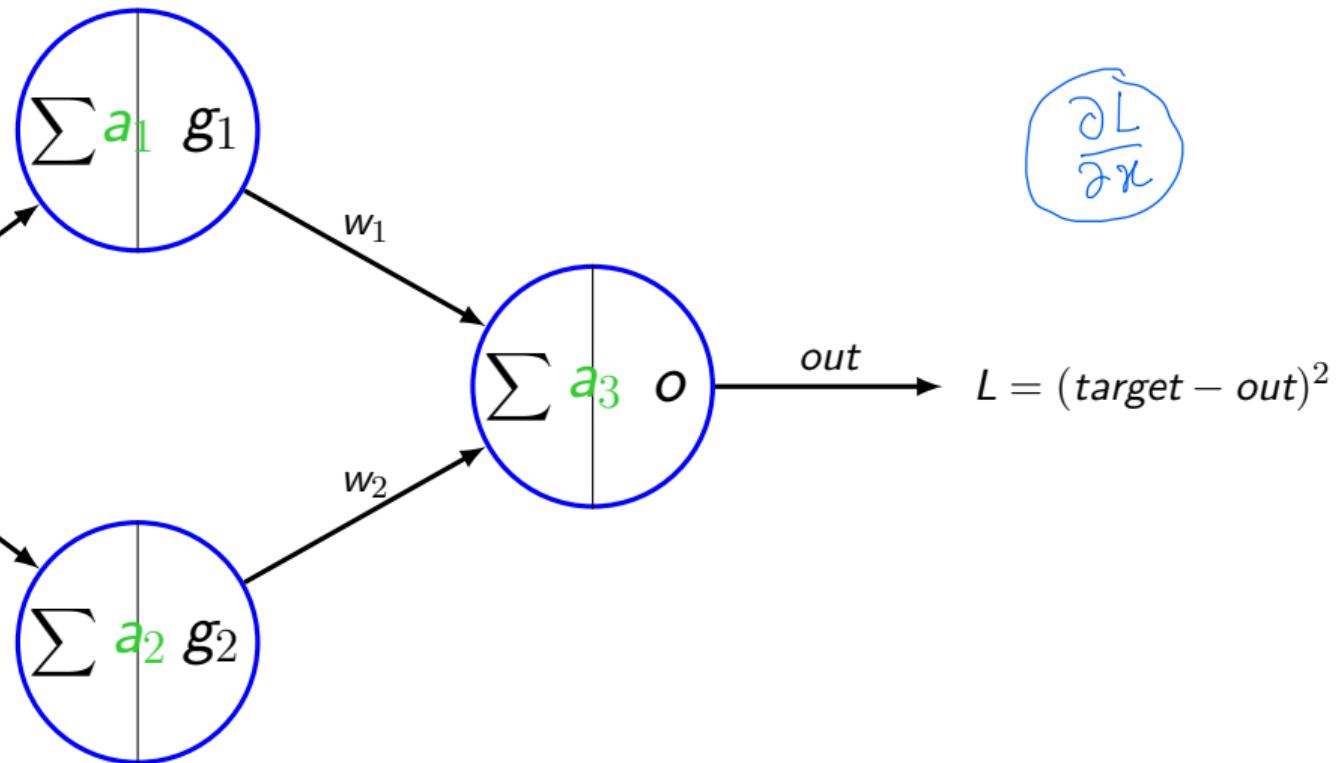
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X



Backpropagation

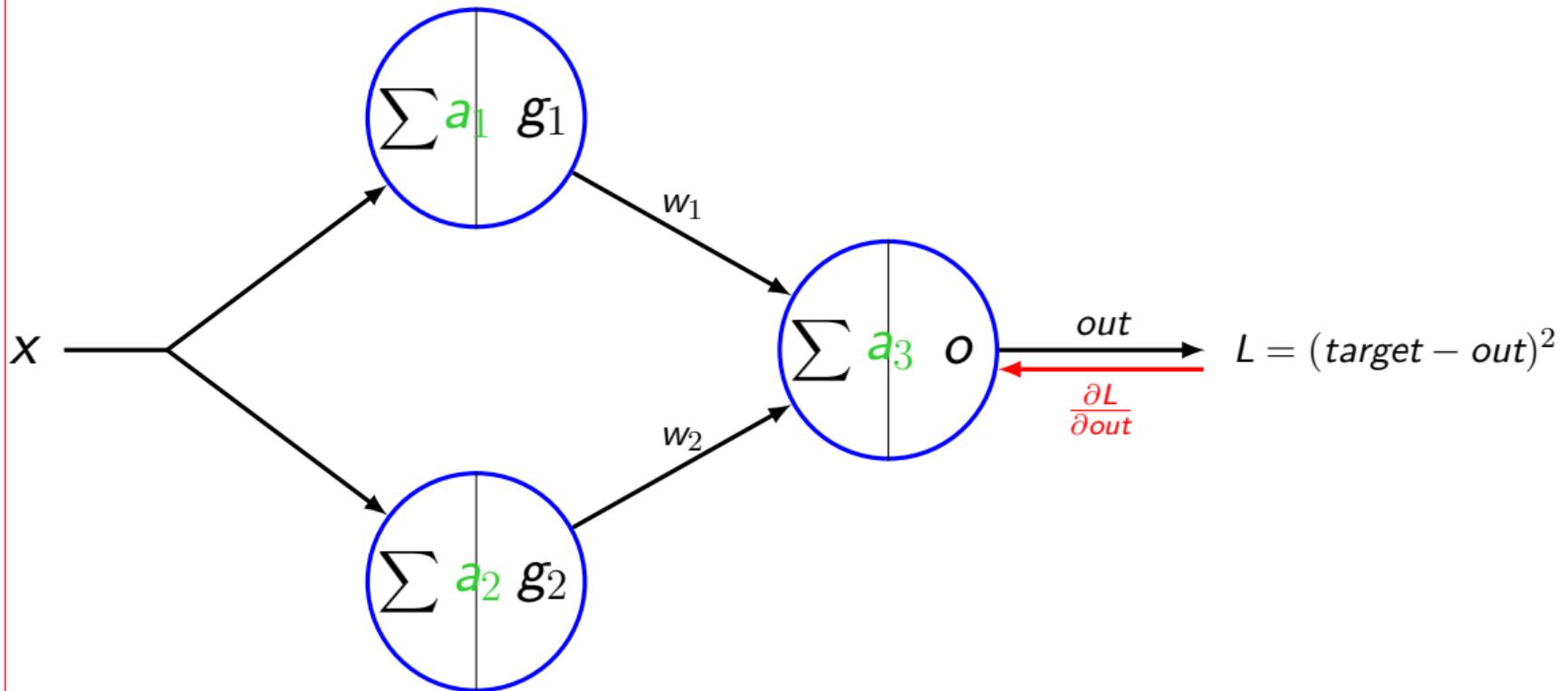
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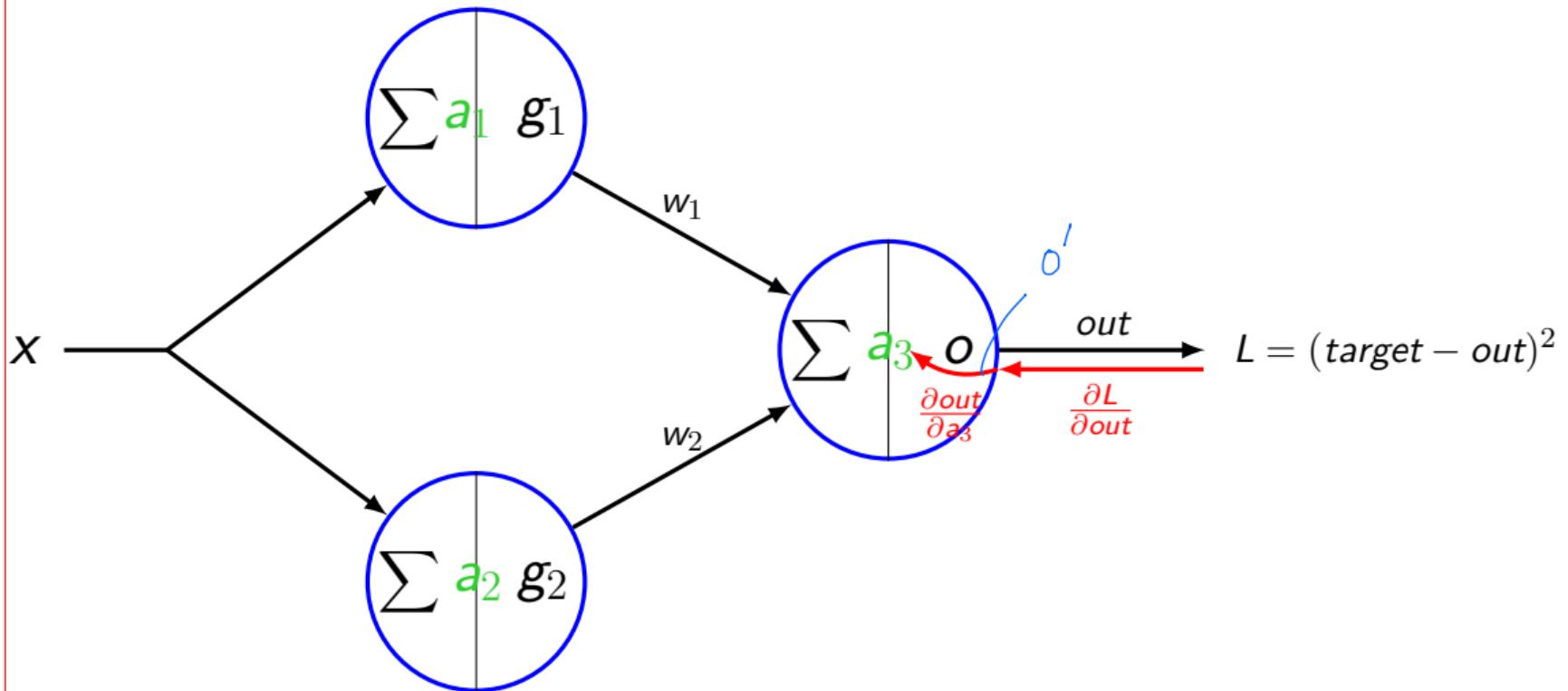
Backpropagation

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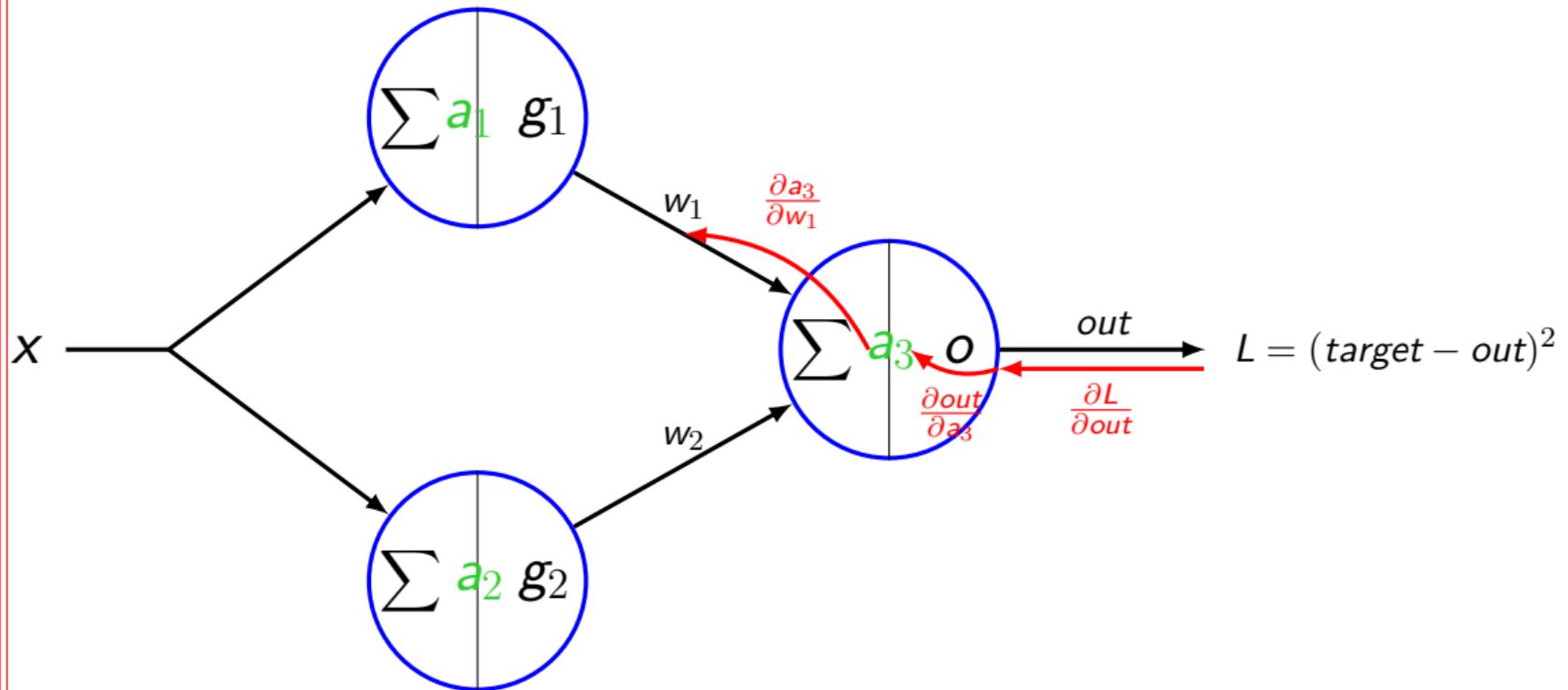
Backpropagation

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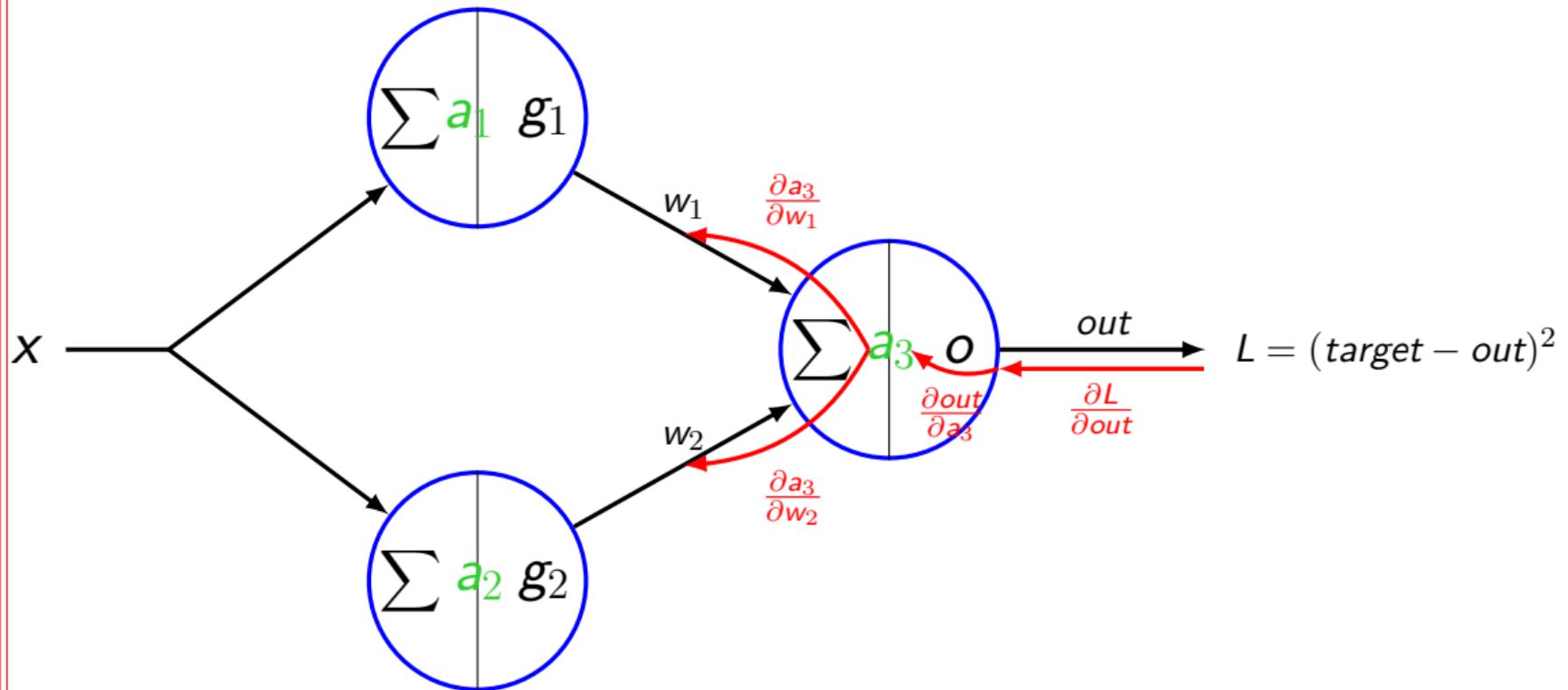
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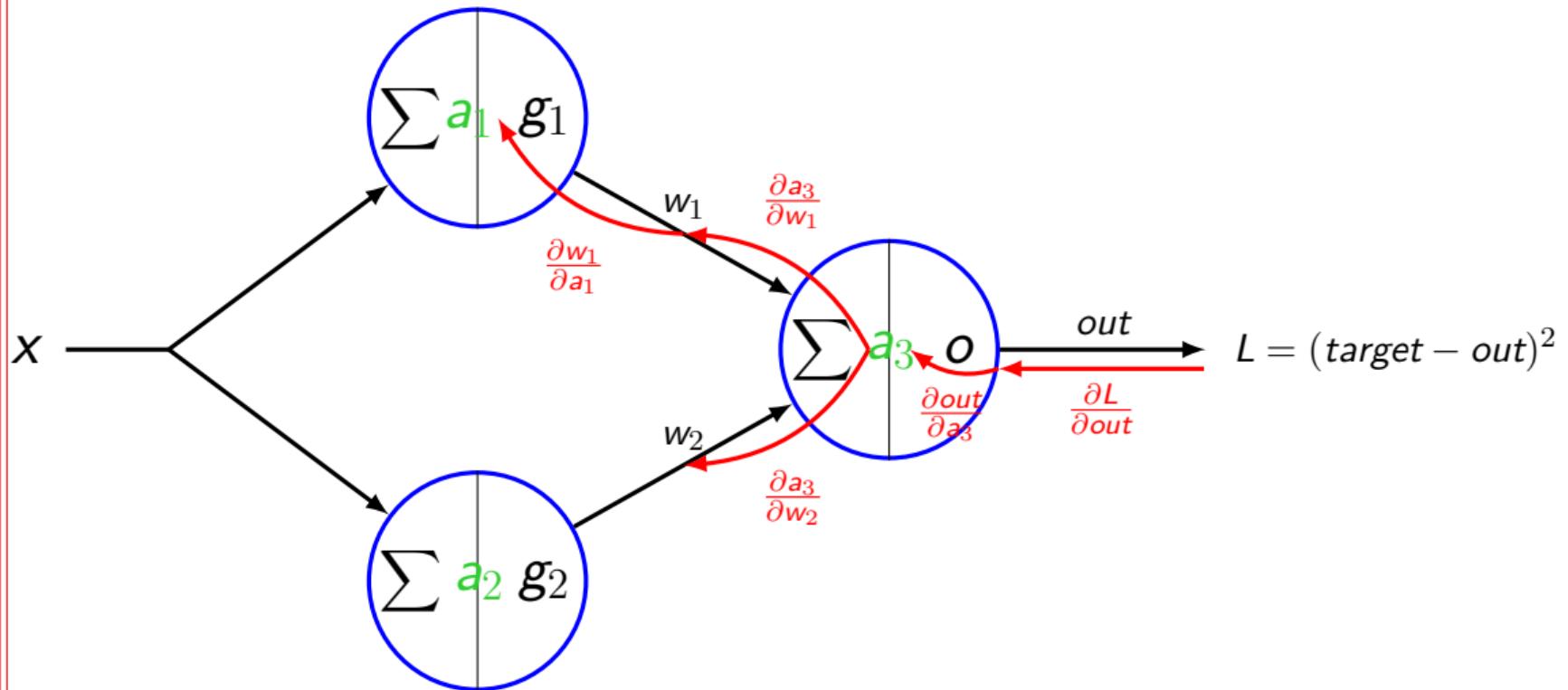
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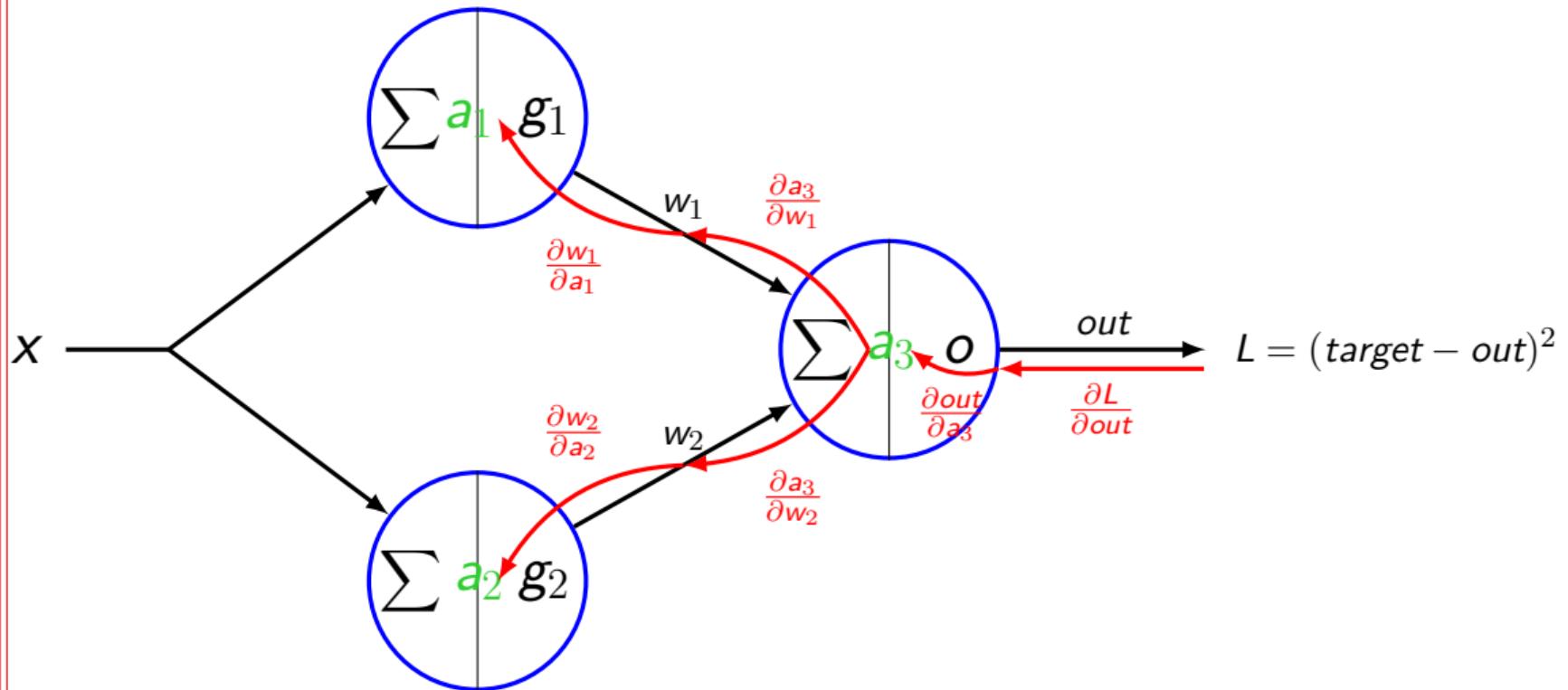
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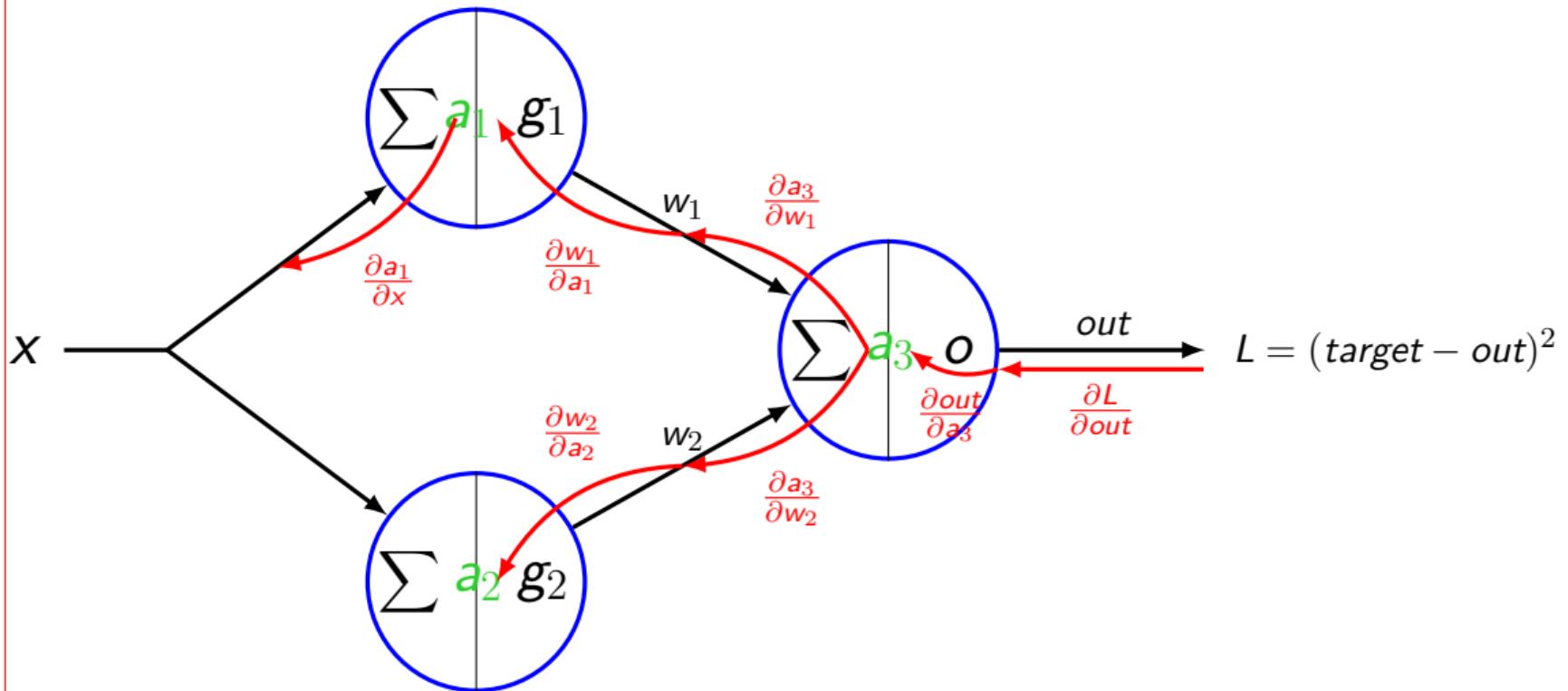
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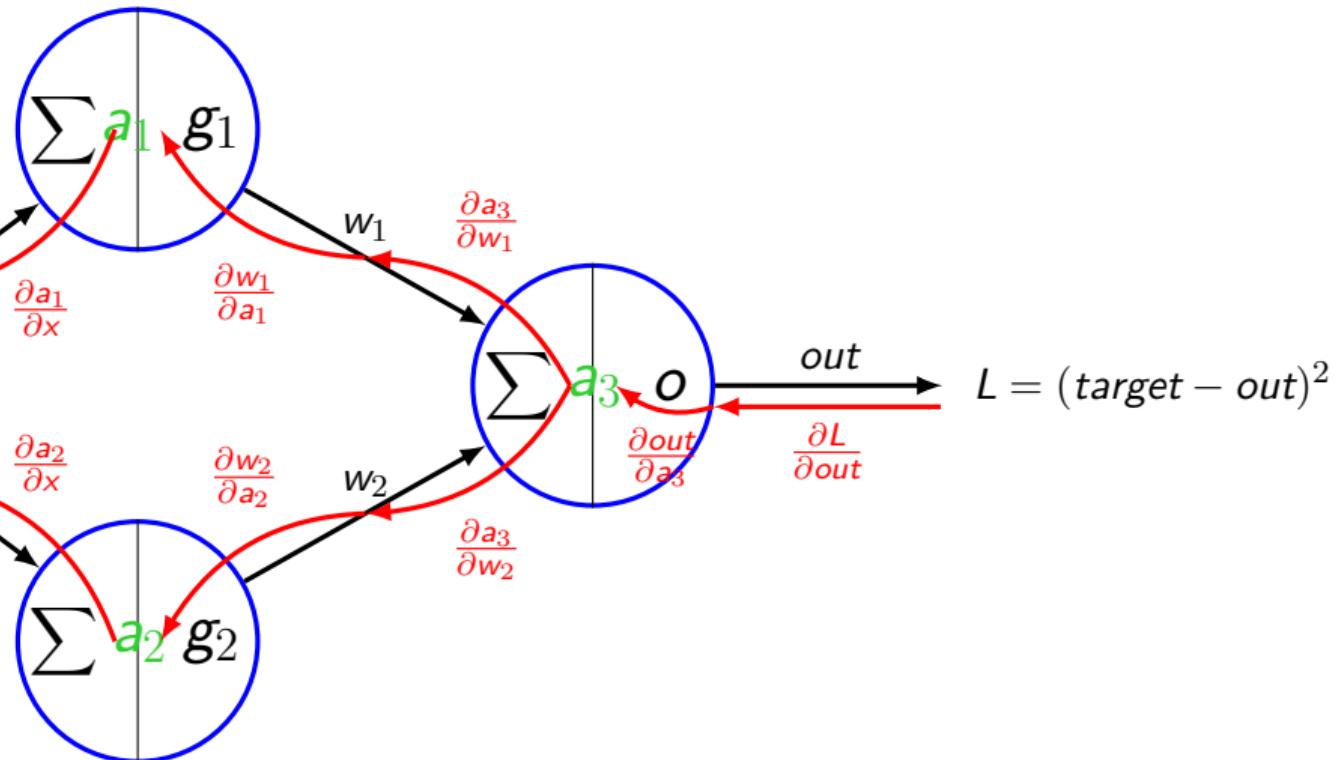
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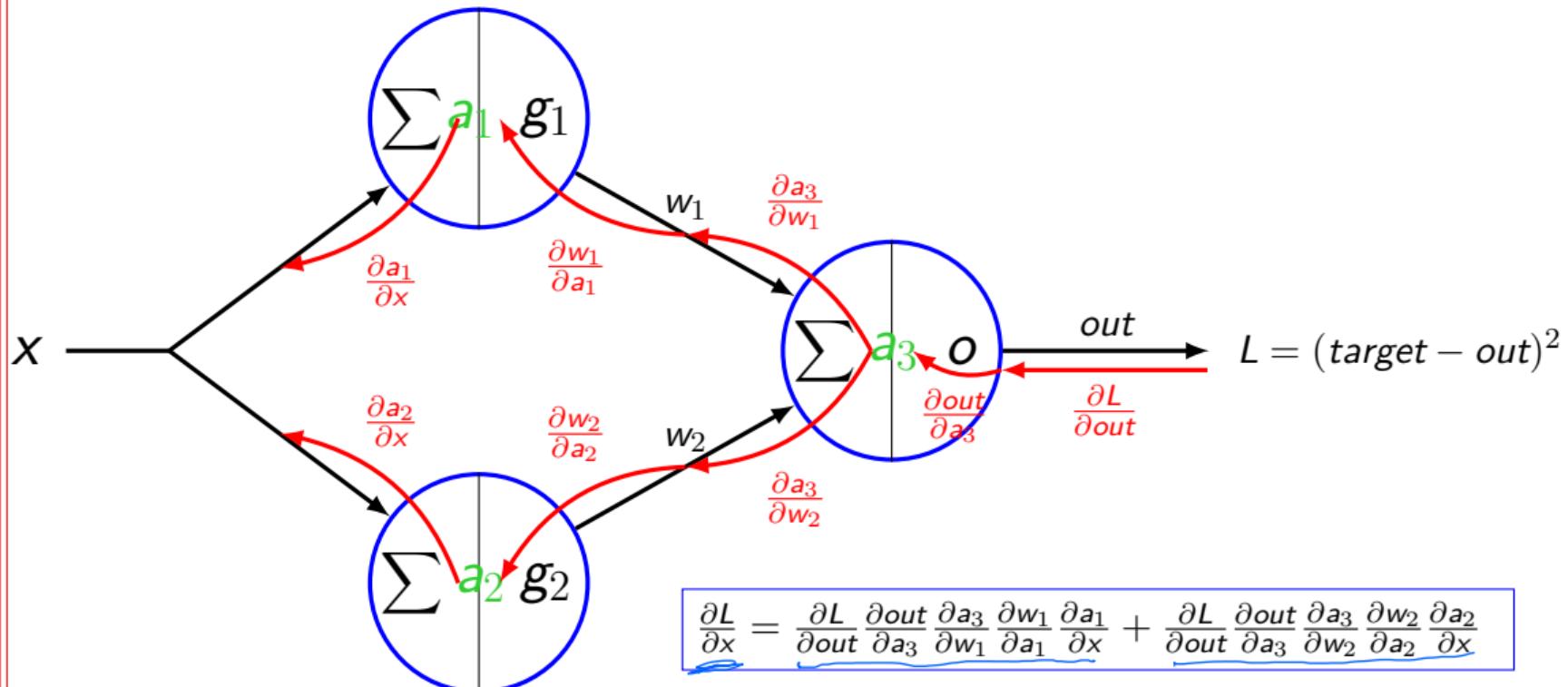
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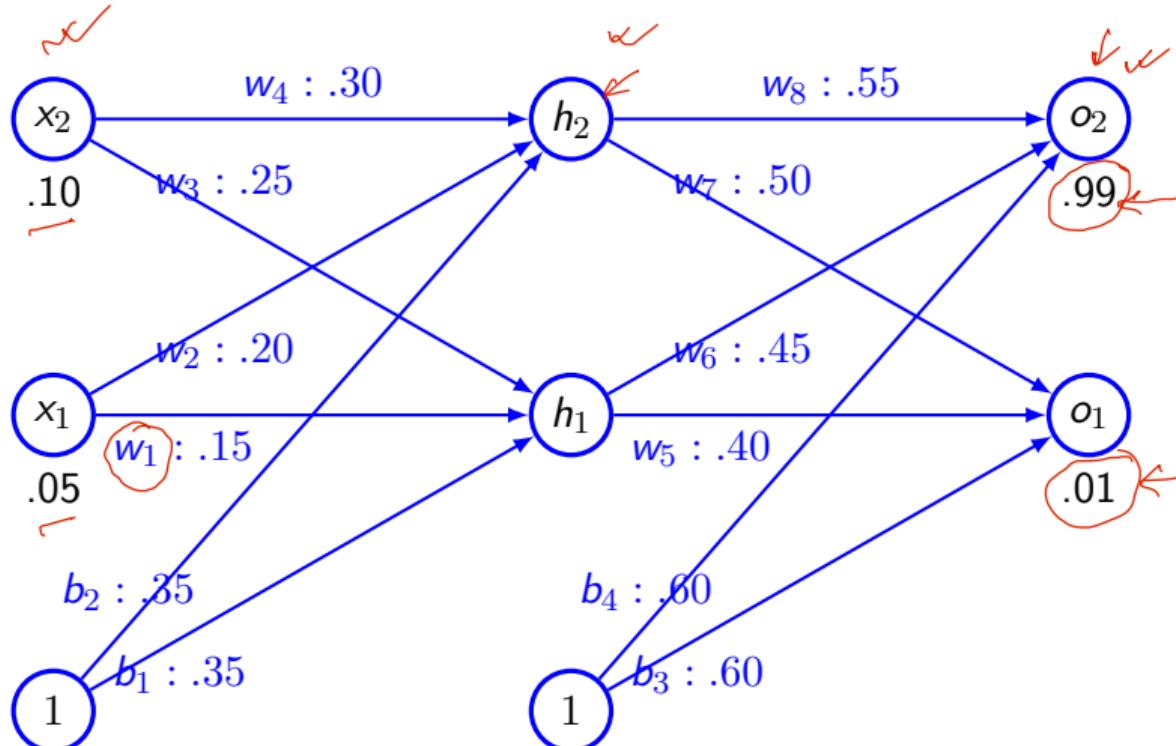


Backpropagation

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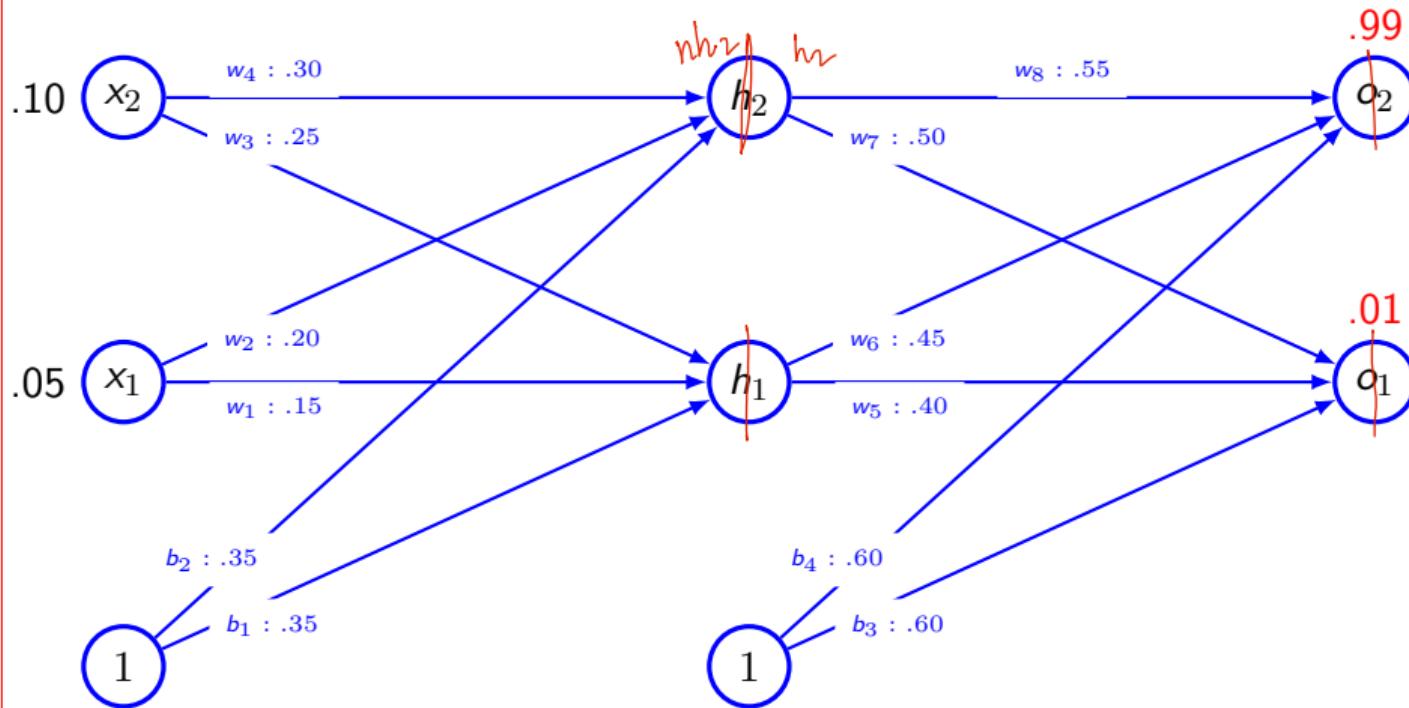


Example

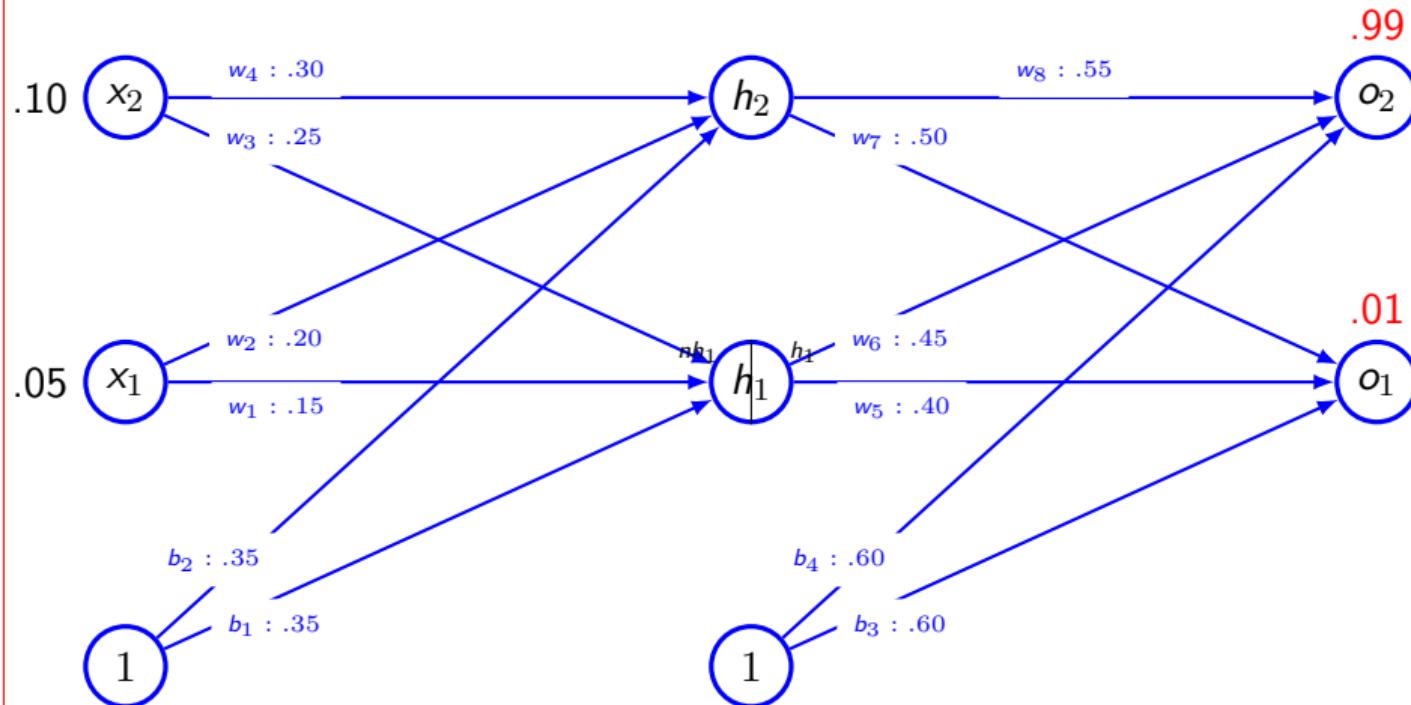


Hidden and output layer have sigmoid activation function. Loss function - MSE.

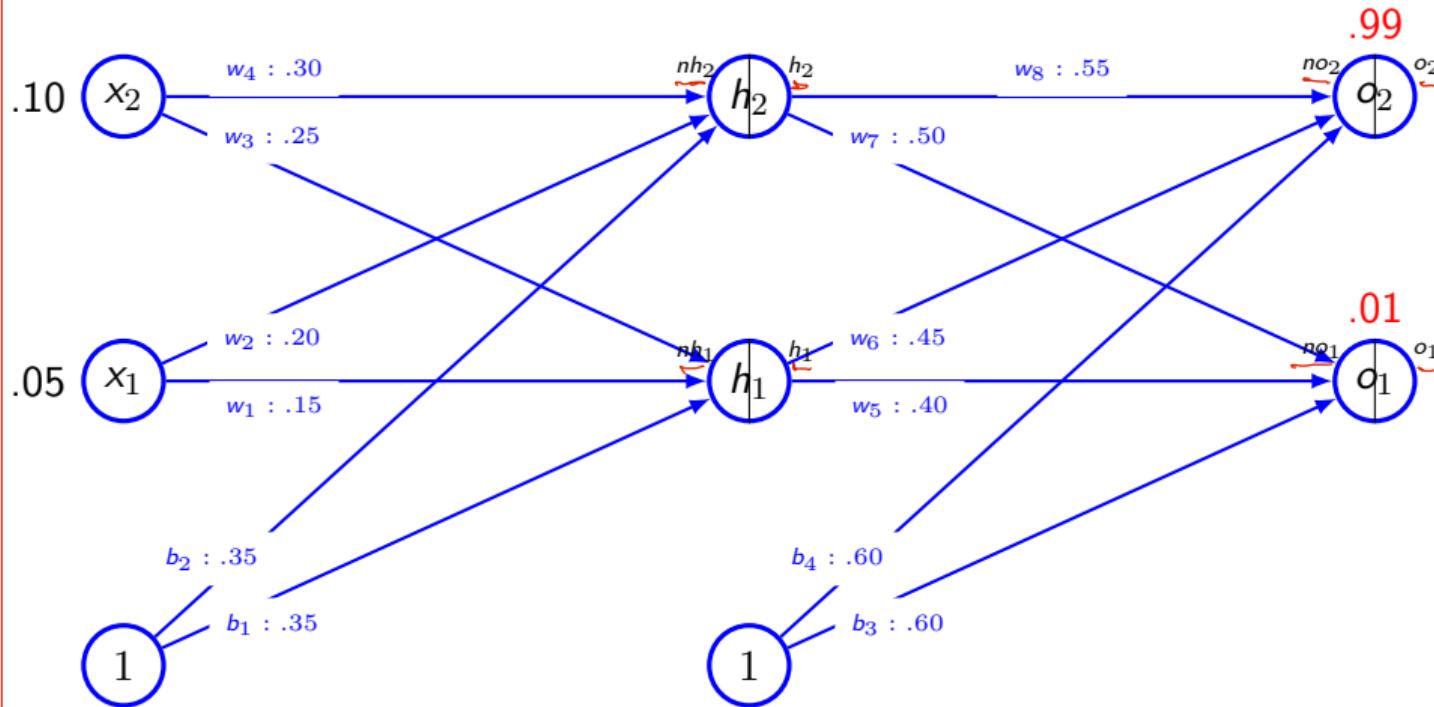
Example



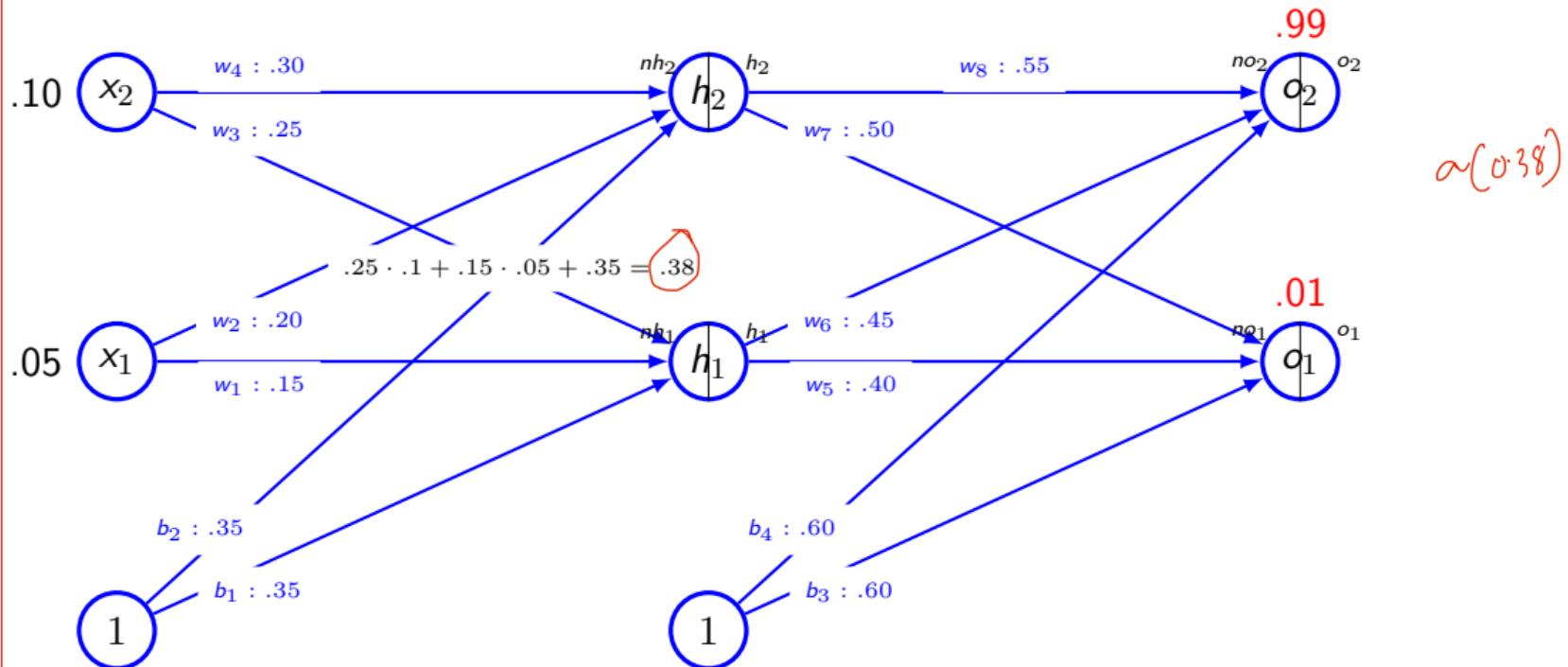
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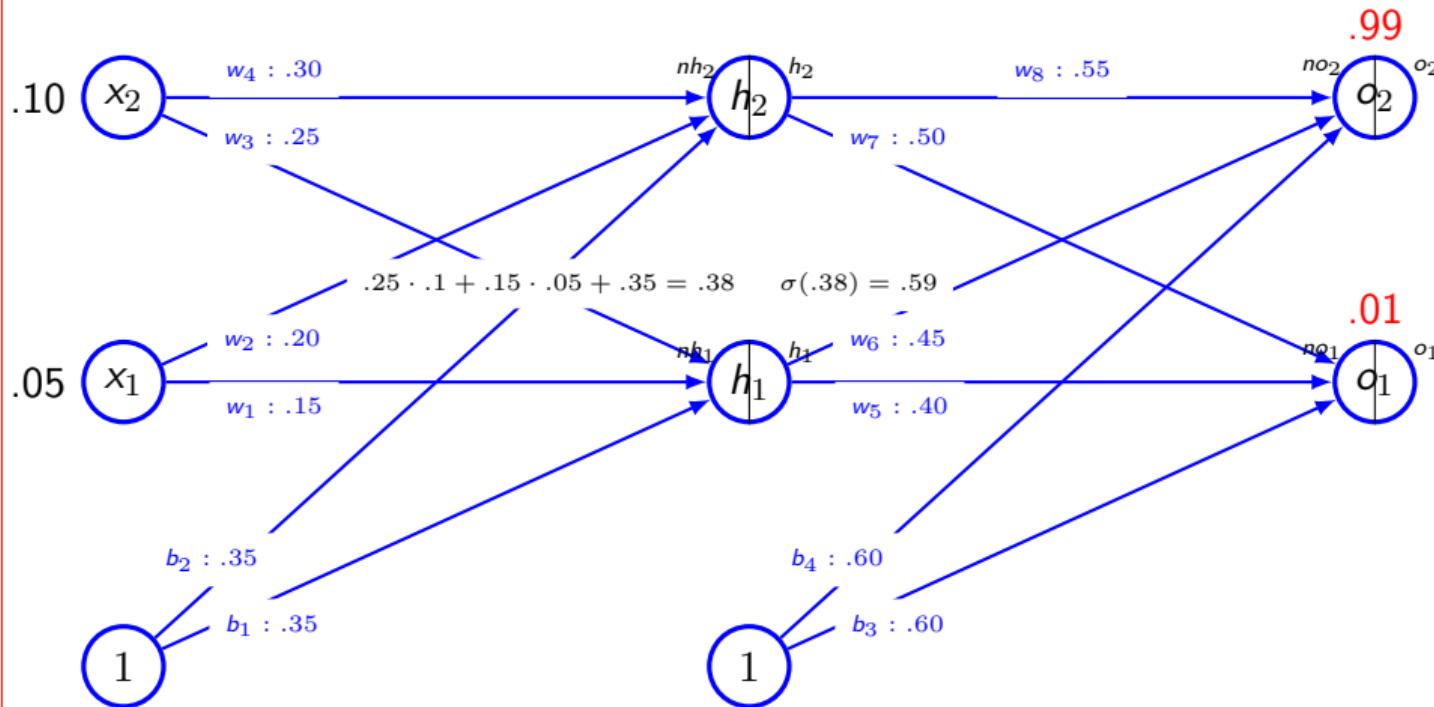
Example



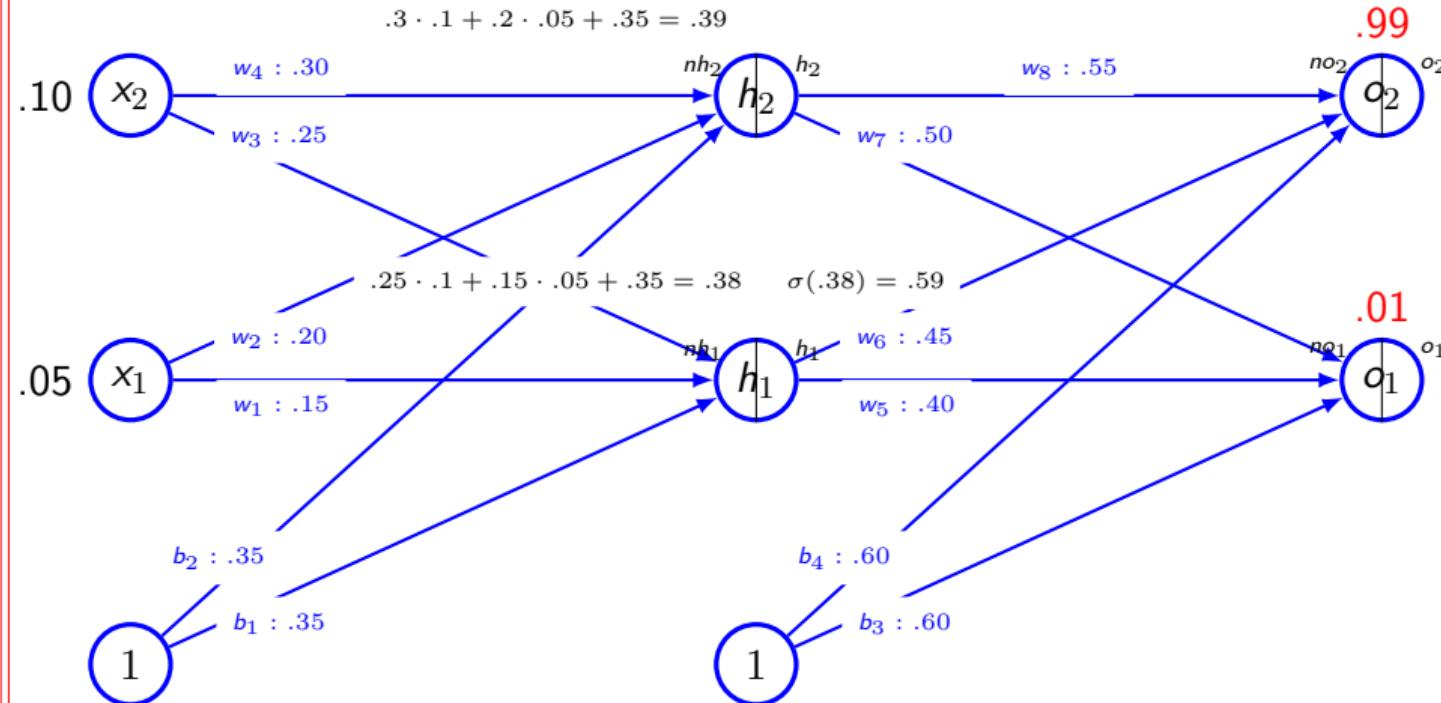
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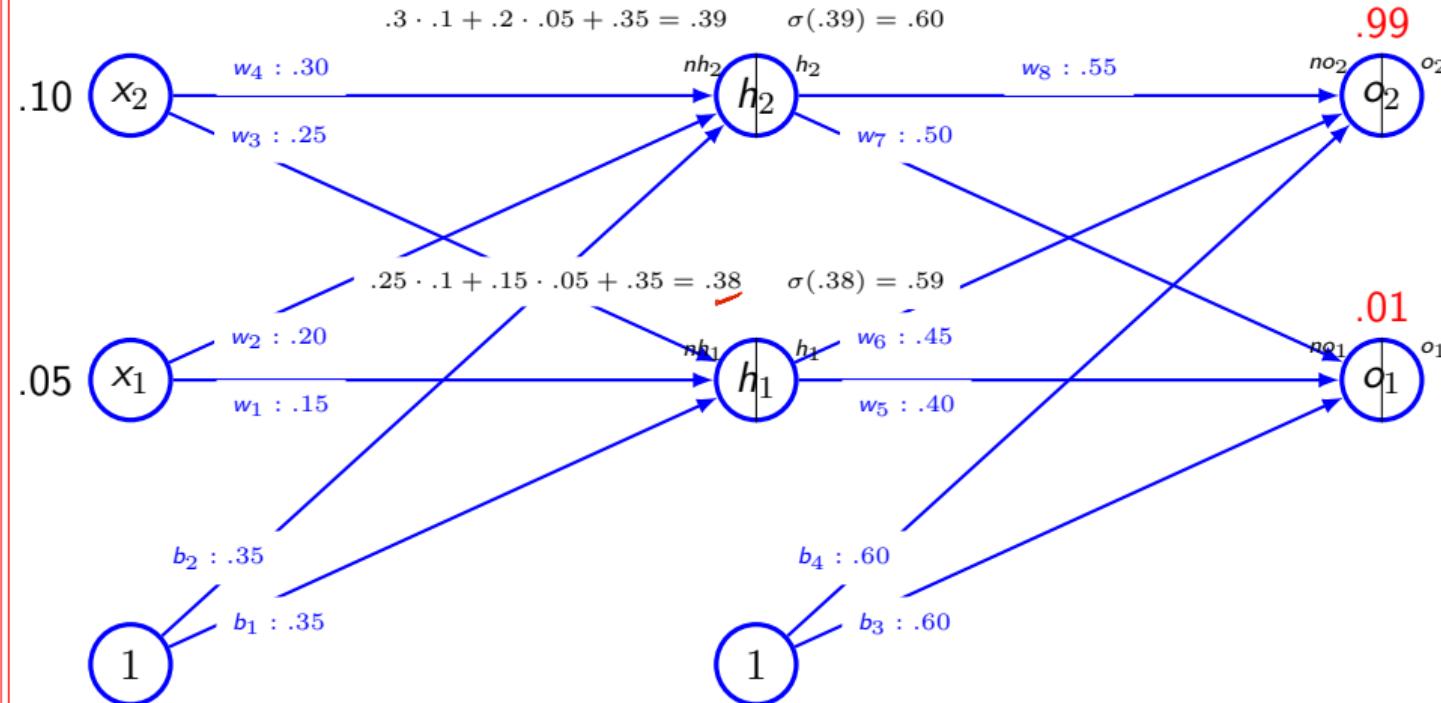
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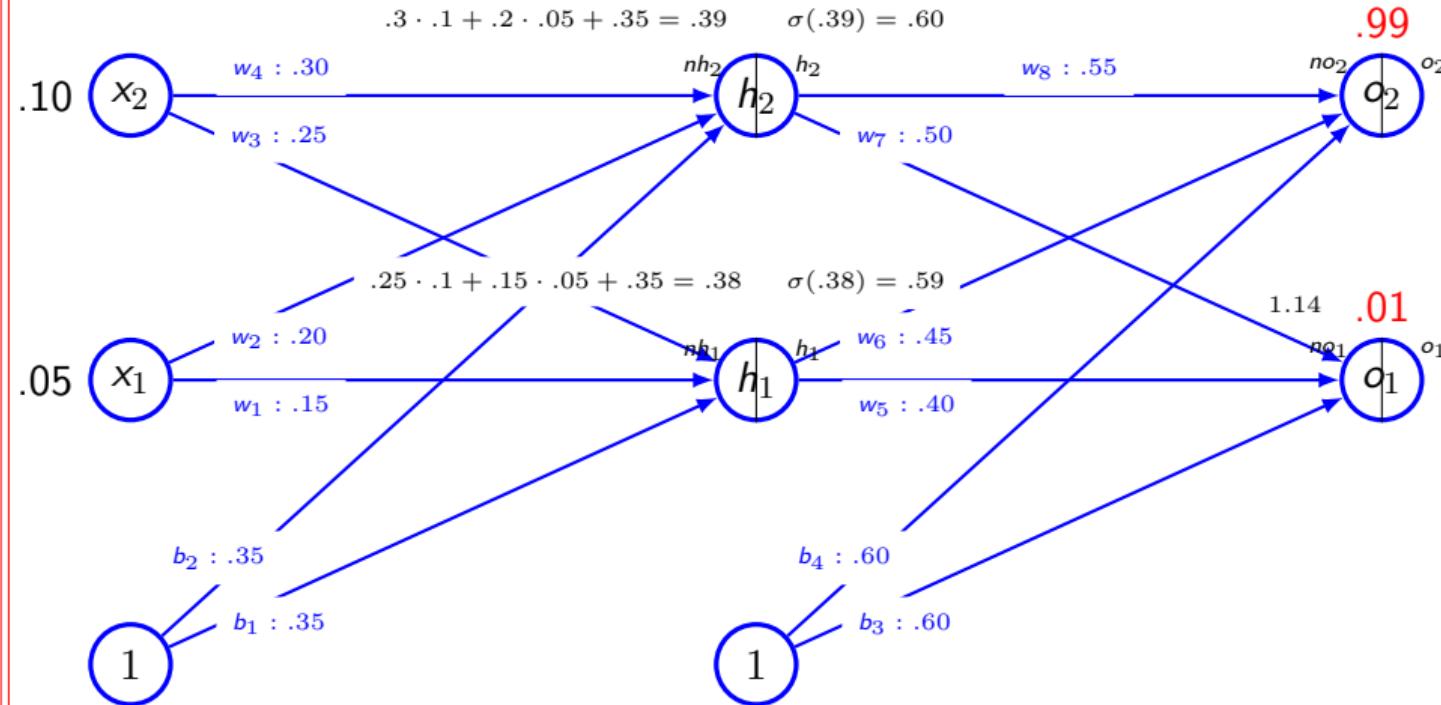
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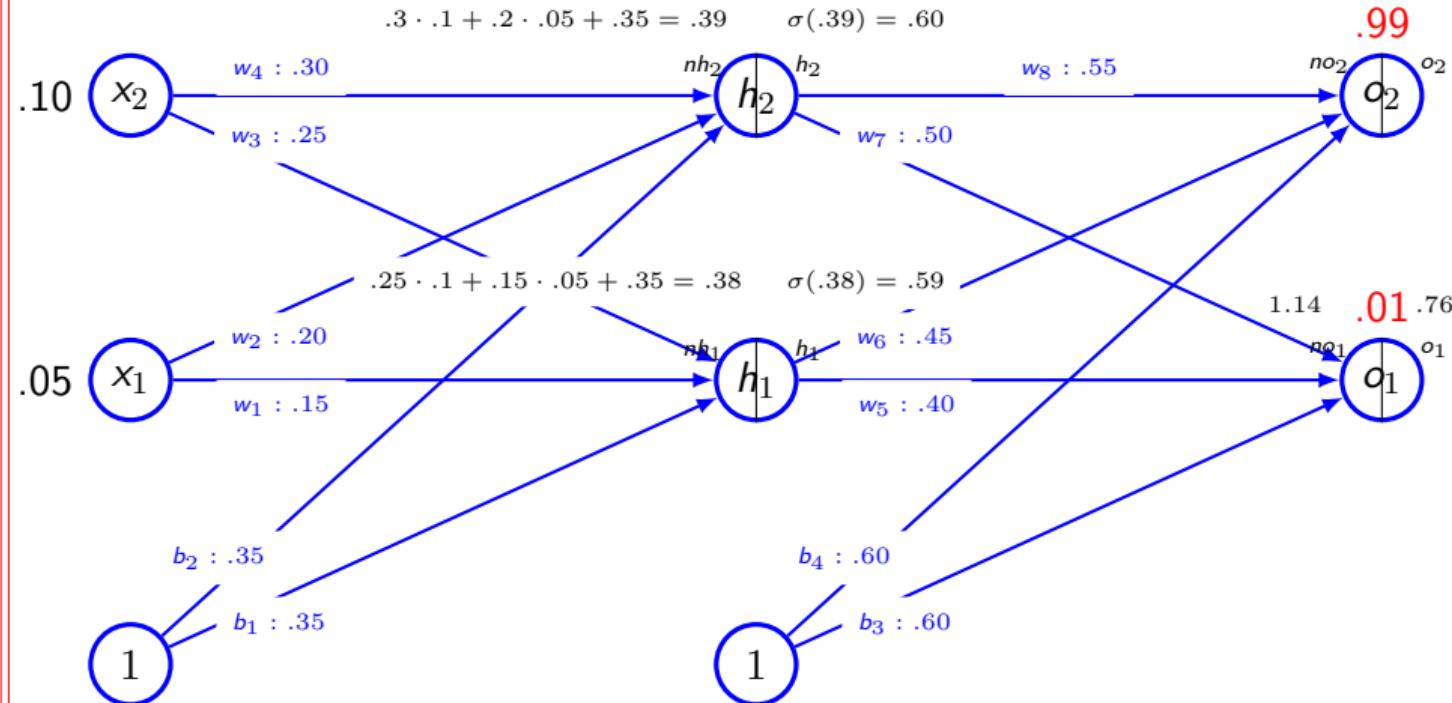
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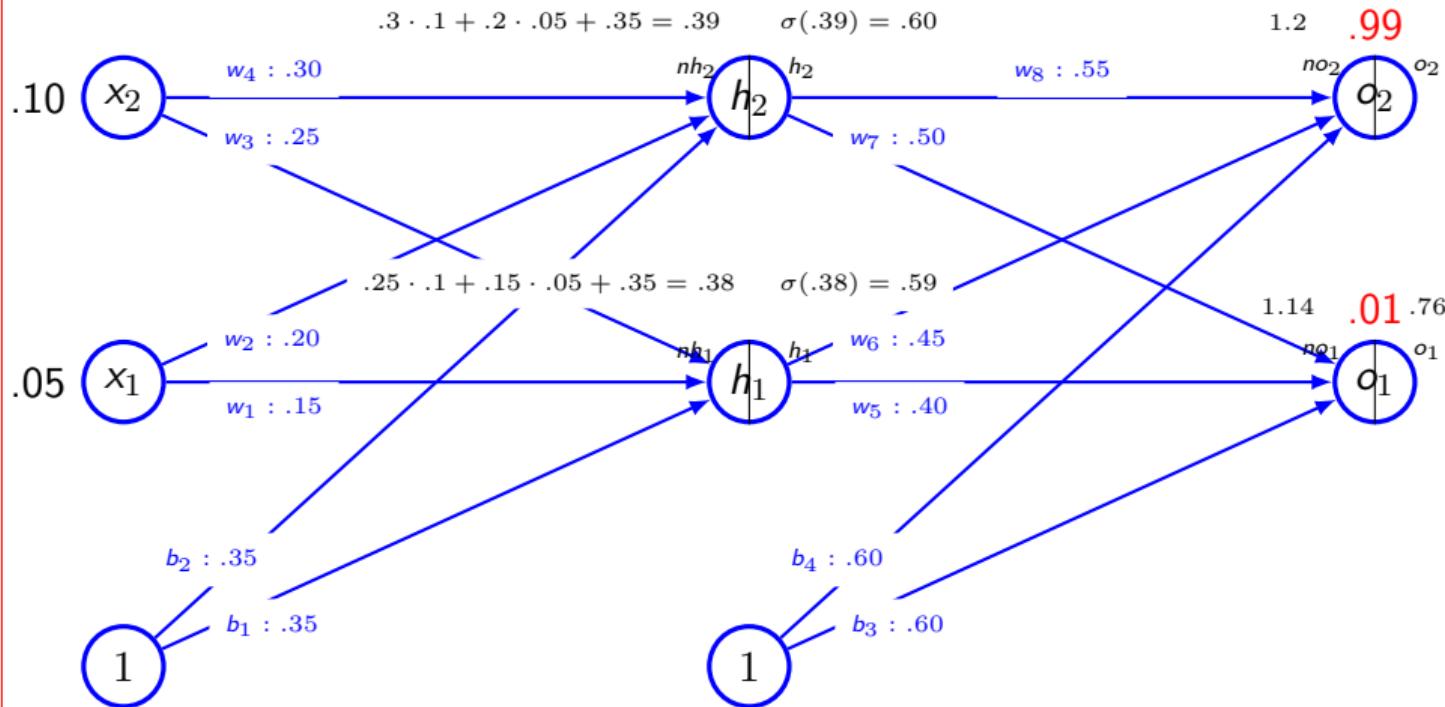
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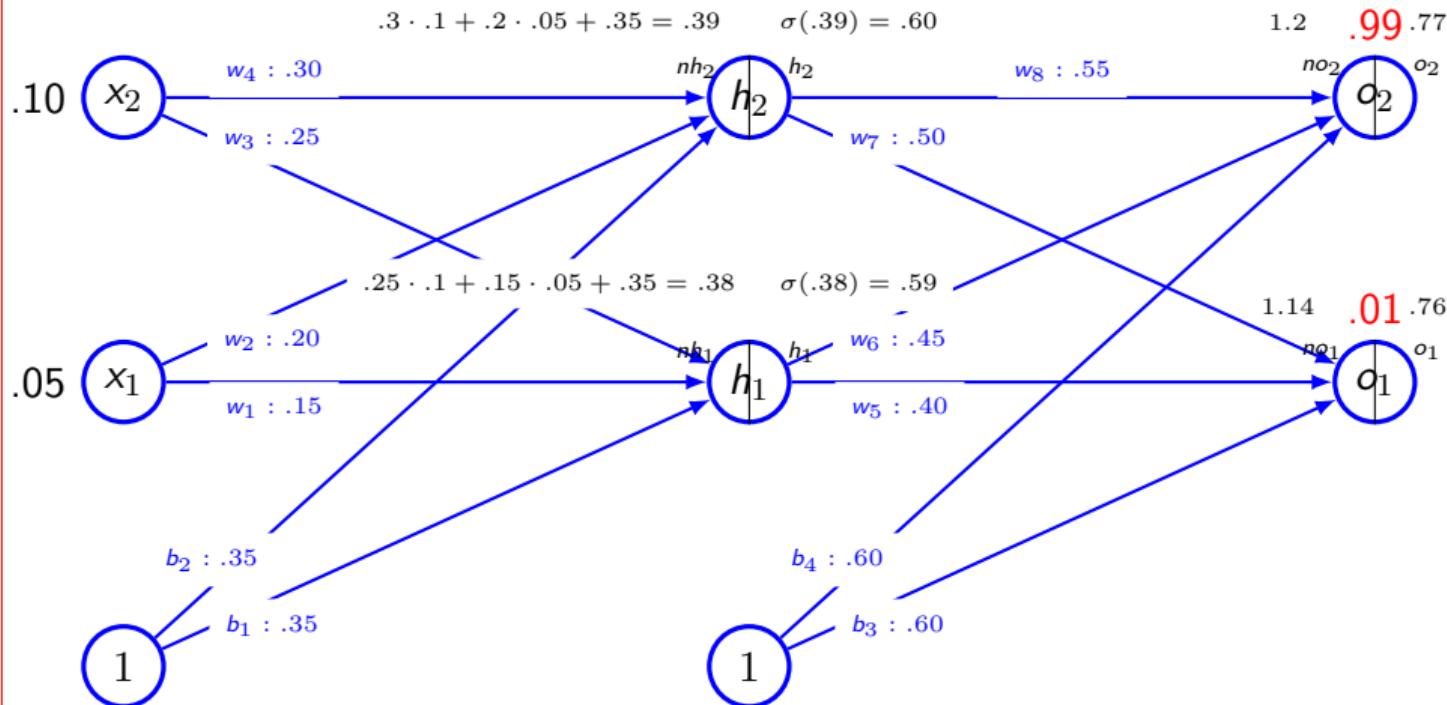
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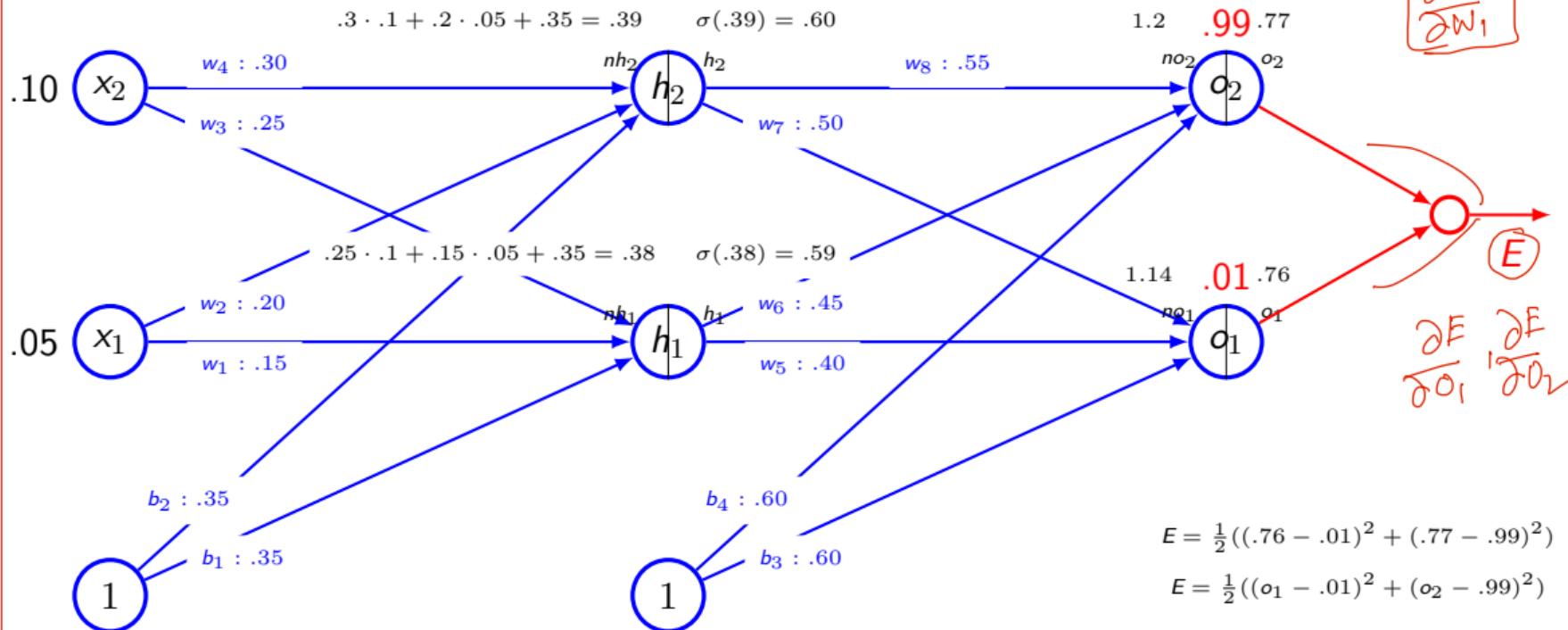
Example



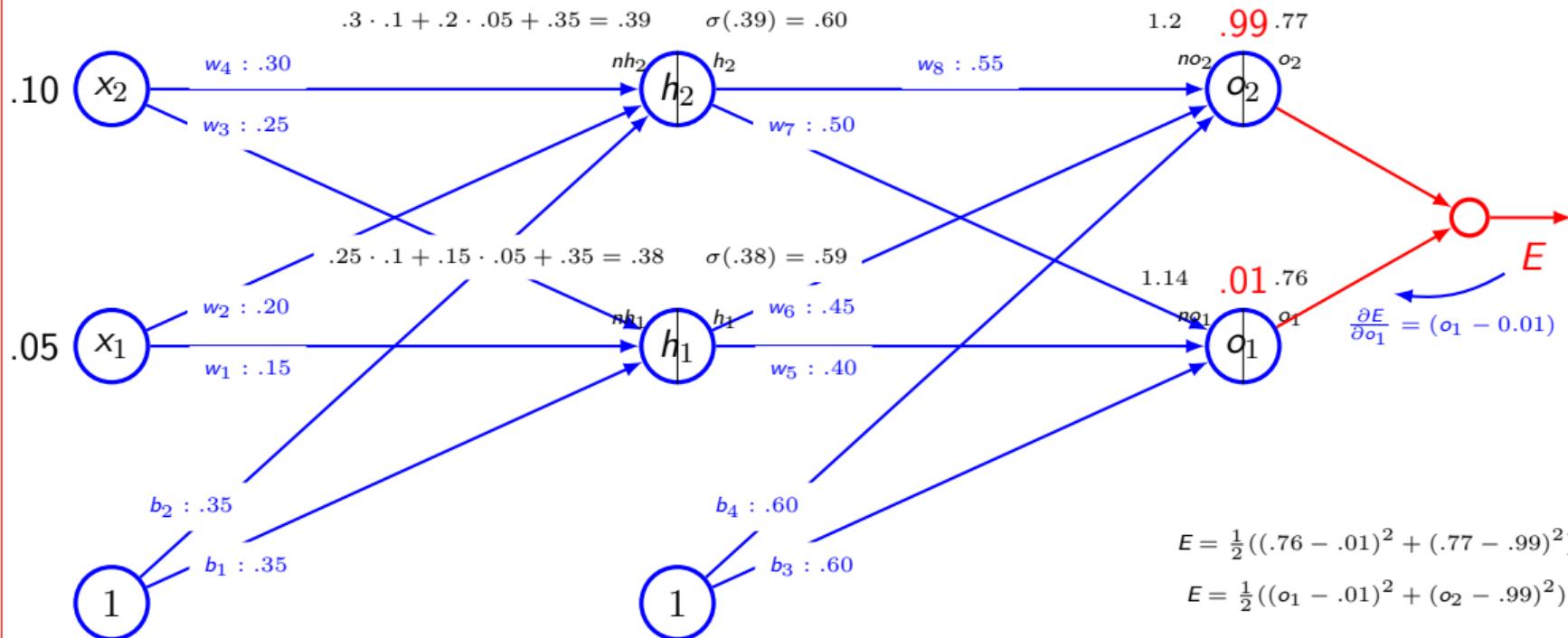
Example



Example

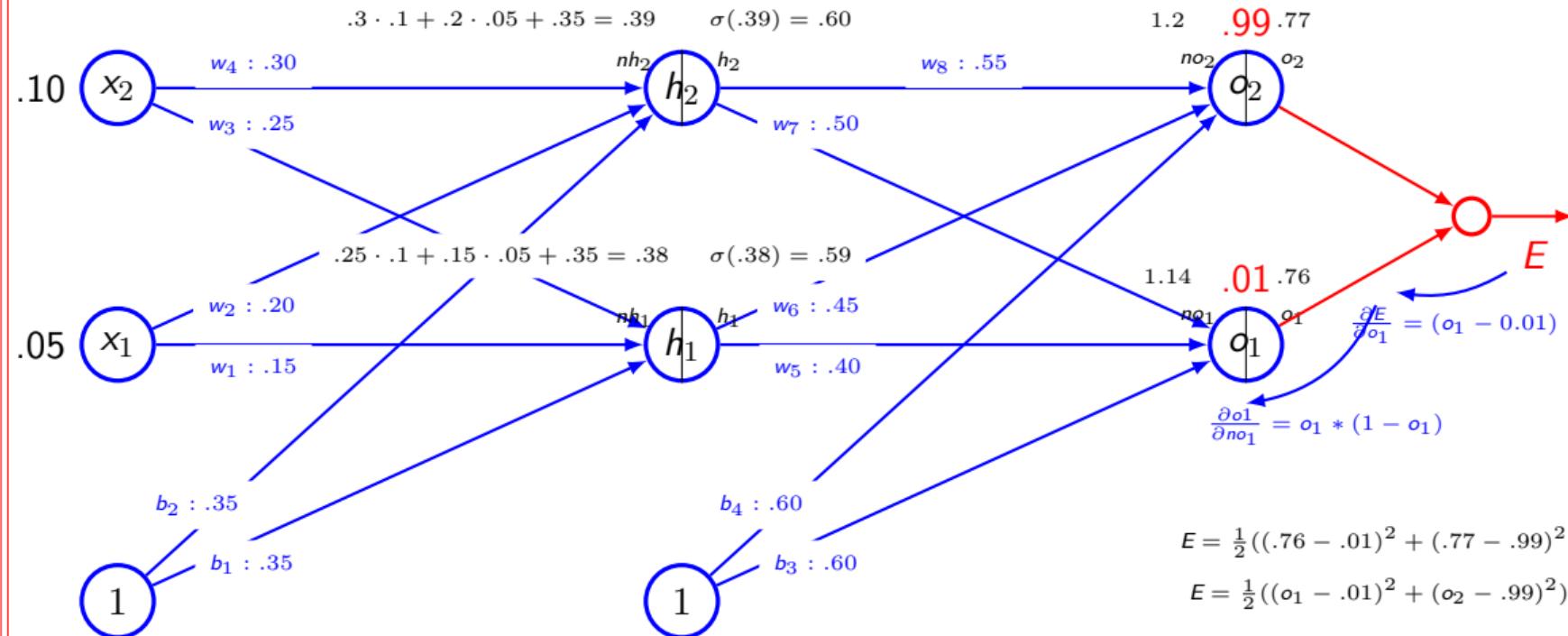


Example



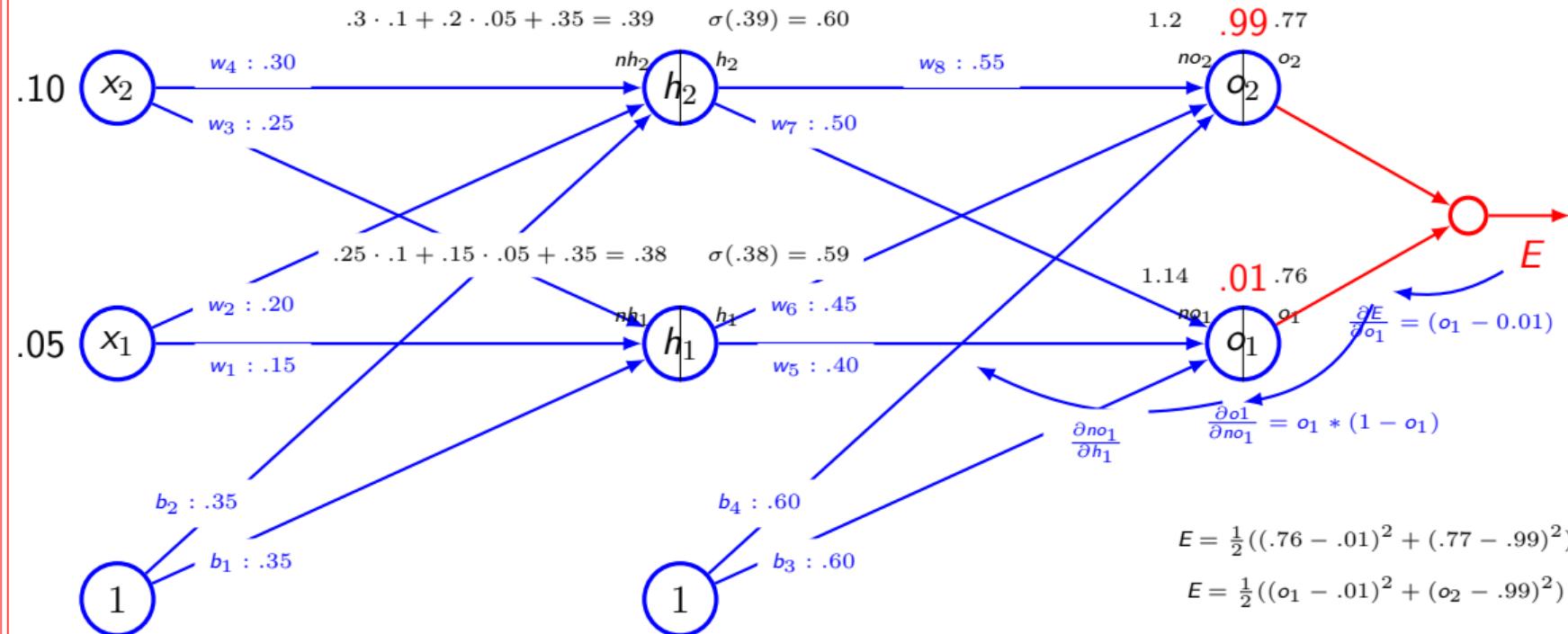
Example

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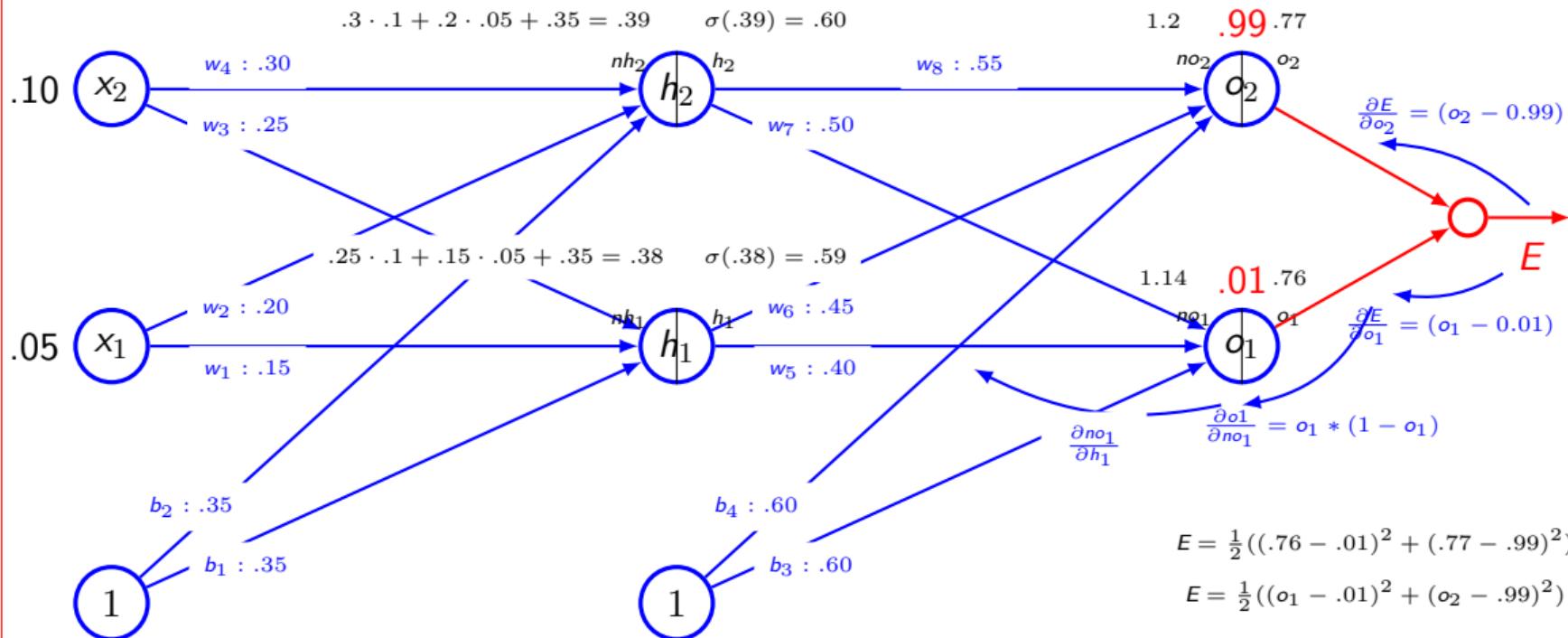


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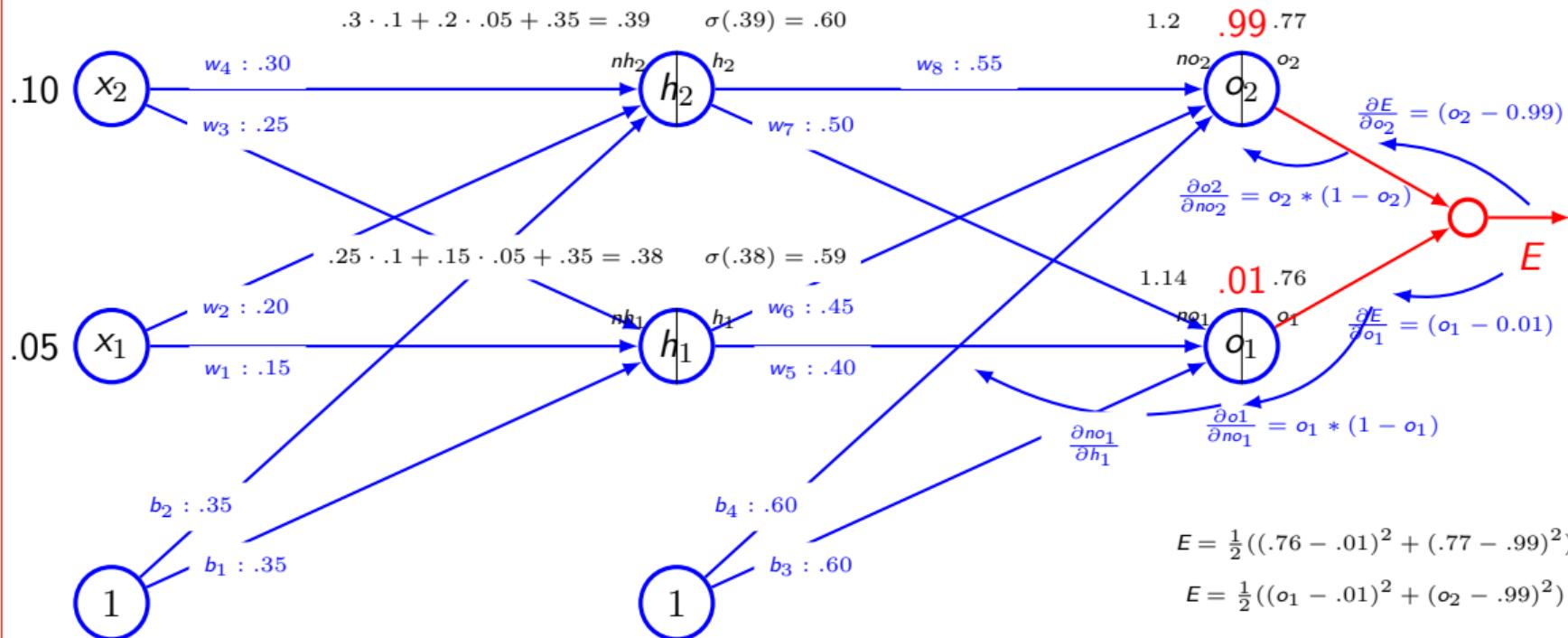
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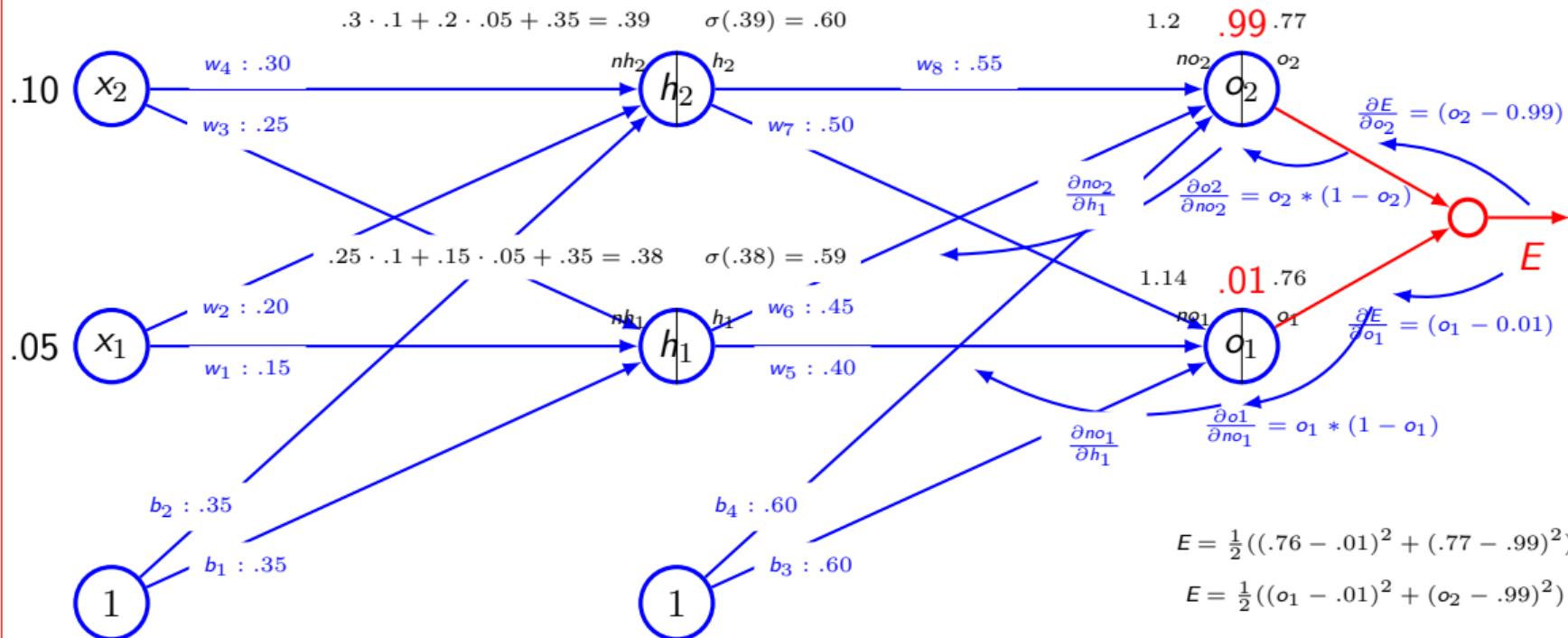
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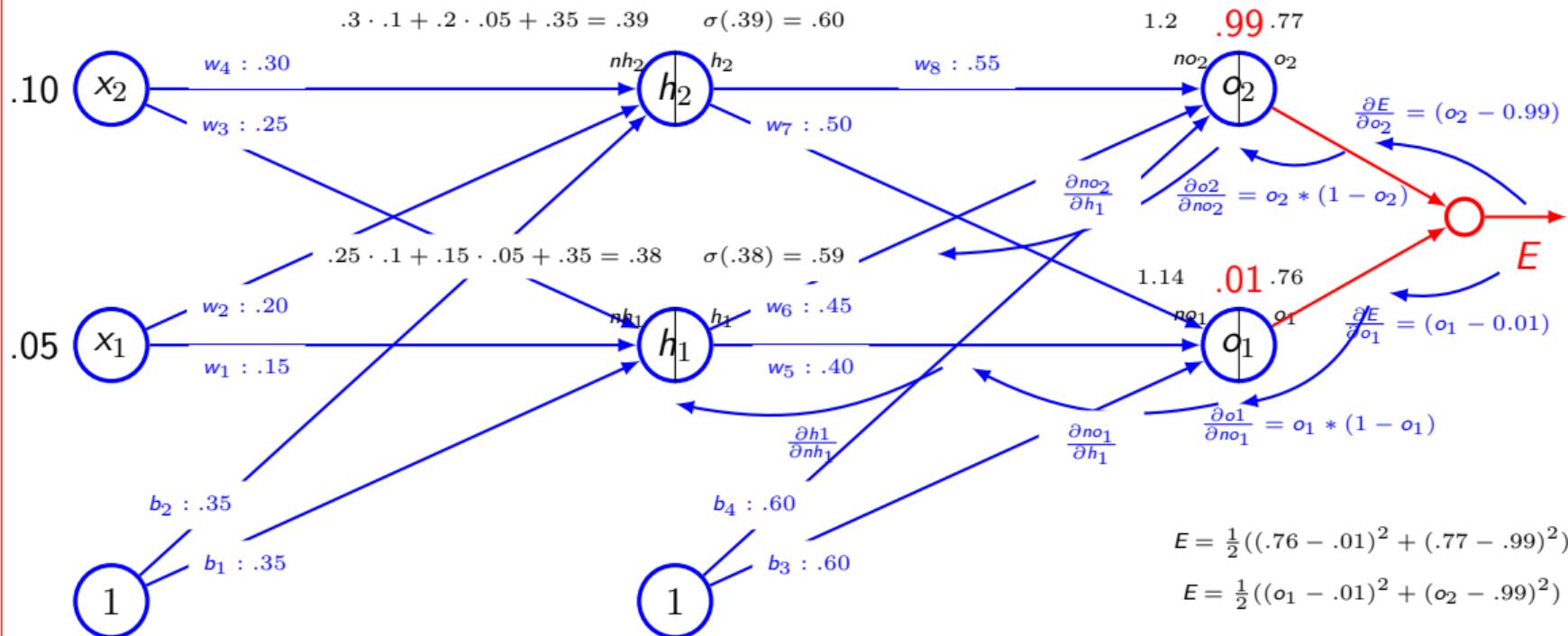
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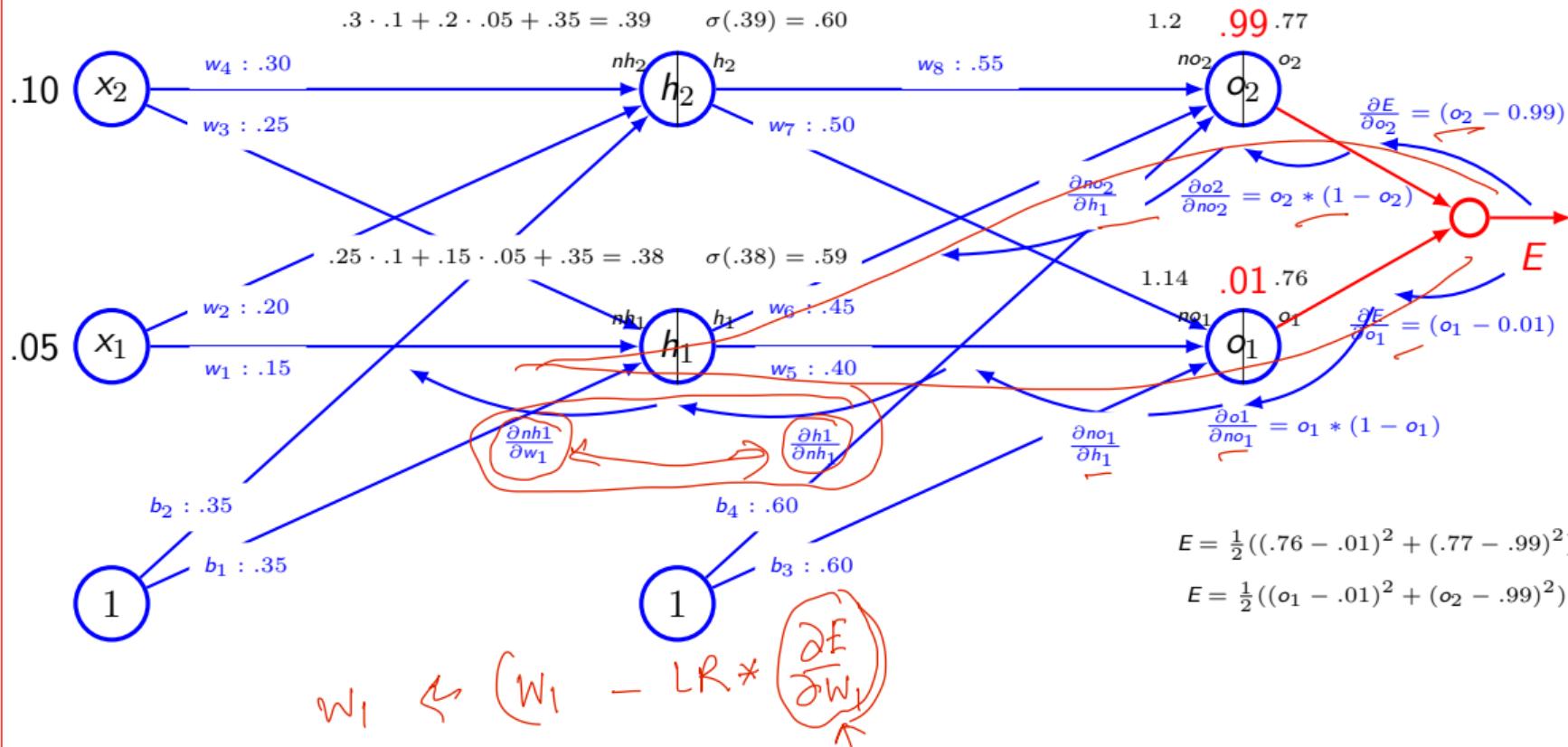
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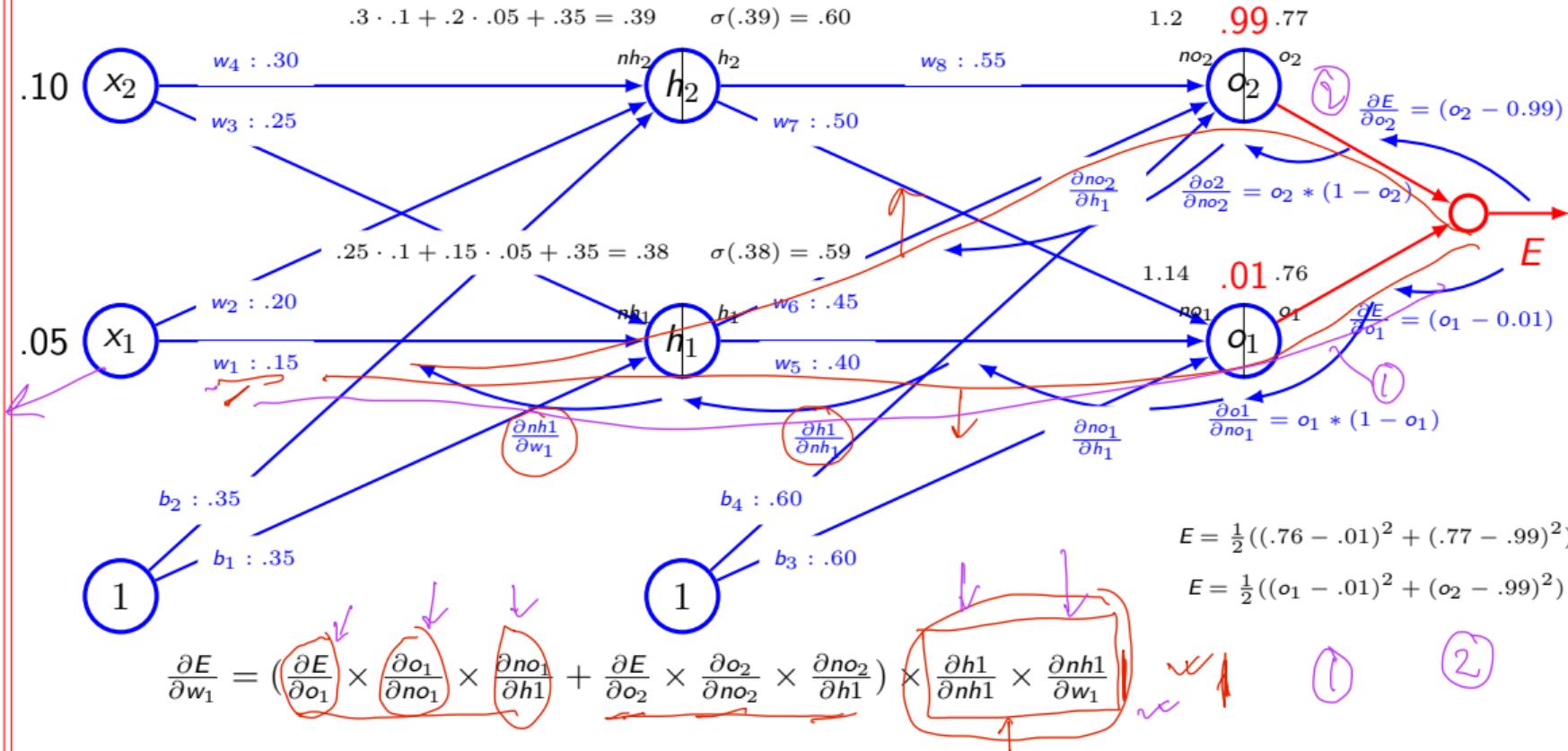
Example



Example

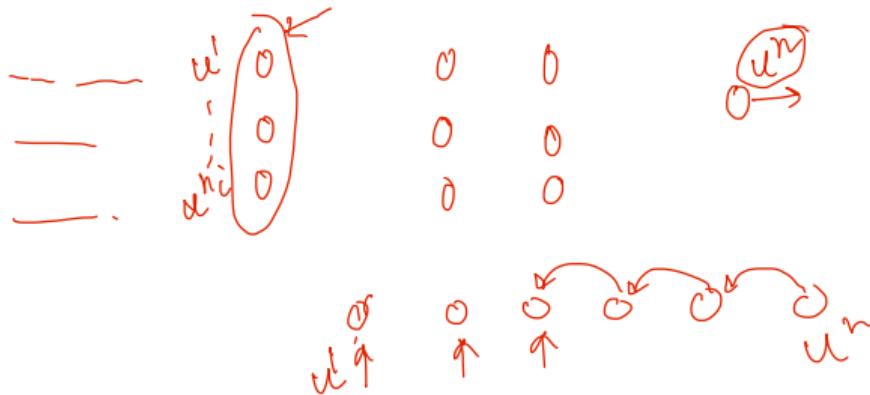


Example



Application of chain rule

- Let us consider $\underline{u}^{(n)}$ be the loss quantity. Need to find out the gradient for this.
- Let $\underline{u}^{(1)}$ to $\underline{u}^{(n_i)}$ are the inputs
- Therefore, we wish to compute $\frac{\partial \underline{u}^{(n)}}{\partial \underline{u}^{(i)}}$ where $i = 1, 2, \dots, n_i$
- Let us assume the nodes are ordered so that we can compute one after another ✓
- Each $\underline{u}^{(i)}$ is associated with an operation $f^{(i)}$ ie. $\underline{u}^{(i)} = f^{(i)}(\underline{A}^{(i)})$



Algorithm for forward pass

```
for  $i = 1, \dots, n_i$  do
```

$$u^{(i)} \leftarrow x_i$$

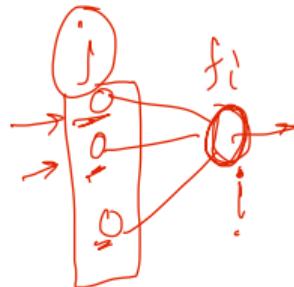
```
end for
```

```
for  $i = n_i + 1, \dots, n$  do
```

$$\begin{aligned} \mathbb{A}^{(i)} &\leftarrow \{u^{(j)} \mid j \in Pa(u^{(i)})\} \\ u^{(i)} &\leftarrow f^{(i)}(\mathbb{A}^{(i)}) \end{aligned}$$

```
end for
```

```
return  $u^{(n)}$ 
```



Algorithm for backward pass

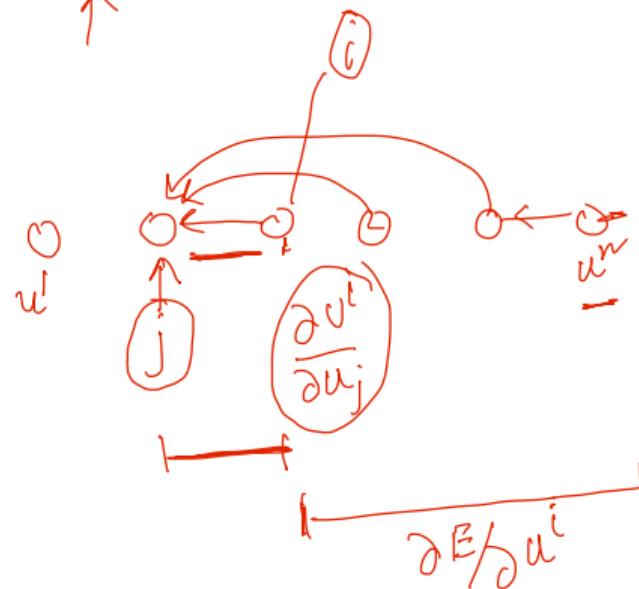
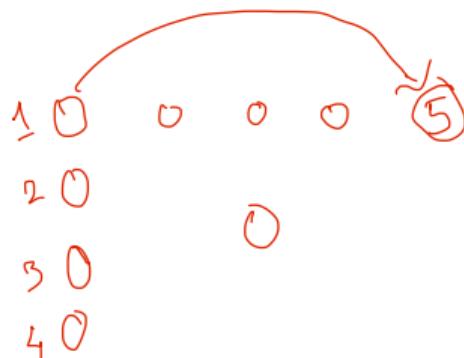
grad_table[$u^{(n)}$] \leftarrow 1

for $j = n - 1$ down to 1 do

grad_table[$u^{(j)}$] $\leftarrow \sum_{i:j \in Pa(u^{(i)})}$ grad_table[$u^{(i)}$] $\frac{\partial u^{(i)}}{\partial u^{(j)}}$

end for

return grad_table

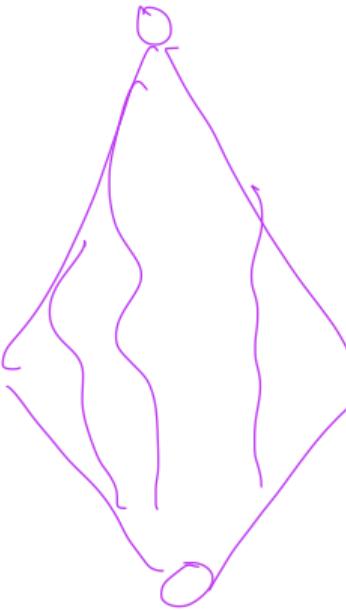
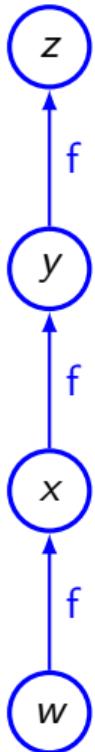


Computational graph & subexpression

- We have $x = f(w)$, $y = f(x)$, $z = f(y)$

$$\begin{aligned} \frac{\partial z}{\partial w} &= \frac{\partial z}{\partial y} \frac{\partial y}{\partial x} \frac{\partial x}{\partial w} \\ &= f'(y) f'(x) f'(w) \\ &= f(f(f(w))) f'(f(w)) f'(w) \end{aligned}$$

Handwritten annotations: A red bracket groups $f'(y) f'(x) f'(w)$. A blue bracket groups $f(f(f(w)))$. A purple bracket groups $f'(f(w))$. A purple bracket groups $f'(w)$.

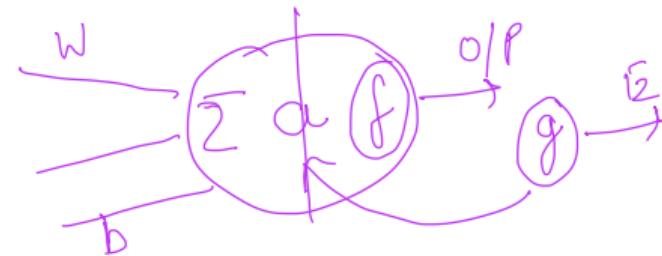
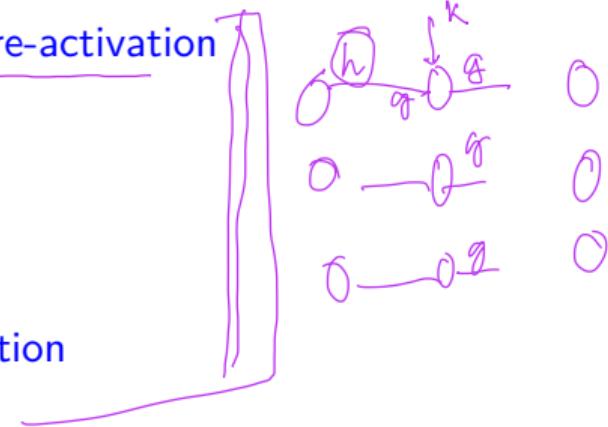


Forward propagation in MLP

- Input
 - $h^{(0)} = x$
- Computation for each layer $k = 1, \dots, l$
 - $a^{(k)} = b^{(k)} + W^{(k)} h^{(k-1)}$ \leftarrow
 - $h^{(k)} = f(a^{(k)})$
- Computation of output and loss function
 - $\hat{y} = h^{(l)}$
 - $J = L(\hat{y}, y) + \lambda \Omega(\theta)$

Backward computation in MLP

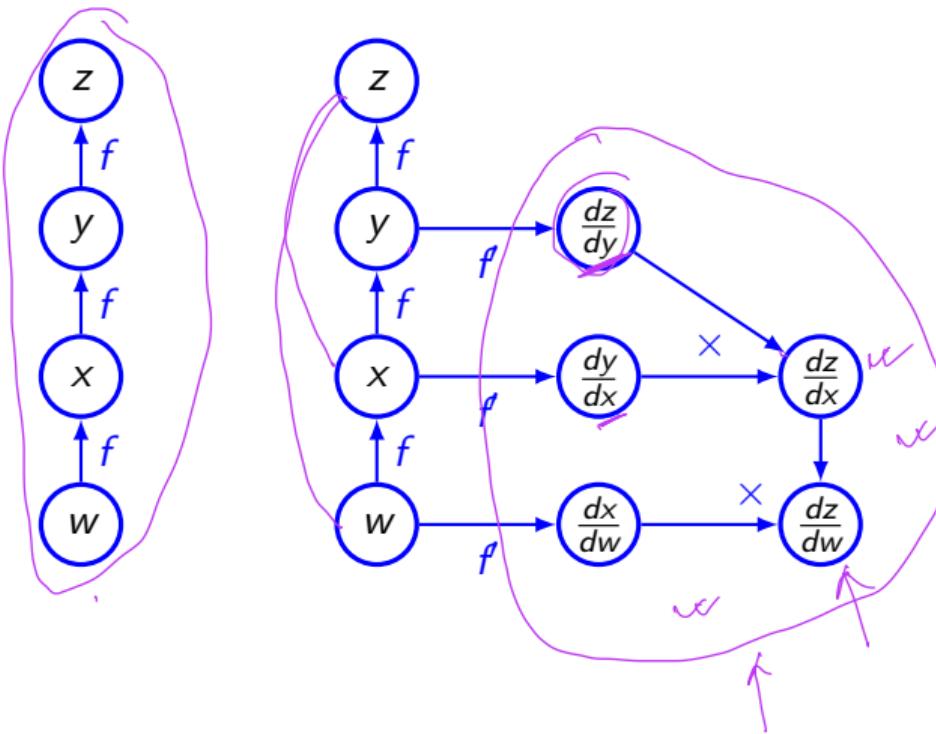
- Compute gradient at the output
 - $g \leftarrow \nabla_{\hat{y}} J = \nabla_{\hat{y}} L(\hat{y}, y)$
- Convert the gradient at output layer into gradient of pre-activation
 - $g \leftarrow \nabla_{a^{(k)}} J = \underbrace{(g \odot f'(a^{(k)}))}_{\text{w.r.t.}}$
- Compute gradient on weights and biases
 - $\nabla_{b^{(k)}} J = g + \lambda \nabla_{b^{(k)}} \Omega(\theta)$
 - $\nabla_{W^{(k)}} J = gh^{(k-1)T} + \lambda \nabla_{W^{(k)}} \Omega(\theta)$
- Propagate the gradients wrt the next lower level activation
 - $g \leftarrow \nabla_{h^{(k-1)}} J = W^{(k)T} g$



Computation of derivatives

- Takes a computational graph and a set of numerical values for the inputs, then return a set of numerical values
 - Symbol-to-number differentiation ↗
 - Torch, Caffe
- Takes computational graph and add additional nodes to the graph that provide symbolic description of derivative
 - Symbol-to-symbol derivative
 - Theano, TensorFlow ↗

Example



Summary

- Writing gradient for each parameter is difficult
- Recursive application of chain rule along the computational graph help to compute the gradients
- Forward pass - compute the value of the operations and store the necessary information
- Backward pass - uses the loss function, computes the gradient, updates the parameters.