Embedded Systems



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Memory

Memory

- Different kind of memories are usually required for embedded systems
 - Volatile, Non-volatile
- Hierarchical design of memory is preferred
 - Trade-off between performance and cost
- Address space of processor is divided to provide different kind of services

• Support for program, interaction through I/O devices

Memory technology

- RAM random access memory
 - Read and write are relatively fast
 - Static RAM (SRAM) is faster than Dynamic RAM (DRAM)
 - DRAM holds data for short time and need to be refreshed periodically
 - SRAM holds data as long as power is maintained
 - SRAM and DRAM are volatile in nature
 - SRAM takes more silicon and it is costly
 - Refresh cycle in DRAM can introduce variability in access time

Non-volatile memory

- Memory is not lost when power is withdrawn
- Early form of non-volatile memory is magnetic tape
- Read only memory (ROM) content is written once only
 - Firmware
- EEPROM electrically erasable programmable ROM
 - Write time is usually higher compared to read time
 - Flash memory write time is high
 - Not a good substitute of working memory
 - NAND flash less expensive, faster erase and write time, reads a data block (100-1000 bits)
 at a time
 - NOR flash longer erase and write time, can be accessed like a RAM
- Flash can only be written and erased bounded number of time
- Disk memory is non-volatile, good secondary storage CD, DVD

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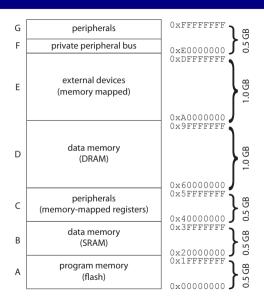
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Memory hierarchy

- Processors use different kind of memories to increase overall capacity while optimizing cost, latency, energy consumption
 - Typically small amount of on-chip SRAM and large amount of off-chip DRAM are used
- For an application programmer, it is not necessary to know fragmented form of memory
- Virtual memory
 - Physical address translation is done by OS and/or hardware
 - Translational look aside buffer

Memory map

- Harvard architecture separate program and data memory
- Von-Neumann architecture stores program and data in the same memory



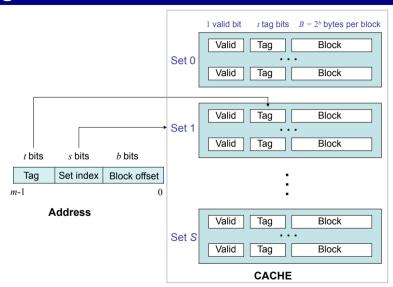
Register file

- Very limited amount usually some power of 2
- Cost is determined by the instruction word
- ISA determines how many registers are accessed simultaneously

Scratchpads and caches

- Intermediate memory is accessed before actual memory
- If program is responsible for read and write from this closer memory then it is called scratchpad
- If the hardware manages such read/write then it is known as cache
- Architecture typically support much larger address space than physical memory of the processor
- Processor may have memory management unit
- Cache miss, page fault

Basic organization of cache



Memory address

- 32 bit architecture can represent address 0 to 2³² − 1
- Each address refers to a byte
 - In C char is 1 byte, int is at least 2 bytes (4 in general)
- Alignment int occupies 4 consecutive bytes starting at an address that is multiple of 4
 - In hexadecimal notation 0, 4, 8, C
- Byte order little vs big endian
 - Intel, ARM little endian, IBM, PowerPC big endian
 - Byte order matters in network protocol

Stack

- A region of memory that is dynamically allocated
- Stack pointer contains the memory address of the top of the stack
 - When an item is pushed, stack pointer is incremented
 - When an item is popped, stack pointer is decremented
- Typically used for implementation of procedure/function call
- Stack overflow

Dynamic memory allocation

- A program can request to operating system for additional memory at any time
- Such memory is allocated in heap
 - It tracks which portion of memory used by which application
- Garbage collector a task runs periodically or when memory gets tight that frees the memory that no longer referred within the program
- Memory fragmentation
- Memory leak
- Real time issue with garbage collector

C program

```
int x = 2;
int* foo(int y){
  int z;
  z = y * x;
  return &z;
int main(){
  int *result = foo(10);
  . . . .
```